

ASAM Ideation Workshop

Modelling Roads and the Streetspace using CityGML 3.0 and its relation to OpenDRIVE

July 24, 2024

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Semantic 3D City Modeling

- ▶ City is decomposed into meaningful objects with clear semantics and defined spatial and thematic properties
 - buildings, roads, railways, terrain, water bodies, vegetation, bridges
 - buildings or roads may be further decomposed into different storeys or sections / intersections (and even more detailed into apartments and single rooms or individual lanes)

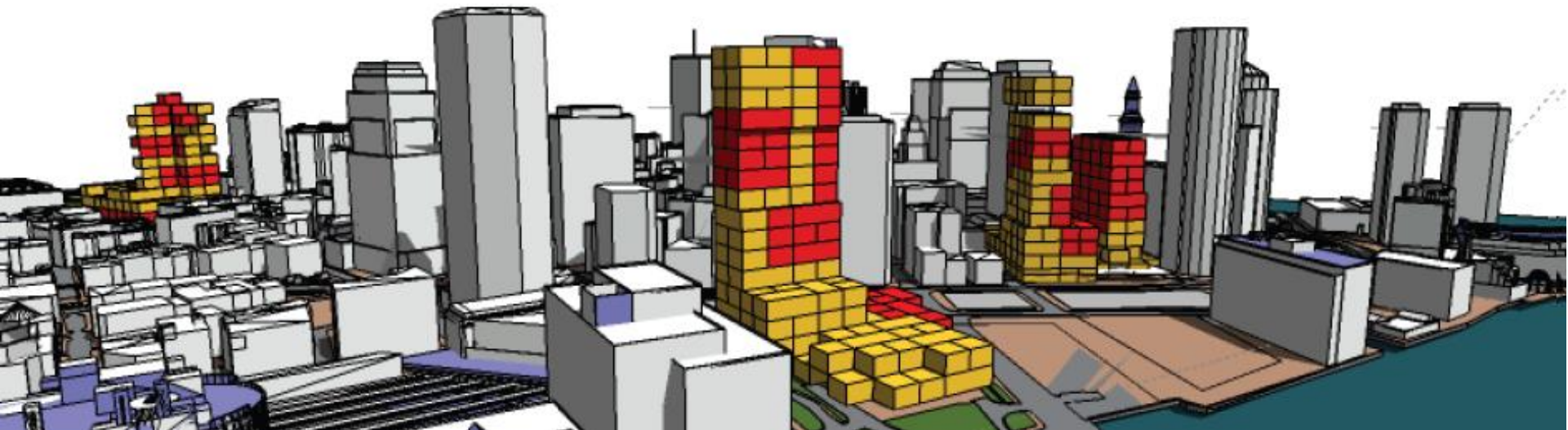
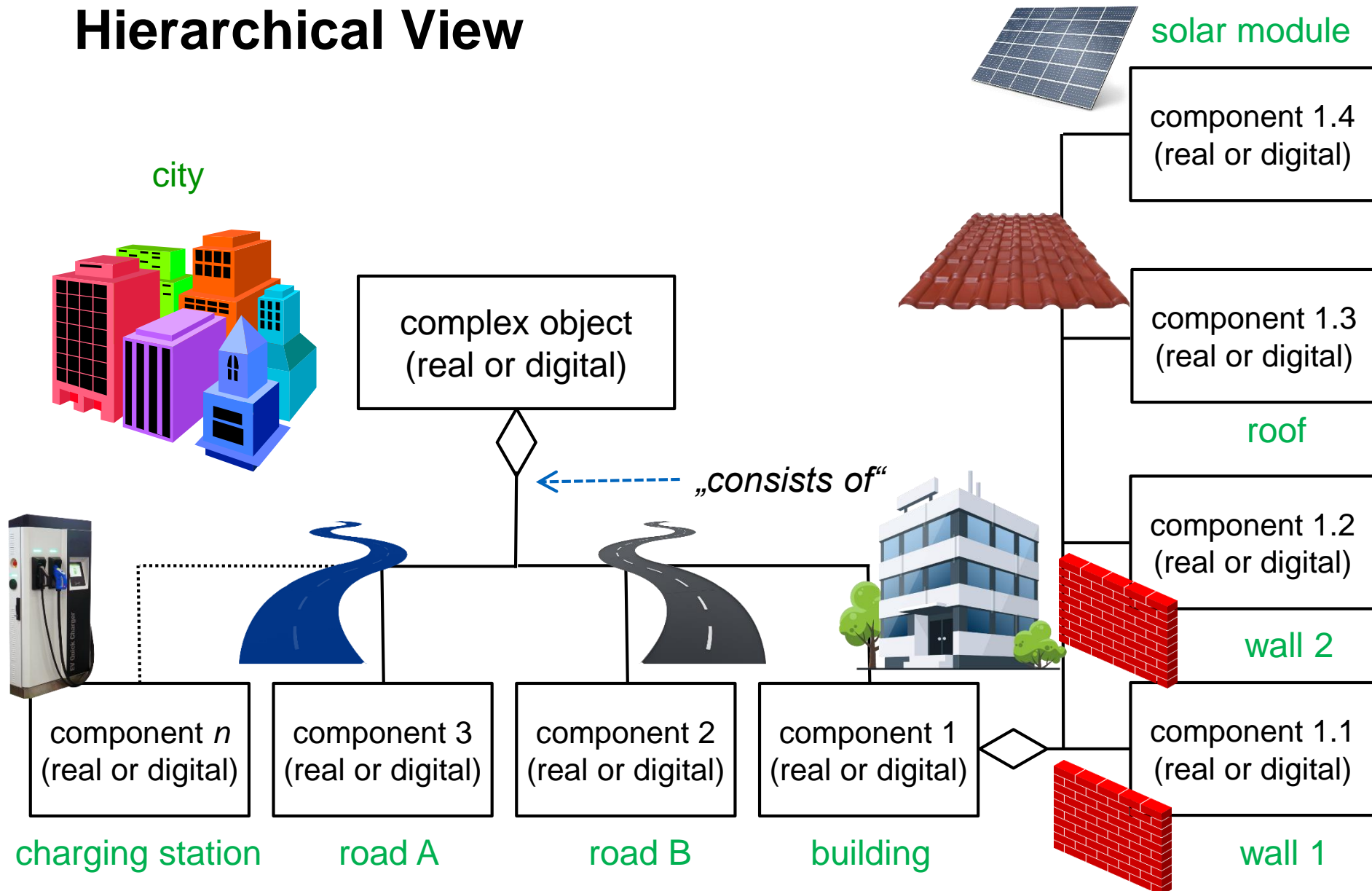
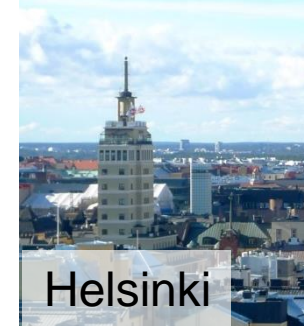
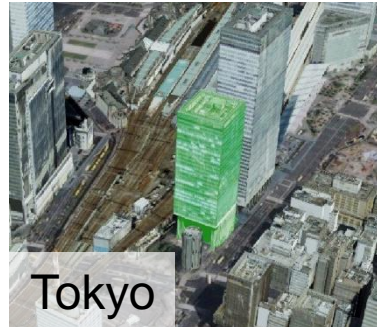


Image: Paul Cote, Harvard Graduate School of Design

Hierarchical View



Standardized Access to Semantic City Models



Mapping the state
of a city at time t_i



Virtually carrying out
planned actions by changing
the city model accordingly

Energy Demand
& Production
Estimation

Noise Immission
Simulation &
Mapping

Testing
automated
driving functions

Traffic planning
and simulation

City Geography Markup Language – CityGML

Application independent Geospatial Information Model
for semantic 3D city and landscape models



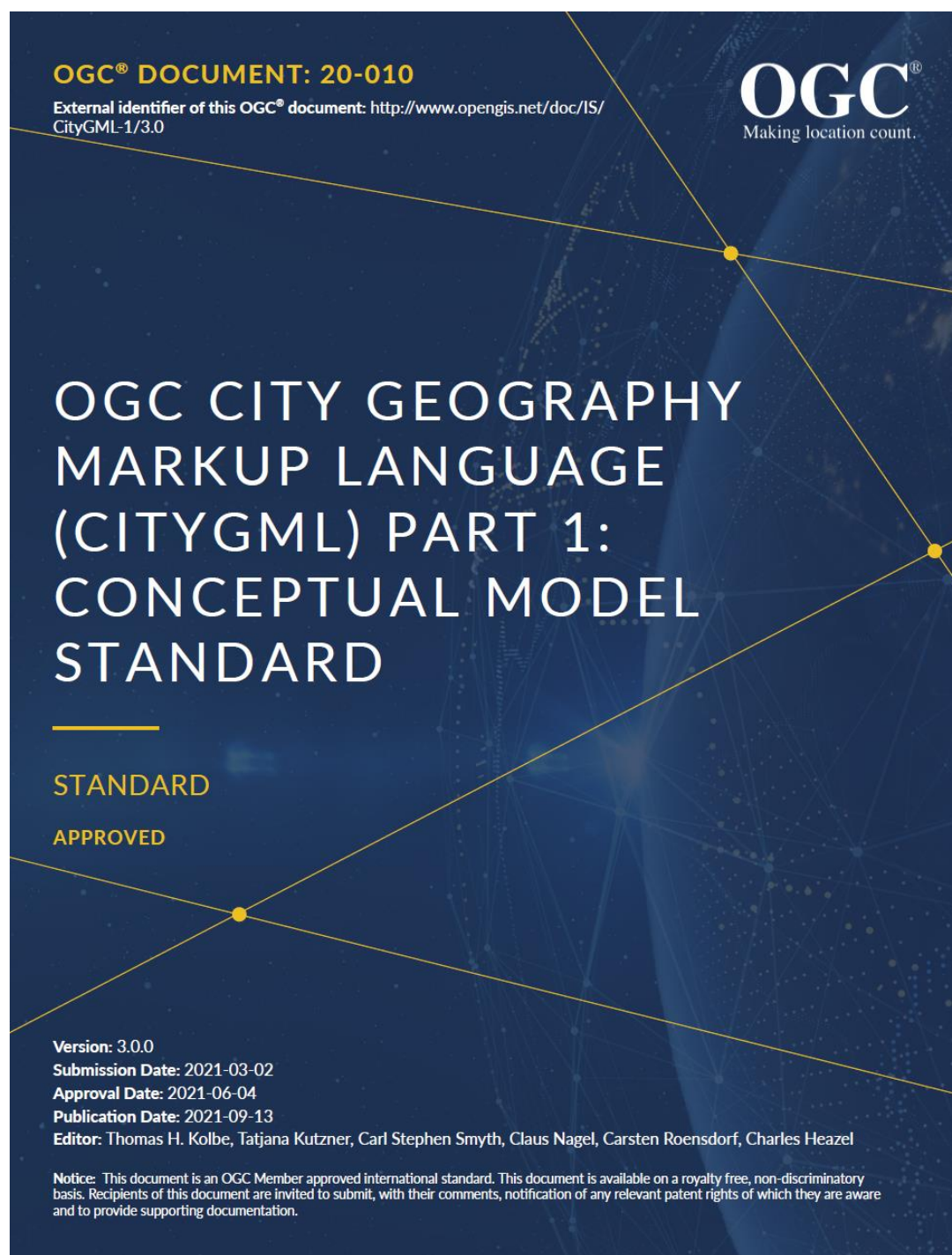
- ▶ comprises **different thematic areas** (buildings, roads, vegetation, water, terrain, tunnels, bridges etc.)
- ▶ **Data model (UML) + Exchange format**
- ▶ Key strengths: **Geo-referenced**, **3D geometries**, **topological information** as well as **semantic capabilities**, **time-dependent properties**, easy **visualization**
- ▶ Large scale (entire city) management using **geo-databases** (e.g. 3DCityDB)

