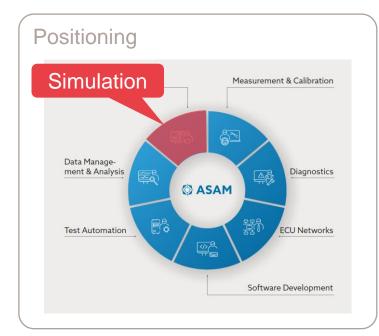
# **ASAM OpenDRIVE®**







Version 1.8

Format XML XSD

License free

First release 2018

## Topics

Daimler DRIVE

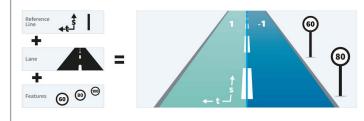
OpenDRIVE (VIRES, 2005)

ASAM OpenDRIVE (2018)

- First OpenX-standard to be transferred to ASAM
- Foundation for ASAM's domain "Simulation"

### Scope

Description of static road networks



### Connects with

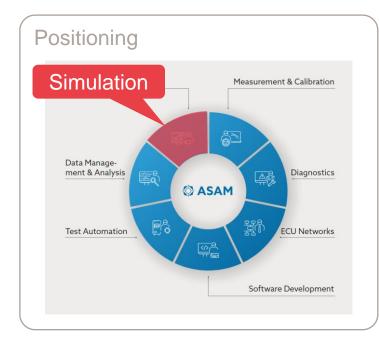
- ASAM OpenCRG
- ASAM OpenSCENARIO

- Description of synthetic and realworld road networks
- Driving and traffic simulation



# ASAM OpenCRG® (Curved Regular Grid)





Version 1.2.0 **Format** CRG + S/W

License free

First release 2018

### Topics

**Daimler CRG** 

OpenCRG (VIRES, 2008) ASAM OpenCRG (2018)

- OpenCRG was a joint effort by Daimler, BMW, Audi, Porsche, Volkswagen
- Transfer to ASAM in 2018 along other OpenX-standards

### Scope

Description of road surfaces



### Connects with

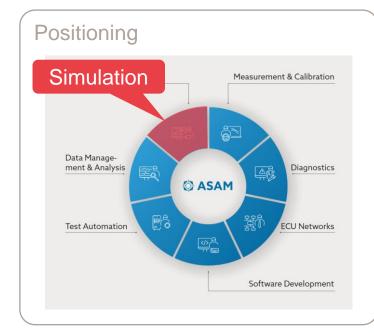
ASAM OpenDRIVE

- **Driving simulation**
- **NVH** simulation
- **Endurance testing**



# **ASAM OpenSCENARIO®**





Version

1.2.0

XML XSD

License free

First release 2018

### **Topics**

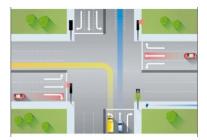
## OpenSCENARIO (VIRES, 2013)

ASAM OpenSCENARIO (2018)

- Intended for logical (paramerized) and concrete scenarios
- Reference implementation: esmini (on github)
- Large user base

### Scope

 Description of dynamic elements in road networks



### Connects with

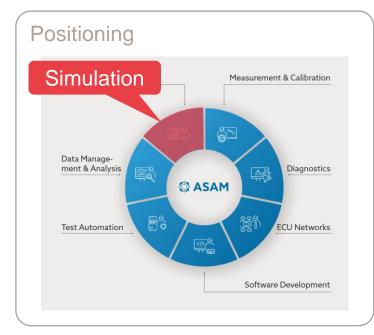
ASAM OpenDRIVE

- Traffic simulation
- Scenario simulation
- Vehicle maneuvers and actions



# **ASAM OpenSCENARIO® 2**





Topics

- Developed by ASAM
- Ideal for abstract and logical (paramerized) scenarios
- Abstraction of actions from static environment (road)

Scope

Dynamic scenario description



Connects with

n/a

### Application areas

- Coverage-based testing
- X-in-the-loop testing
- Scenario simulation

Version **2.0.0** 

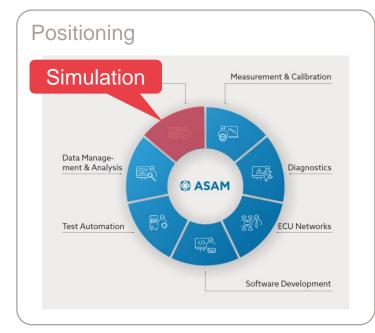
Format
Language
+ Domain
model

free free

First release **2022** 

# **ASAM OpenLABEL®**





Version **1.0.0** 

Format **JSON** 

License free

First release 2021

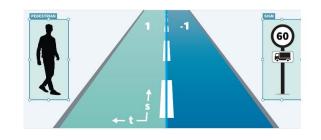
### **Topics**

- Initiated and developed by ASAM
- Allows the import of ontologies and taxonomies
- Labeling in single frames or across series of frames
- Quickly adopted by railroad industry



### Scope

Object labeling and scenario tagging



### Connects with

OpenXOntology

- Multi-sensor data labeling
- Scenario tagging