International Standard of the **Open Geospatial Consortium**

- ▶ Version 2.0.0 was issued in 3/2012
- ▶ **Version 3.0 was issued in 2021**

The recent version CityGML 3.0

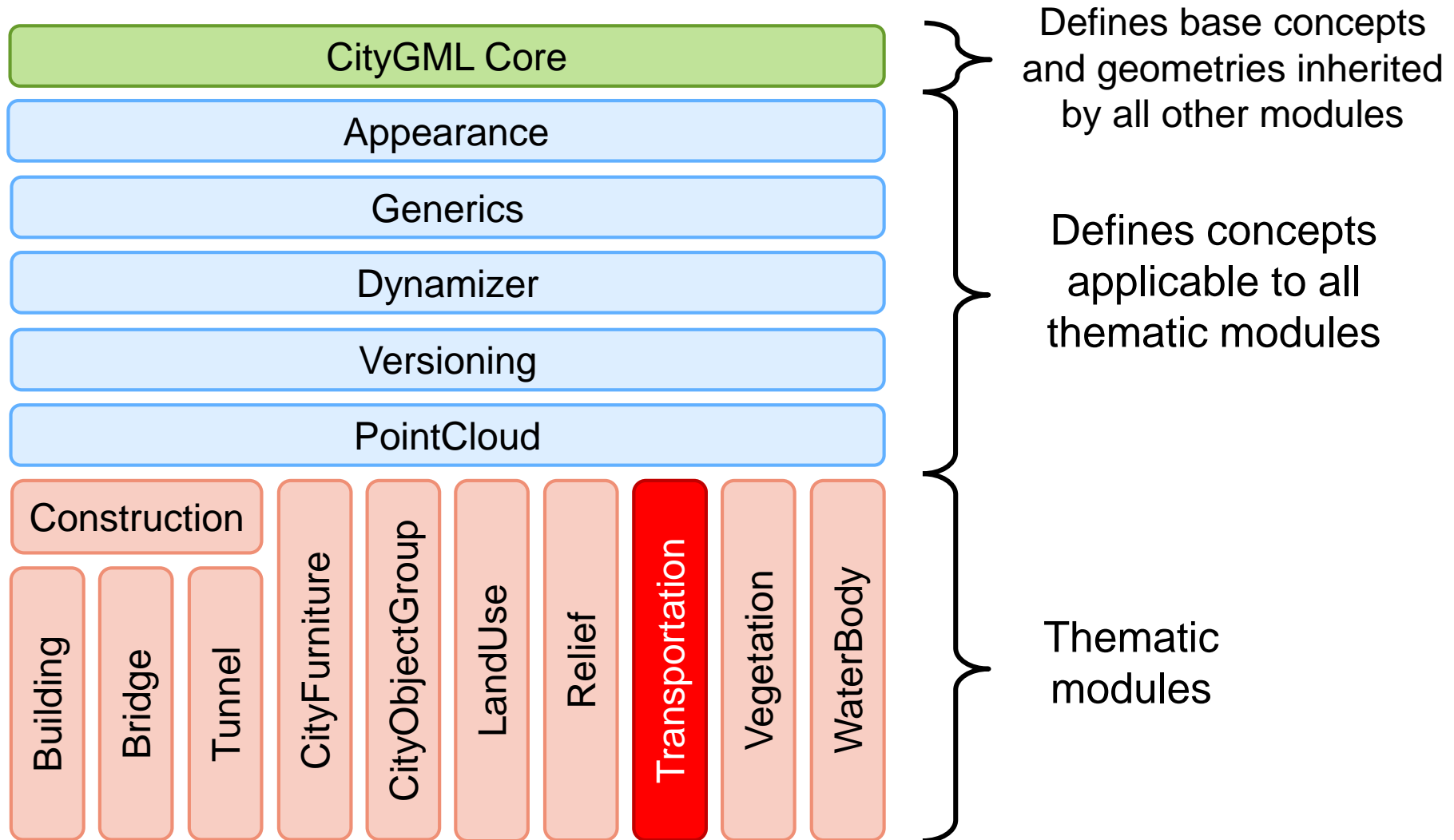
- ▶ On 13 September 2021, after eight years of development, the OGC published version 3.0 of the international standard CityGML
- ▶ The new version can be downloaded here:
<https://docs.ogc.org/is/20-010/20-010.html>



CityGML Usage

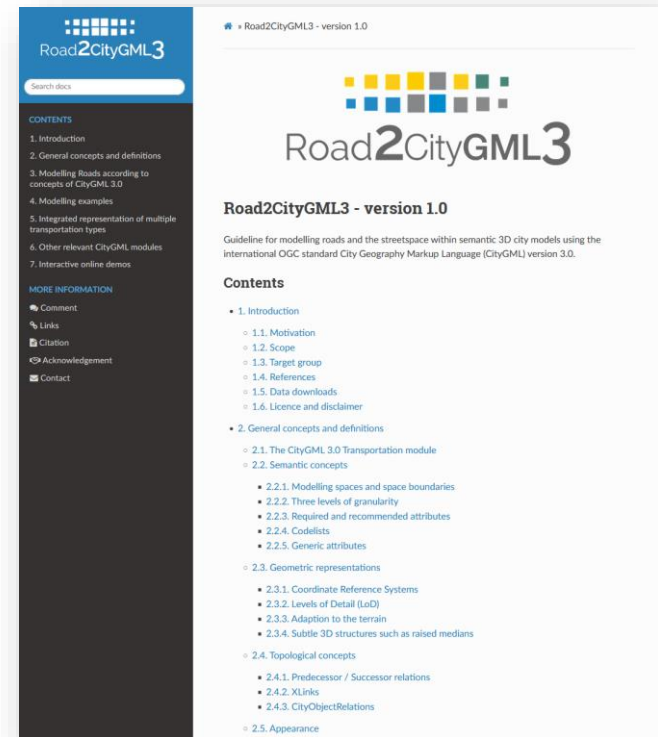
- ▶ CityGML is already successfully used at national scale
 - The official national and municipal 3D geoinformation standards of Germany and the Netherlands based on CityGML 1.0/2.0
 - Japan published 3D city models for >100 cities based on CityGML and the i-Urban Revitalization Application Domain Extension
- ▶ Many cities worldwide use CityGML for their 3D city models
- ▶ List of Open CityGML Datasets:
<https://github.com/OloOcki/awesome-citygml>
 - from 18 countries, in different Levels of Detail, most data are officially maintained 3D city models

Modular structure of the CityGML standard



Guideline Road2CityGML3

- ▶ <https://tum-gis.github.io/road2citygml3>
- ▶ Concepts of the CityGML 3.0 for modelling the streetspace
 - Semantics
 - Geometries
 - Topology
 - Appearance
- ▶ Examples
 - E.g. NYC, Melbourne, Ingolstadt, Munich
- ▶ Data downloads



Representation of Road Infrastructure

- ▶ Real world objects are represented by geographic features as defined in **ISO 19109**
- ▶ Each object has a **unique identifier** (gml:id attribute)
- ▶ **Hierarchical structure** / decomposition into individual objects

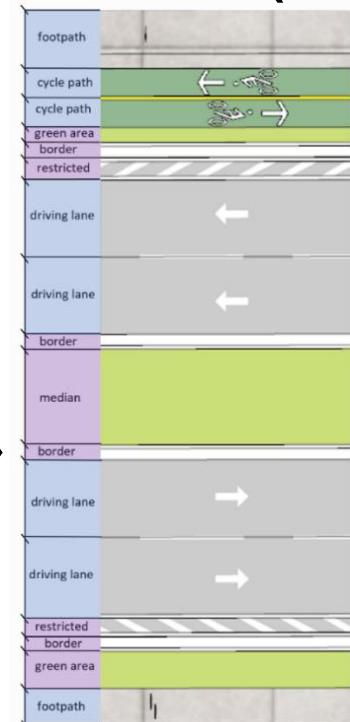
Road



Section



Traffic Areas (Lanes)



Representation of Roads

- ▶ A **Road** is a transportation space used by vehicles, bicycles and/or pedestrians.
- ▶ Usually **Roads** should be distinguished by individual names



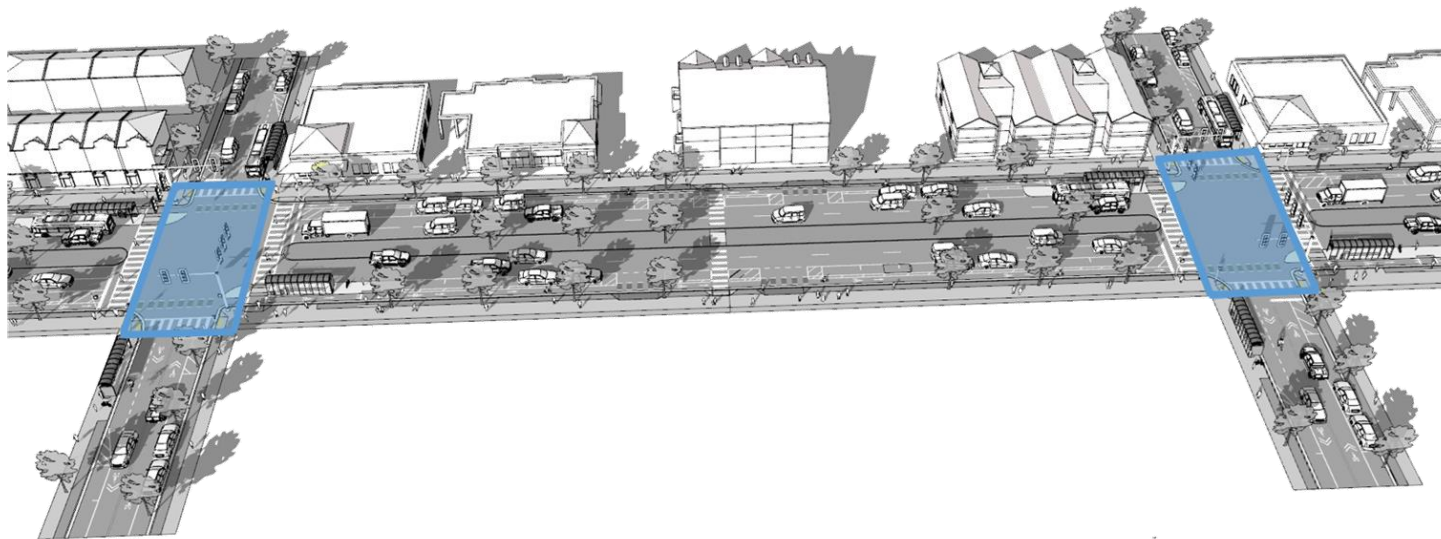
Segmenting road networks into Sections and Intersections

- ▶ **Roads** can consist of several **Sections**
- ▶ A **Section** is a transportation segment that can clearly be assigned to one **Road** (or **Railway**, **Track**, **Waterway**) object.
- ▶ **Sections** should cover the entire width of a **Road** and thus directly correspond to the representation of transportation objects in **granularity 'area'**.



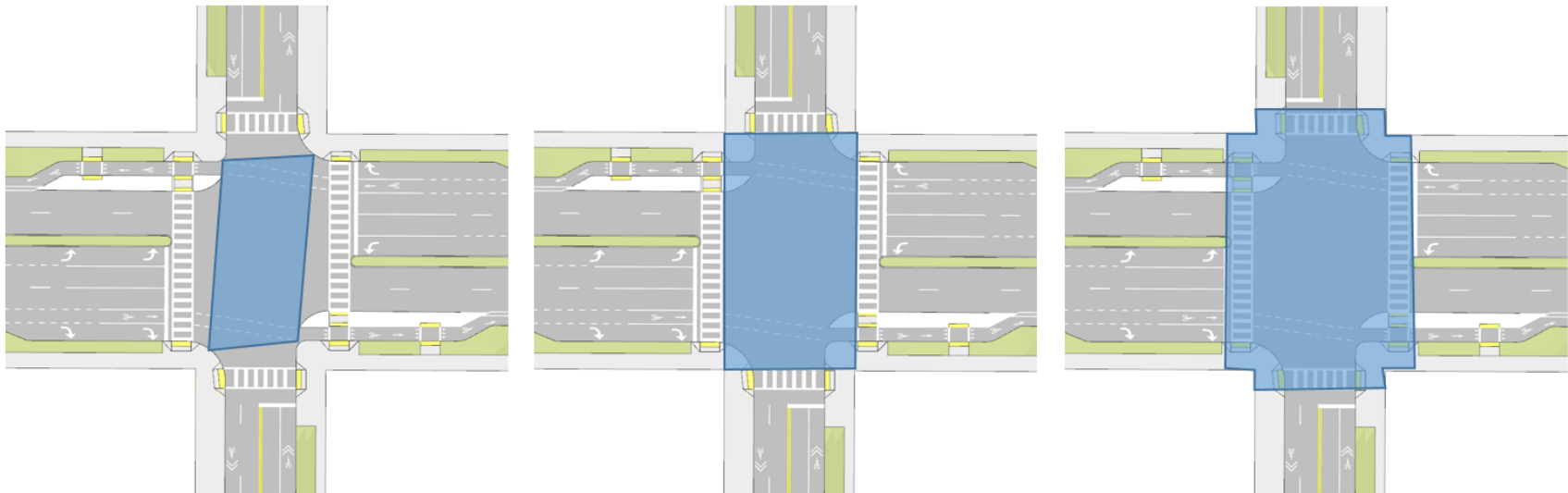
Segmenting road networks into Sections and Intersections

- ▶ An **Intersection** is a transportation space that is a shared segment of multiple **Roads** or other transportation objects such as **Railways** (e.g. a crossing of two **Roads** or a level crossing of a **Road** and a **Railway**).
- ▶ The link of an **Intersection** to multiple **Roads** can be explicitly modelled (using **XLinks**)



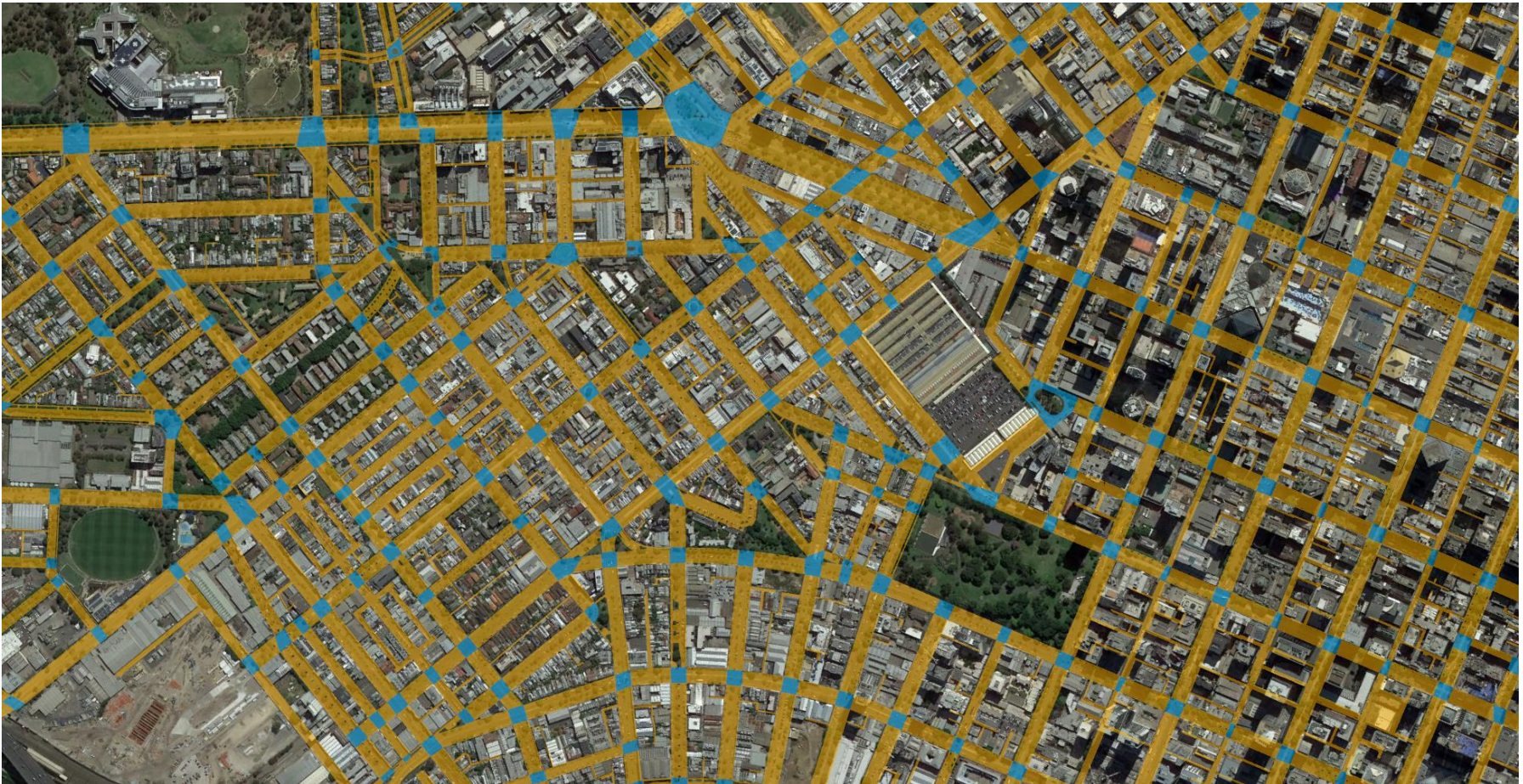
Segmenting road networks into Sections and Intersections

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- ▶ Different possibilities to define Intersections areas



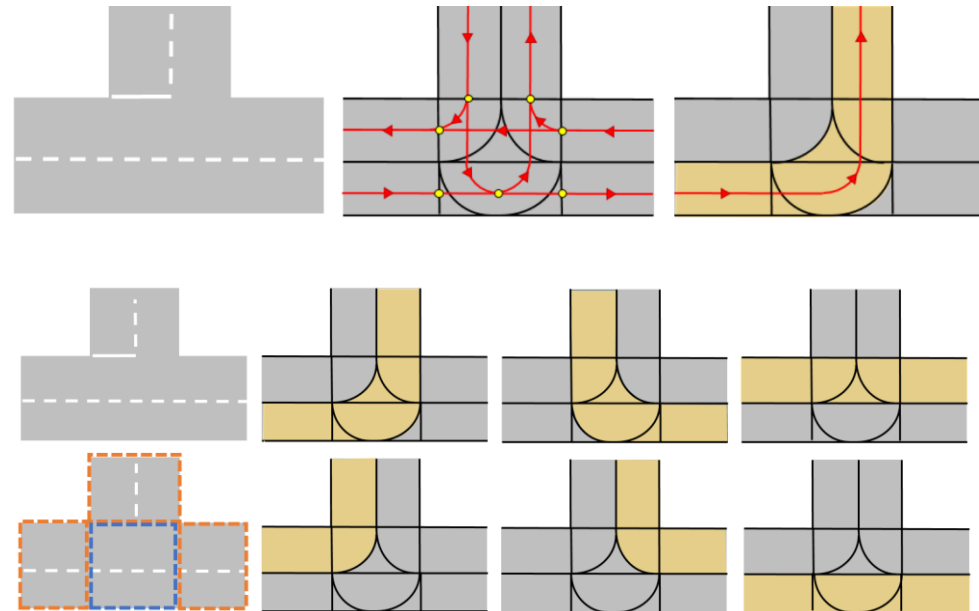
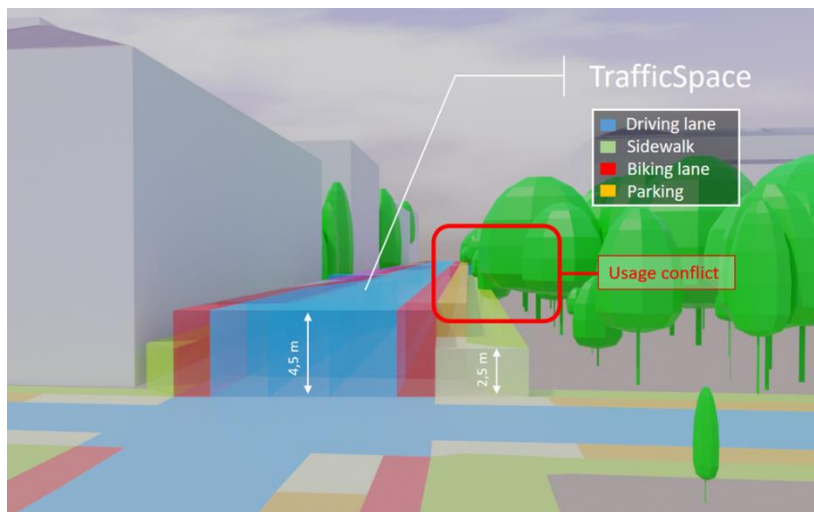
Segmenting road networks into **Sections** and **Intersections**

- ▶ Example: Melbourne



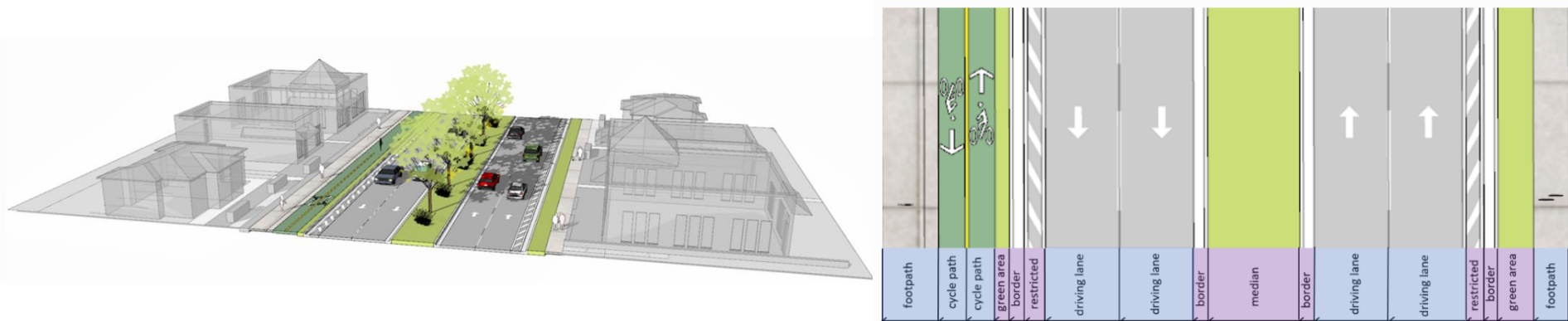
Transportation Spaces in CityGML

- ▶ **TrafficSpace** is a space in which traffic takes place
- ▶ Can be represented geometrically using e.g. **linear or volumetric geometries** (or geometric representation can be omitted if not required)
- ▶ Ground surfaces of **TrafficSpaces** are **TrafficAreas**



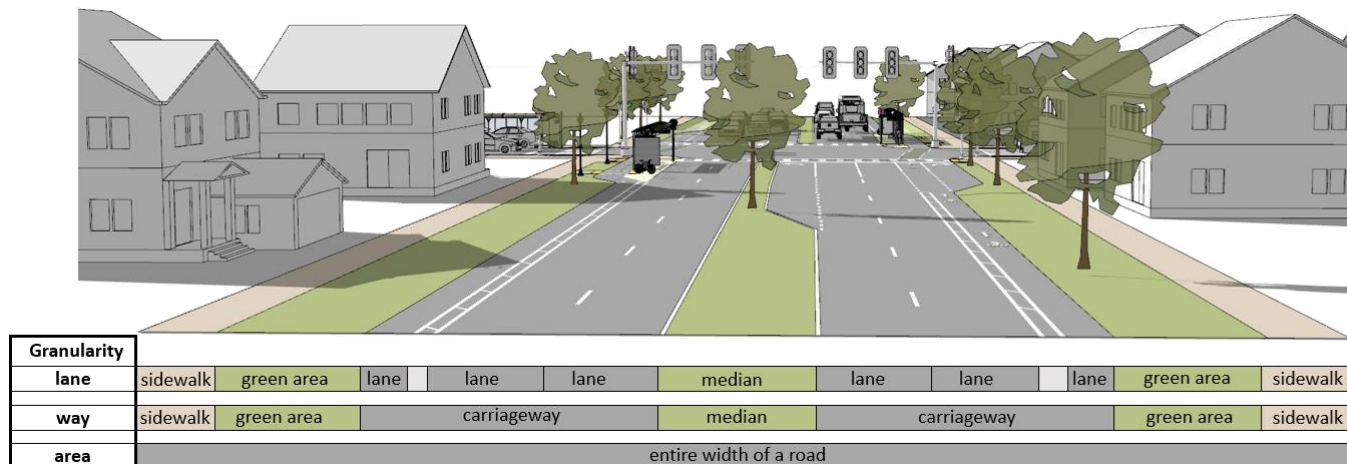
TrafficAreas and AuxiliaryTrafficAreas

- ▶ A **TrafficArea** is the ground surface of a **TrafficSpace** upon which traffic actually takes place.
- ▶ **AuxiliaryTrafficAreas** are describing further elements of the **Road**, like kerbstones, raised medians, and green areas not intended for direct traffic usage.
- ▶ Standardized attributes on function, surface material, etc.
- ▶ **Example: Section** with two carriageways segmented into **TrafficAreas** and **AuxiliaryTrafficAreas**



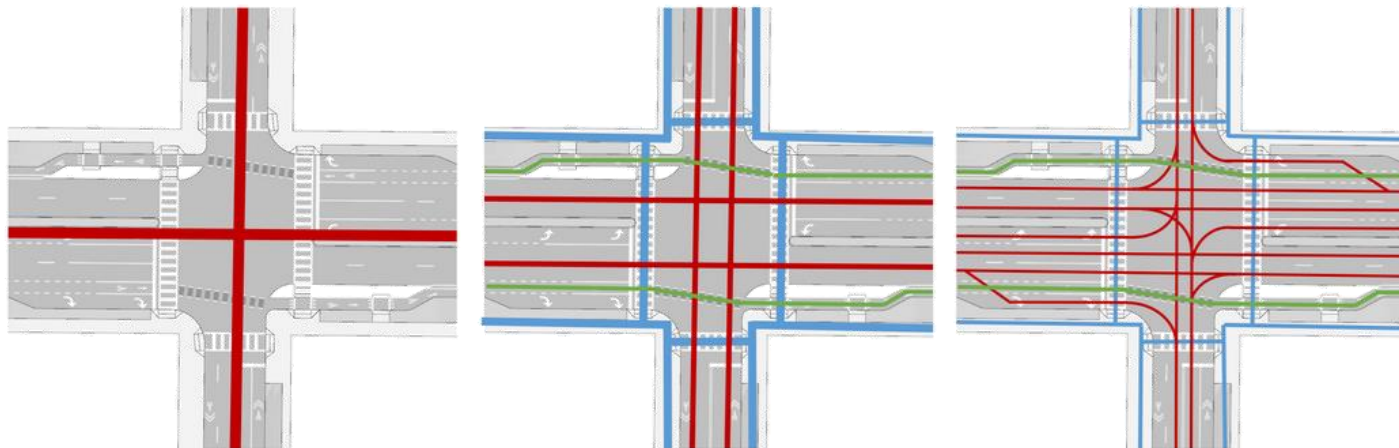
Three levels of granularity

- ▶ In **granularity 'area'** the entire width of a **Road** is modelled with one single object.
- ▶ In **granularity 'way'** individual objects are modelled per surface function (or traffic type). This means one object per carriageway is used. *Granularity of OpenDRIVE lane data*
- ▶ In **granularity 'lane'** each individual lane (including driving lanes for vehicles) are modelled separately.


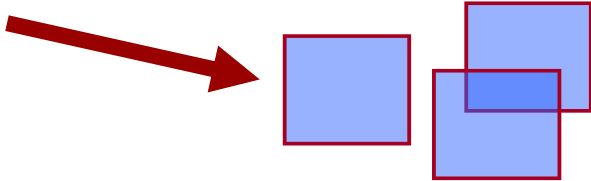


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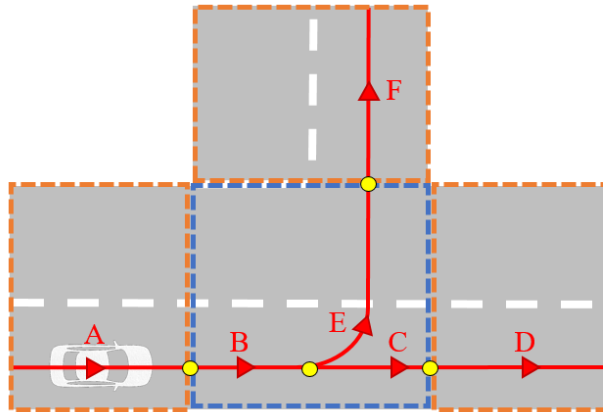
Geometry

- ▶ ISO 19107:2003 Geographic information - Spatial schema
- ▶ Geometry Types most relevant for Transportation Module
 - GM_Point
 - GM_MultiPoint
 - **GM_MultiCurve** 
 - **GM_MultiSurface** 
 - GM_Solid
 - GM_Object
- ▶ Nearly all geometries use 3D coordinates
- ▶ Coordinates always have to be given with respect to a coordinate reference system (CRS)

<<CodeList>> GM_CurveInterpolation	
+	linear
+	geodesic
+	circularArc3Points
+	circularArc2PointWithBulge
+	elliptical
+	clothoid
+	conic
+	polynomialSpline
+	cubicSpline
+	rationalSpline

Topology

- ▶ Predecessor / Successor Concept
- ▶ Traffic direction attribute
- ▶ Useful for routing / navigation applications

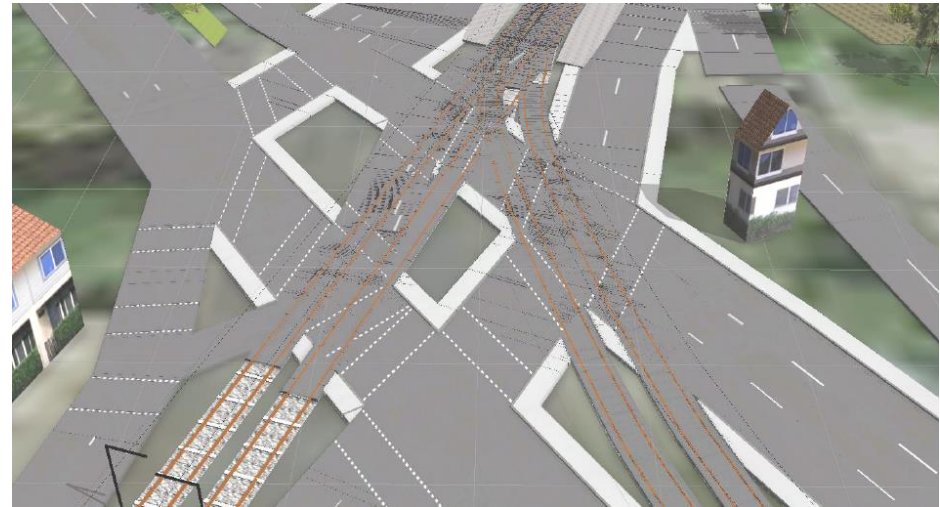


TrafficSpace	Predecessor	Successor(s)
A		B
B	A	E, C
C	B	D
D	C	
E	B	F
F	E	

- ▶ Linking concept for non-redundant representations (e.g. XLinks)
 - Geometry shared by different semantic objects only needs to be represented once

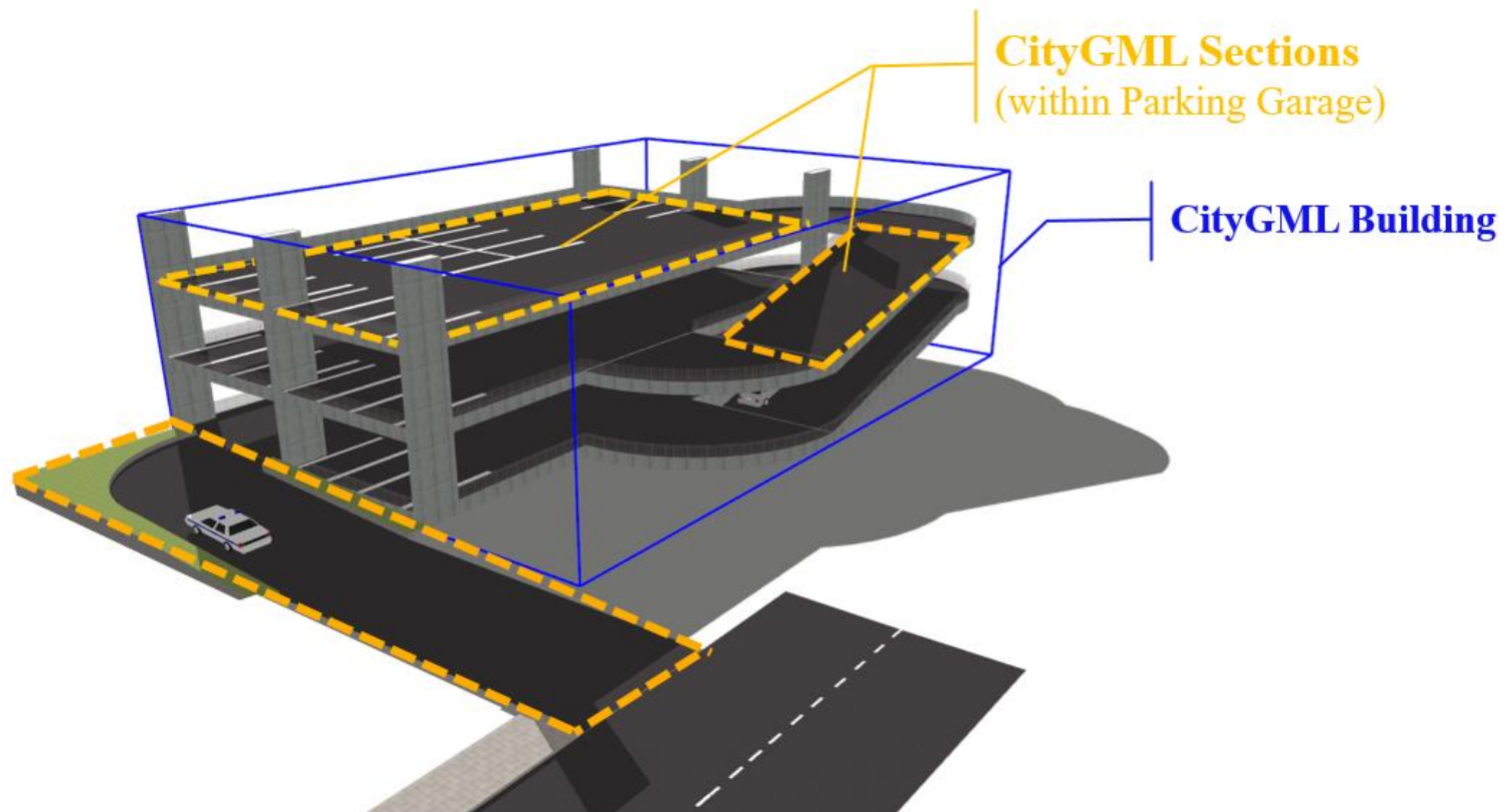
Integration of multiple Transportation types

- ▶ Concepts apply to Road, Railway and Waterway infrastructure
- ▶ Combined and non-redundant geometric and semantic modelling of multiple transportation infrastructure possible
- ▶ **Consistent, integrated and complete 3D city model**



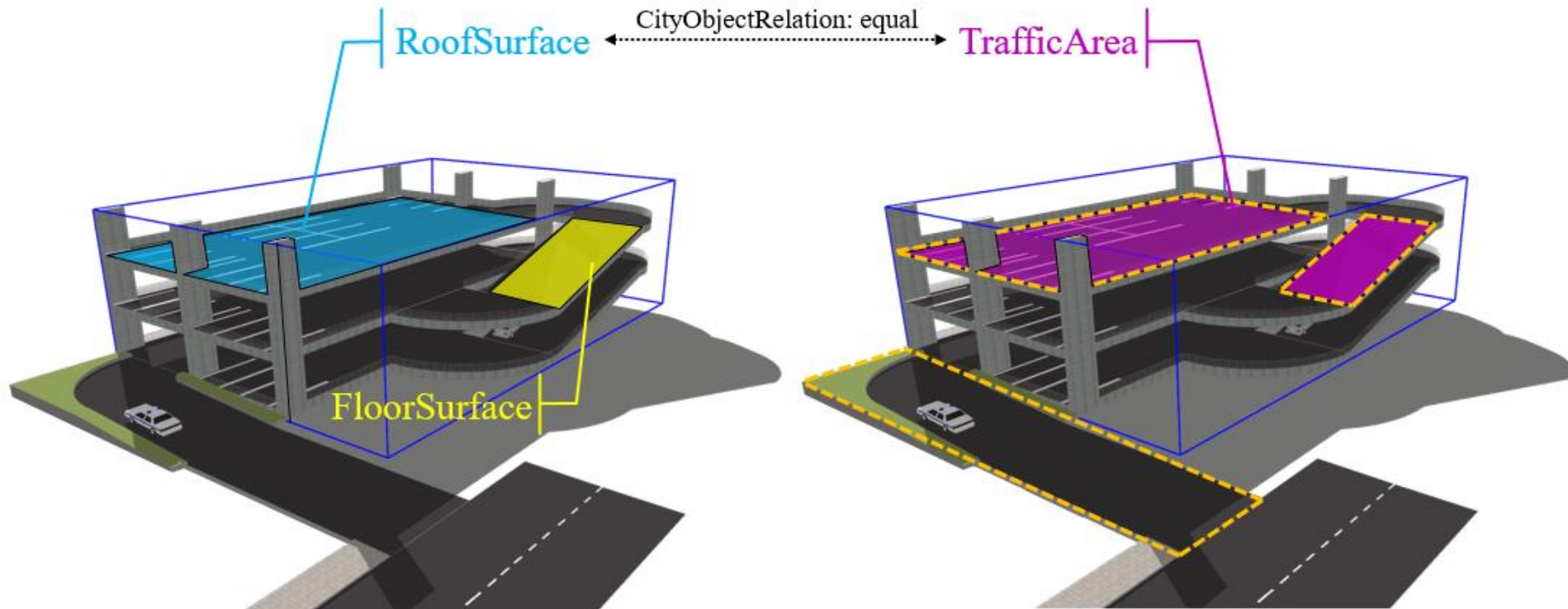
Roads within Buildings (Parking garage)

- ▶ Transportation networks and *Roads* can reach into *Buildings* (e.g. within a parking garage)



Roads within Buildings (Parking garage)

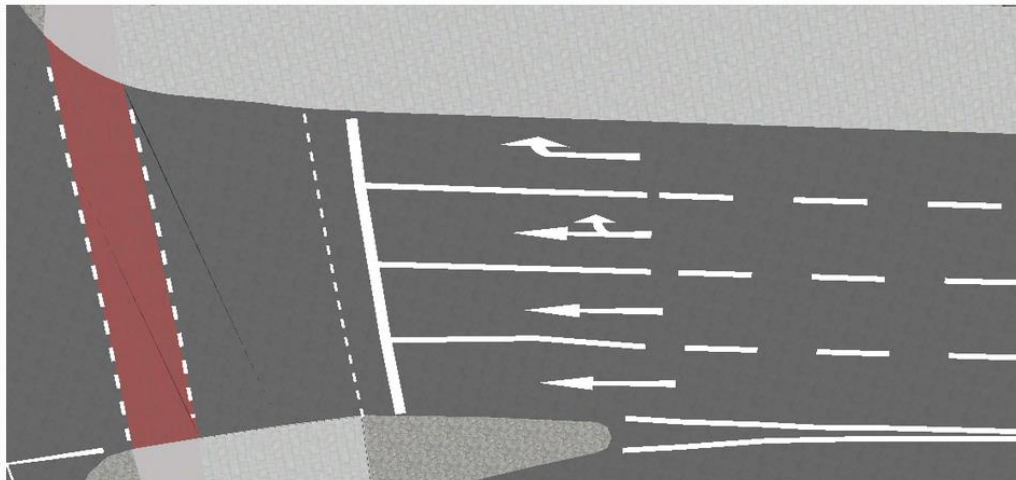
- ▶ Transportation networks and *Roads* can reach into *Buildings* (e.g. within a parking garage)



Other relevant CityGML objects

► Markings

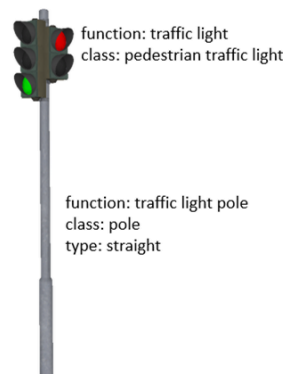
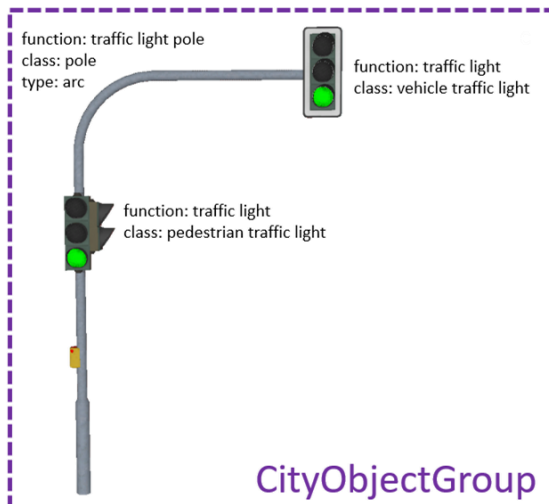
- Visible pattern on a transportation area relevant to the structuring or restriction of traffic
- E.g. using explicit (polygonal) geometries
- Each marking can be related to a specific lane
- Attributive information on function (e.g. stop line, arrow straight, etc.) can be contained



Other relevant CityGML objects

► CityFurniture

- Object or piece of equipment installed in the outdoor environment for various purposes (e.g. street signs, traffic signals, street lamps, benches, trash bins, bike racks, etc.)
- Traffic signs / lights can be related to individual lanes
- Implicit or explicit geometries (point / surfaces geometries or actual 3D models)



function: road sign
class: 305



function: sign pole
class: pole

function: road sign
class: 205



function: sign pole
class: pole

function: road sign
class: 206

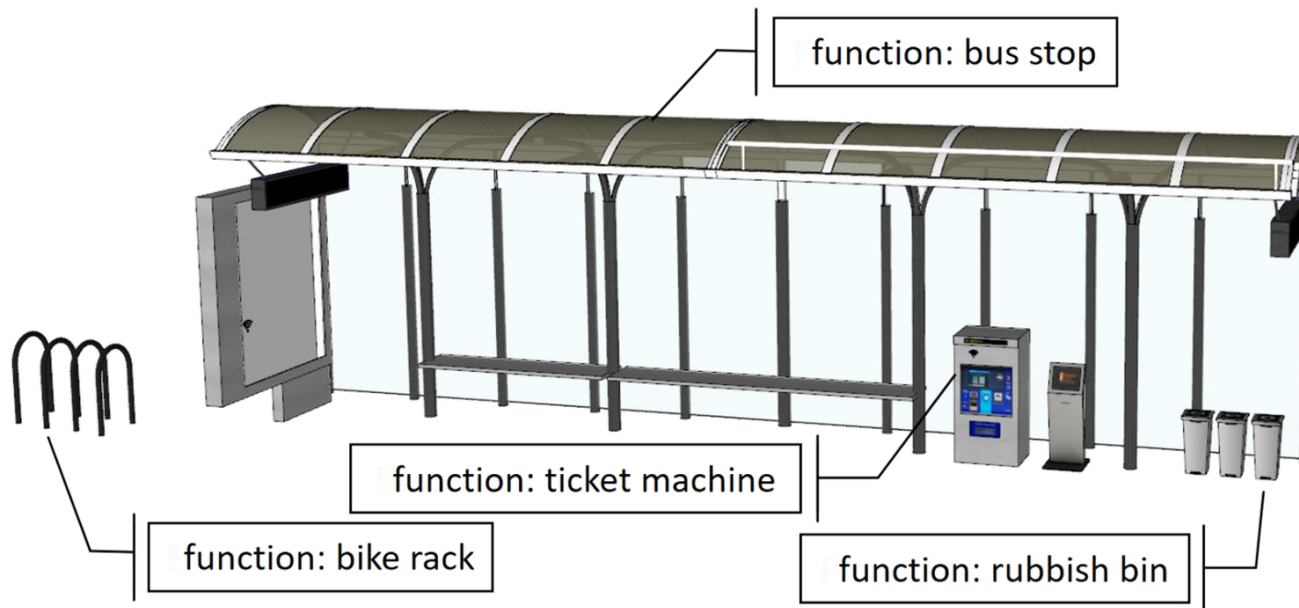


function: sign pole
class: pole

Other relevant CityGML objects

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- Object or piece of equipment installed in the outdoor environment for various purposes (e.g. street signs, traffic signals, street lamps, benches, trash bins, bike racks, etc.)



Other relevant CityGML objects

► Holes

- Openings in the surface of a street, road, or plaza, such as road damage, manholes, or gullies



Other relevant CityGML objects

- ▶ **Squares**
- ▶ Transportation space for unrestricted movement of vehicles, bicycles and/or pedestrians
- ▶ Includes plazas as well as large sealed surfaces such as parking lots or gas stations



Other relevant CityGML objects

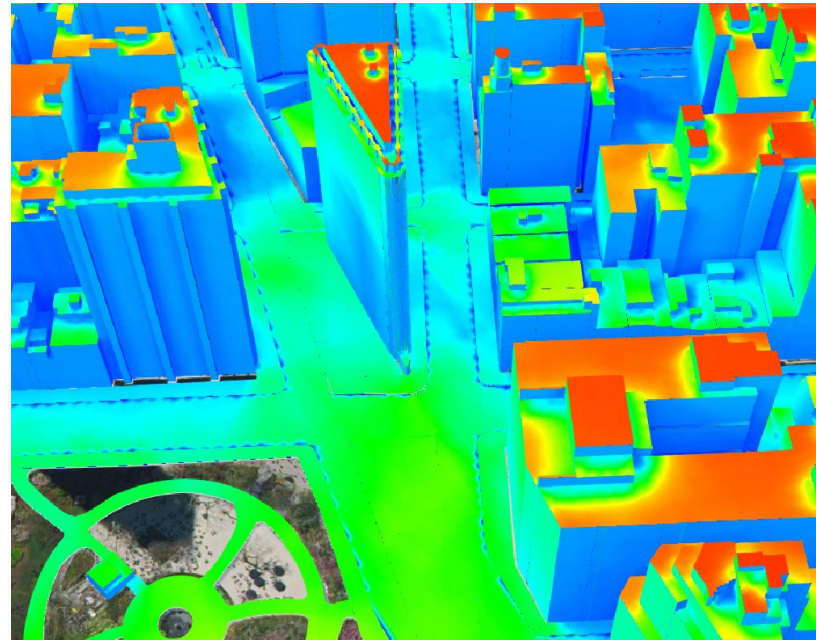
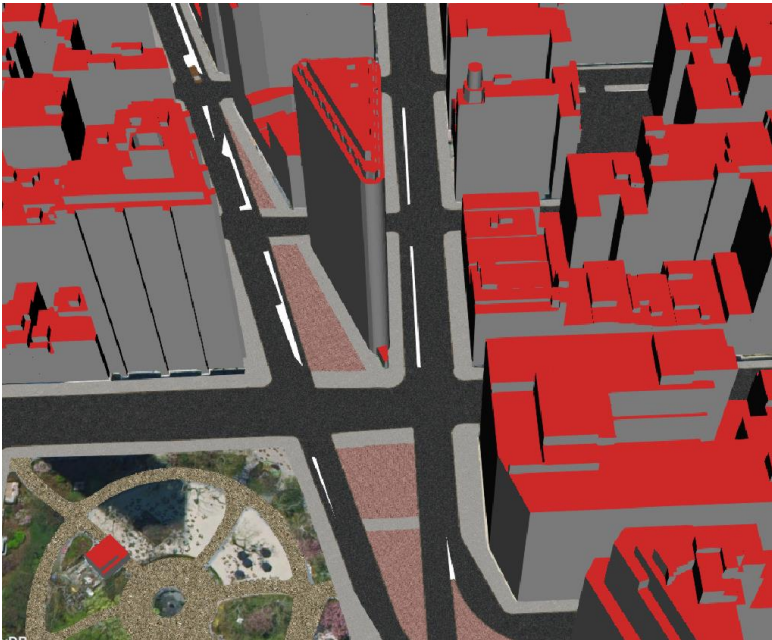
► Vegetation

- Solitary vegetation objects, such as trees, bushes and ferns, or vegetation areas that are covered by plants of a given species or a typical mixture of plant species, such as forests, steppes and wet meadows



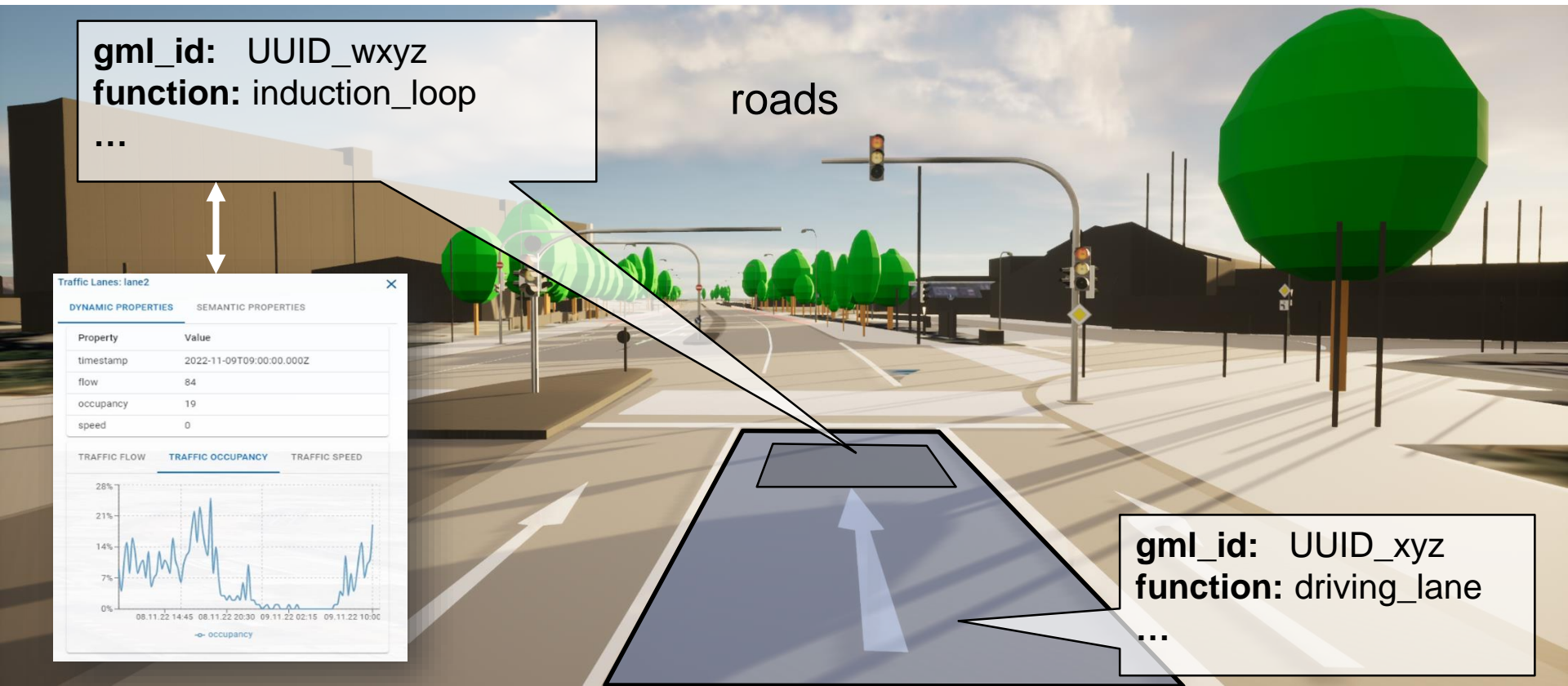
Appearance

- ▶ Colors / textures can be associated with city objects
- ▶ E.g. material definitions from the X3D and COLLADA standards
- ▶ Single surface geometry object may have surface data for multiple themes (arbitrary categories, e.g. solar irradiation)



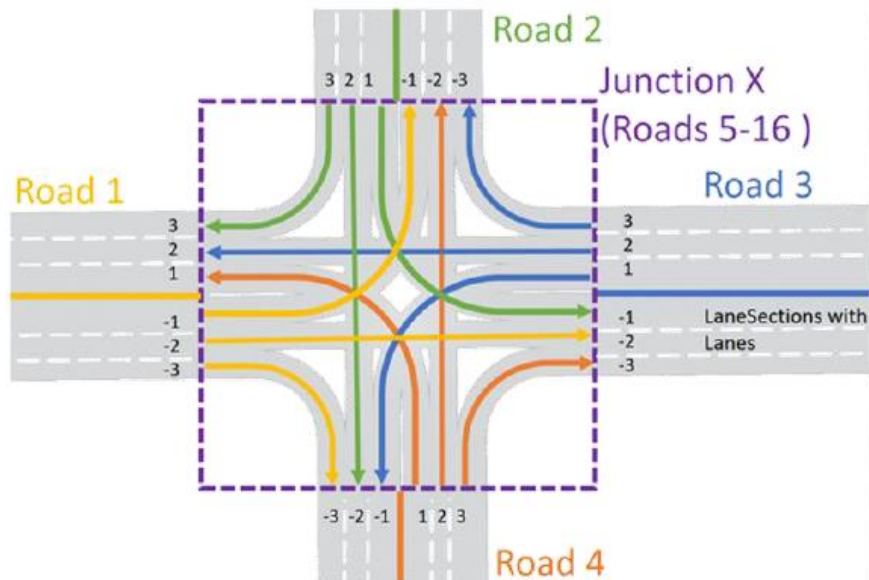
Representing time-dependent properties using Dynamizers

- ▶ **Dynamizer**
- ▶ Concepts that enables representation of time-varying data for city object properties as well as for integrating sensors with 3D city models.



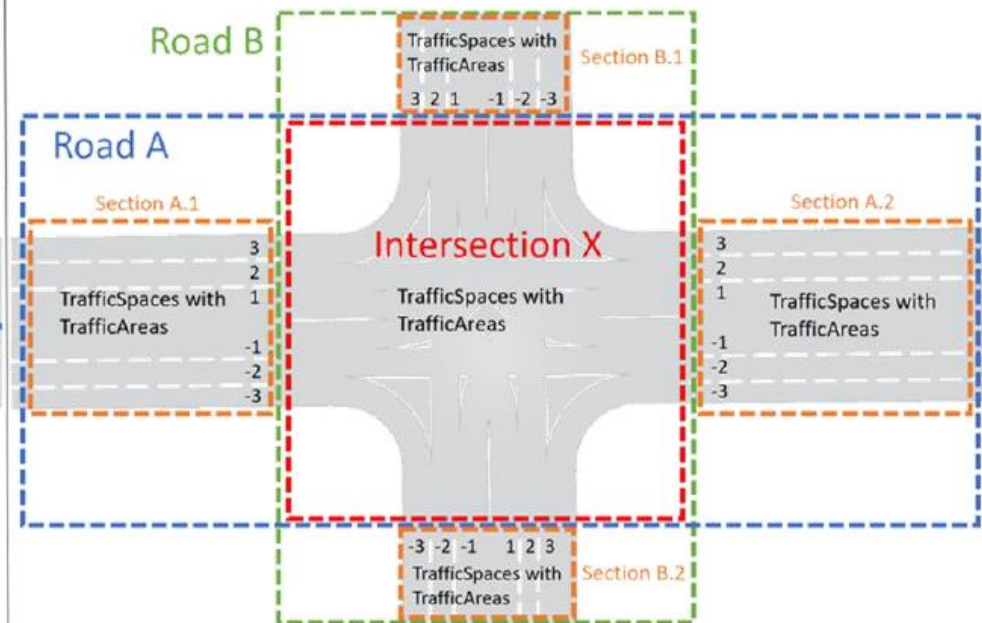
Comparison of OpenDRIVE and CityGML

OpenDRIVE Standard Roads /
Roads within a Junction



Referenceline-based (parametric)
redundant and overlapping
geometries and data gaps

|| **CityGML** Roads with Sections /
and Intersection

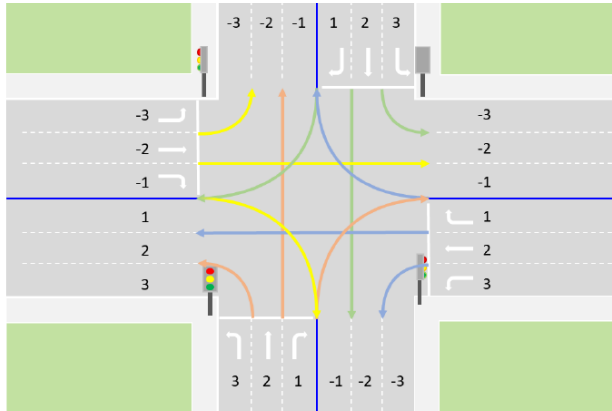


Surface-based (explicit coordinates)
and non-redundant without
overlapping geometries or gaps

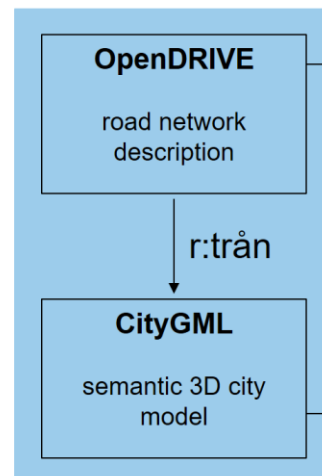
Open source OpenDRIVE to CityGML converter

<https://rtron.io/>

Parametric OpenDRIVE



Spatio-Semantic Road Space Model



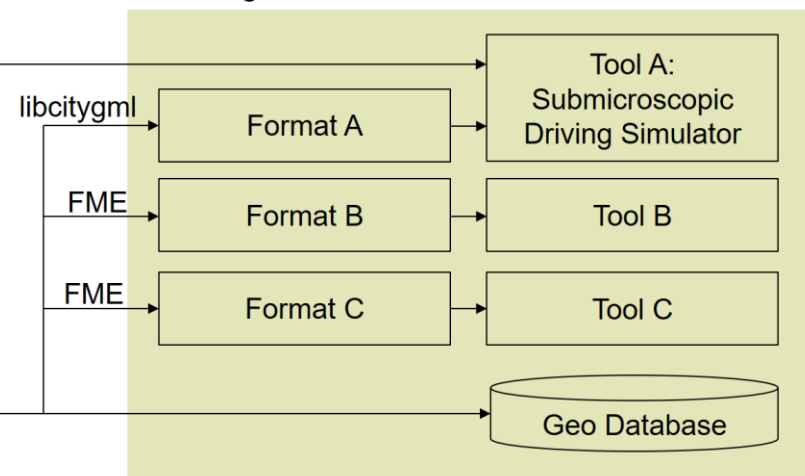
Semantic 3D city model with explicit coordinates



Application

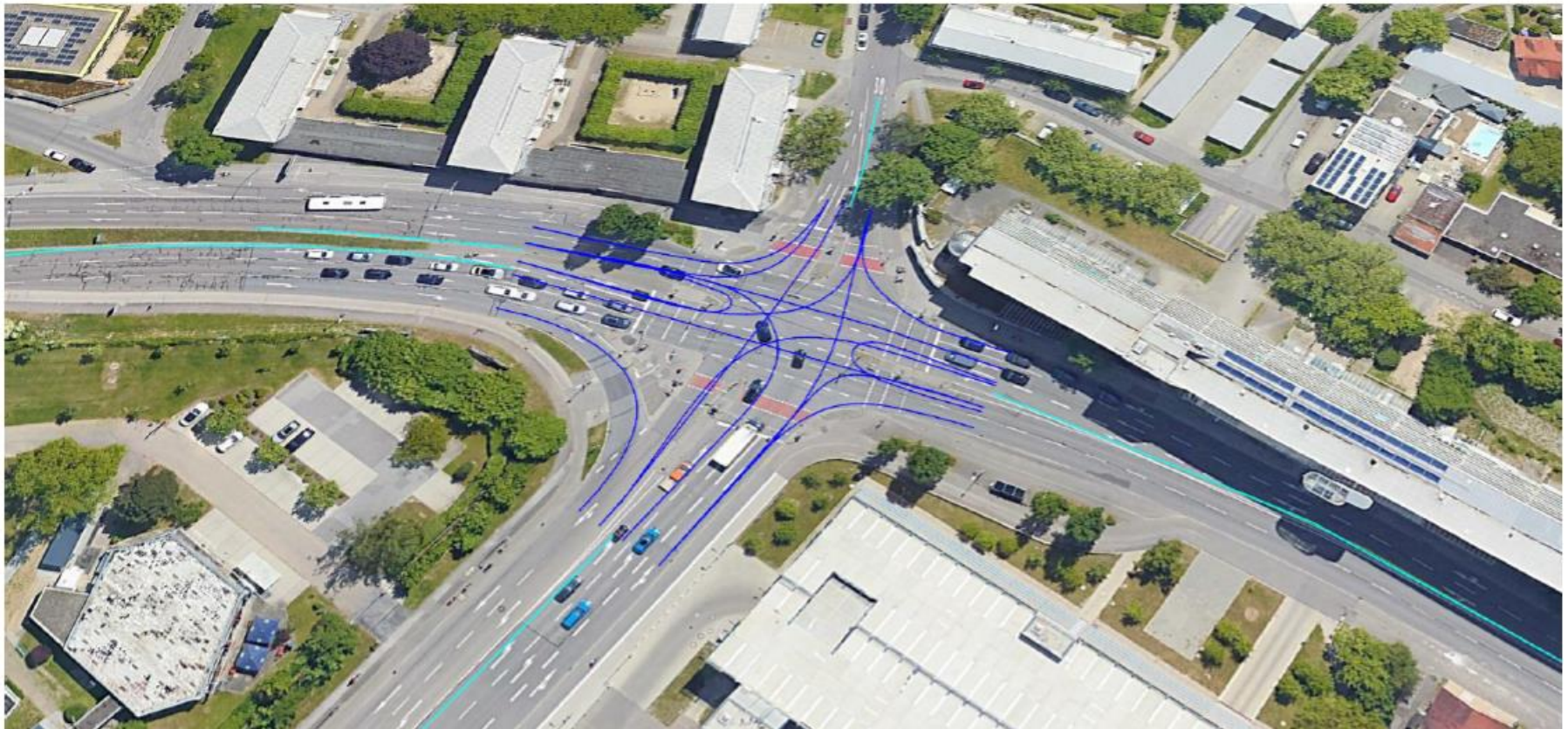
Target Formats

Tools



CityGML 3.0 from OpenDRIVE

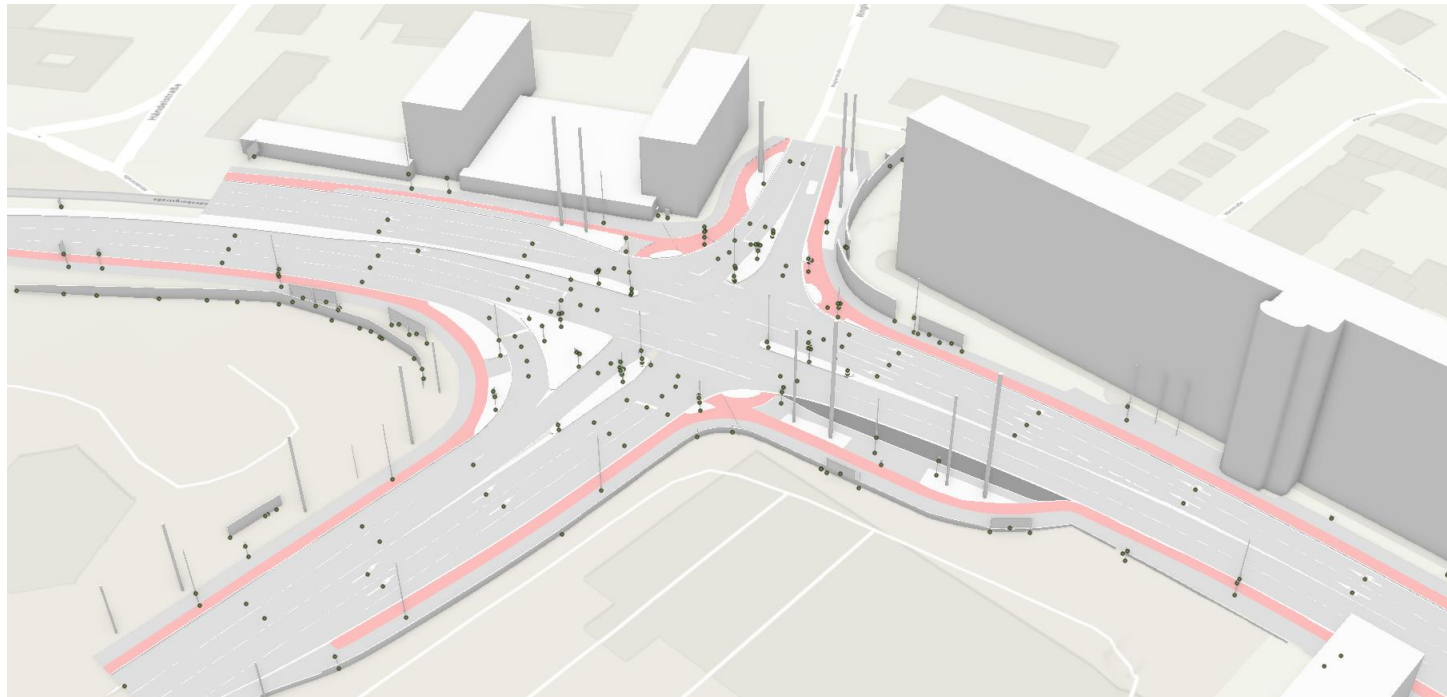
- ▶ OpenDRIVE data created by 3DMappingSolutions GmbH
Intersection in Ingolstadt



CityGML 3.0 from OpenDRIVE

Converted from OpenDRIVE to
CityGML 3.0 using r:tron
Contains overlaps and redundant geometries
due to the original data structure

<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	AuxiliaryTrafficArea (613)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	AuxiliaryTrafficSpace (406)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	Building (10)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	CityFurniture (279)
<input type="checkbox"/>	<input checked="" type="checkbox"/>	CityModel (1)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	GroundSurface (10)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	Intersection (1)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	Marking (618)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	Road (1)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	RoofSurface (10)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	Section (5)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	SolitaryVegetationObject (20)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	TrafficArea (751)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	TrafficSpace (675)
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	WallSurface (66)



CityGML 3.0 aus OpenDRIVE

CityFurniture

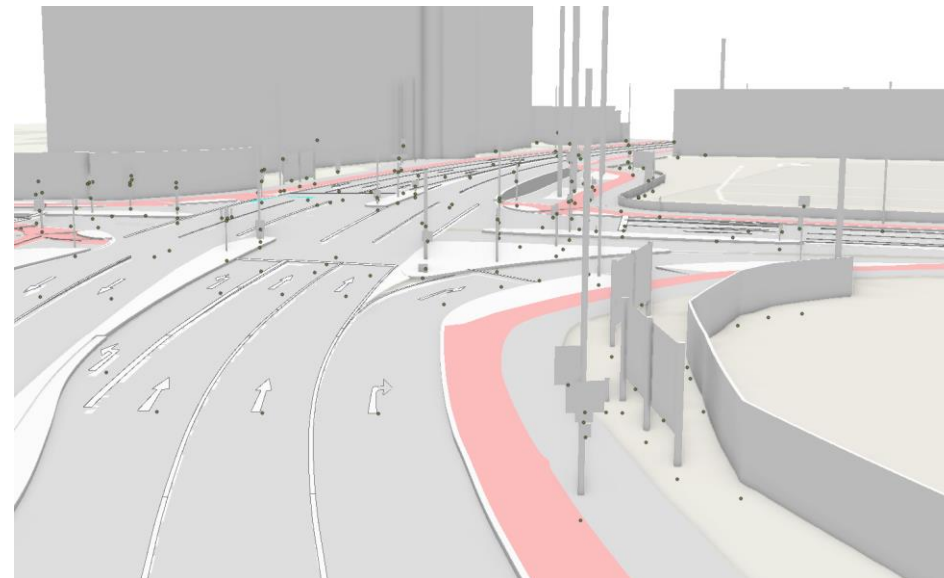
- Poles
- Traffic signs
- Traffic lights
- Barriers
- etc.

Vegetation

- Trees
- Information on height, diameter, etc

Information on signs / traffic lights and trees is (in some cases) abstracted with points containing attributes on type-subtype etc.

This can be substituted with actual 3D sign models etc.



CityGML 3.0 Streetspace Modeling Example 1

- ▶ Streetspace model of Ingolstadt automatically generated from OpenDRIVE data and visualized in the UnrealEngine



<https://www.youtube.com/watch?v=t5UXEVQcMj4>

CityGML 3.0 Streetspace Modeling Example 2

- Digital Twin Munich: Web-based traffic simulation visualization combined with a semantic 3D city model



CityGML 3.0 Streetspace Modeling Example 3

- Dataset examples:

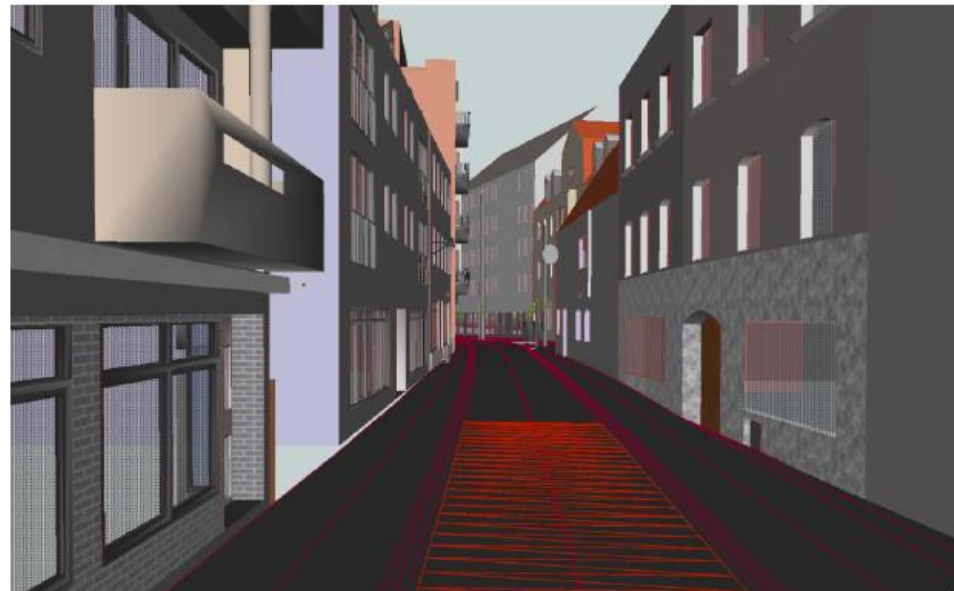
<https://github.com/savenow/lod3-road-space-models>

Easy combination of multiple (geo-referenced) datasets

Road model and point cloud



Road model and LOD3 buildings



Common Misunderstandings about CityGML

▶ *CityGML is just an exchange format*

- **NO!** - It is in the first place a conceptual schema on how to represent 3D city models in an interoperable, integrative, and multi-application supportive way
- Due to historic reasons the normative part of CityGML is its encoding as a GML application schema (there was no standards category for semantic data models in OGC back in 2006 – only abstract or implementation specifications by then)
- There are alternative mappings of the CityGML conceptual model onto other platforms like spatial databases, JSON, and Graph DB

▶ *CityGML is a visualization format*

- **NO!** – CityGML puts focus on the representation of spatio-semantic characteristics of 3D city and landscape features (Ontology)
- However, visualizations e.g. in 3DTiles, i3S, X3D, glTF, COLLADA, KML, OpenFlight can easily be generated from CityGML

(Some) Advantages of CityGML compared to (pure) visualization formats

- ▶ Extensive semantic, topological, temporal and geometric concepts
- ▶ Geo-referenced data (important for large infrastructure objects where the Earth's curvature cannot be neglected)
- ▶ Easy combination with other (geo-referenced) data
- ▶ Many cities worldwide model their 3D city models according to CityGML
- ▶ Database solution available (3DCityDB)
 - Spatial indices on the data
 - Spatio-semantic queries and analysis
- ▶ Searchability of objects and semantic information
 - Number intersection types
 - Relations between signs of a certain type next to vegetation
 - Road layout identification
- ▶ Association of sensor observations with semantic 3D models

Extending CityGML

► CityGML extension mechanisms

1. **Generic classes and attributes**
2. **Application Domain Extensions (ADE)**

Formally specified augment data model with additional concepts required by use-case (e.g. new properties or object types)

► Models can be enriched with additional information (generic attributes) very easily

- Reflective information
- Number of recognitions by vehicles
- Speed limit
- Intersection type
- ...

CityGML subsets

- ▶ CityGML is application independent and used by multiple disciplines and is useful to several communities
- ▶ Thus, CityGML contains many concepts and a powerful but complex data model

However,

- ▶ “Implementations may employ a subset of constructs according to their specific information needs.”
[CityGML 3.0 specification, 2021]
- ▶ Suggestion: Subset of relevant objects and concepts
 - Only used subset required to OpenDRIVE community

Conclusion

- ▶ **Revised** and **extended** concepts for modelling transportation Infrastructure in the context of semantic 3D city models
 - Concepts for **geometric and semantic segmentation**
 - Geometric representations: **linear, areal, volumetric or point cloud**
 - Concept for representing city objects using **Spaces**
 - Multiple **levels of granularity** (down to lane level)
 - **Integrated representation** for multiple transportation infrastructure (roads, railways, footpaths, waterways, etc.)
 - Including detailed information bicycle paths and pedestrian areas
- ▶ A number of use cases benefit from these concepts

Relevant links

- ▶ CityGML3.0
<https://www.ogc.org/standards/citygml>
- ▶ Guideline explaining CityGML 3.0 Transportation Module
<https://tum-gis.github.io/road2citygml3/>
- ▶ Interactive Streetspace Demos
<https://wiki.tum.de/display/gisproject/Online+Demo+Collection>
- ▶ Data Downloads
<https://wiki.tum.de/display/gisproject/Download+Section>
- ▶ 3DCityDB
<https://www.3dcitydb.org/3dcitydb/>
- ▶ Open Source Converter r:tr n: OpenDRIVE to CityGML
<https://rtron.io/>

Resources on CityGML

- ▶ CityGML 2.0 Standard [Gröger, Kolbe, Nagel, Häfele 2012]
<https://www.ogc.org/standards/citygml>
- ▶ T. H. Kolbe, 2009: Representing and Exchanging 3D City Models with CityGML. In: Lee, Zlatanova (eds.), 3D Geo-Information Sciences, Springer
<https://mediatum.ub.tum.de/node?id=1145752>
- ▶ B. Willenborg, M. Sindram, T. H. Kolbe, 2017: Applications of 3D City Models for a better understanding of the Built Environment. In: Behnisch, Meinel (eds.): Trends in Spatial Analysis and Modelling. Springer
<https://mediatum.ub.tum.de/node?id=1348882>
- ▶ List of worldwide Open Data 3D city models in CityGML („Awesome CityGML“):
<https://github.com/OloOcki/awesome-citygml>
- ▶ F. Biljecki, K. Kumar, C. Nagel, 2018: CityGML Application Domain Extension (ADE): overview of developments. Open geospatial data, softw. stand. 3, 13
<https://doi.org/10.1186/s40965-018-0055-6>

Resources on CityGML 3.0

- ▶ CityGML 3.0 Conceptual Model + UML Diagrams + Discussions
<https://github.com/opengeospatial/CityGML-3.0CM>
- ▶ CityGML 3.0 XML Schema Files, Test datasets
<https://github.com/opengeospatial/CityGML-3.0Encodings>
- ▶ IFC → CityGML 3.0 FME Workspace
<https://github.com/tum-gis/ifc-to-citygml3>
- ▶ T. Kutzner, K. Chaturvedi, T. H. Kolbe, 2020: CityGML 3.0: New Functions Open Up New Applications. PFG – Journal of Photogrammetry, Remote Sensing and Geoinformation Science, 2020, 19
<http://dx.doi.org/10.1007/s41064-020-00095-z>
- ▶ C. Beil, R. Ruhdorfer, T. Coduro, T. H. Kolbe, 2020: Detailed Streetspace Modelling for Multiple Applications: Discussions on the Proposed CityGML 3.0 Transportation Model. ISPRS International Journal of Geo-Information 9 (10)
<https://www.mdpi.com/2220-9964/9/10/603>

Additional Information

Alternative CityGML Encodings (1)

- ▶ **CityJSON** is a JSON-based exchange format for CityGML city models (www.cityjson.org)
 - issued as an „OGC Community Standard“
 - originally developed by TU Delft
 - there is some software support (e.g. different tools by TU Delft, 3DCityDB, FME, citygml4j, etc.)
- ▶ **3DCityDB** is a spatial/relational database schema for the storage and management of CityGML city models (www.3dcitydb.org)
 - developed by the Chair of Geoinformatics at TU Munich in cooperation with the companies virtualcitySYSTEMS and M.O.S.S.
 - Open Source implementation for PostGIS and Oracle Spatial
 - in productive use worldwide in many cities, countries and in research projects; sometimes embedded in commercial systems

Alternative CityGML Encodings (2)

- ▶ **OWL / RDF** schemas for the use and analysis of CityGML city models in the Semantic Web / Linked Data. There are two separate developments:
 - Ontology of the Univ. of Geneva (Prof. Gilles Falquet, Prof. Claudine Métral): <http://cui.unige.ch/isi/icle-wiki/ontologies> and <http://cui.unige.ch/isi/onto//citygml2.0.owl>
 - **CityOWL** Ontology of the Univ. of Lyon (LIRIS, Group of Prof. Gilles Gesquière): <https://github.com/VCityTeam/UD-Graph>
- ▶ Alternative encodings do not necessarily support the full model scope of CityGML
 - e.g. some limitations with CityJSON, and not directly compatible with OGC services like WFS; but more compact and simpler encoding compared to XML-based encoding, simpler processing e.g. in web browsers

The CityGML Ecosystem

- ▶ **CityGML is based on GML** and is thus compatible with many OGC web services standards, e.g.
 - **Web Feature Service** – Access (read, write, modify) entire 3D city models, individual objects and their components
 - **Web Processing Service** – generic interface for encapsulating functions (e.g. data transformations, AI analyses, etc.)
 - **3D Portrayal Service** – Visualization of 3D models (derivation of 3D visualization formats)
- ▶ For all services there are different implementations / products (both commercial and Open Source)
- ▶ These web services are in turn compatible with the **OGC Catalog Service for the Web (CS/W)** specification
- ▶ Comprehensive basis for **Smart City developments**

3D City Database

<https://www.3dcitydb.org>
<https://github.com/3dcitydb>

- ▶ Open Source software package for the efficient storage, management, and visualization of CityGML-based 3D city models

- ▶ **Development cooperation**

- Chair of Geoinformatics at TUM (Lead)
- virtualcitySYSTEMS GmbH, Berlin
- M.O.S.S. Computer Grafik System GmbH, Taufkirchen



- ▶ **Development status** (current version: 4.2.0)

- full support of CityGML 1.0.0 and 2.0.0
- Oracle/PostGIS relational database schema + Import/Export tool with a graphical user interface and a command line interface
- offers a Web Feature Services 2.0 according to the OGC standard
- V5.0 currently under development → support of CityGML 3.0

Working with / Visualization of CityGML Datasets

- ▶ **FZKViewer** [KIT Karlsruhe, free software]
<https://www.iai.kit.edu/english/1648.php>
- ▶ **eveBIM** [CSTB France, free software]
<https://www.evebim.fr/telechargement/>
- ▶ **3DCityDB + 3DCityDB Web Viewer** [TU Munich / VCS / MOSS, Open Source software]
<https://www.3dcitydb.org>
- ▶ **Azul for MacOS** [TU Delft, Open Source software]
<https://github.com/tudelft3d/azul>
- ▶ **FME Data Inspector** [Safe Software, commercial]
<https://www.safe.com/fme/fme-desktop/>
- ▶ **ArcGIS Interoperability Extension** [ESRI, commercial]
<http://www.esri.com/software/arcgis/extensions/datainteroperability>

Extract / Transform / Load (ETL) for CityGML

- ▶ **HALE Studio** [wetransform, Open Source software]
<https://github.com/halestudio/hale>
- ▶ **Feature Manipulation Engine** [Safe Software, commercial]
<https://www.safe.com/fme/fme-desktop/>
- ▶ **GDAL GML Application Schema** [Open Source software]
<https://gdal.org/drivers/vector/gmlas.html>
- ▶ **Deegree** [lat/lon GmbH, Open Source software]
<https://github.com/deegree/deegree3>
- ▶ **CityGML tools** [citygml4j, Open Source software]
<https://github.com/citygml4j/citygml-tools>