The ASAM OpenX Landscape

Benjamin Engel CTO, ASAM eV 01.12.22 ASAM Regional Meeting China





Association for Standardization of Automation and Measuring Systems

Quick Intro...

Ben Engel

CTO @ ASAM

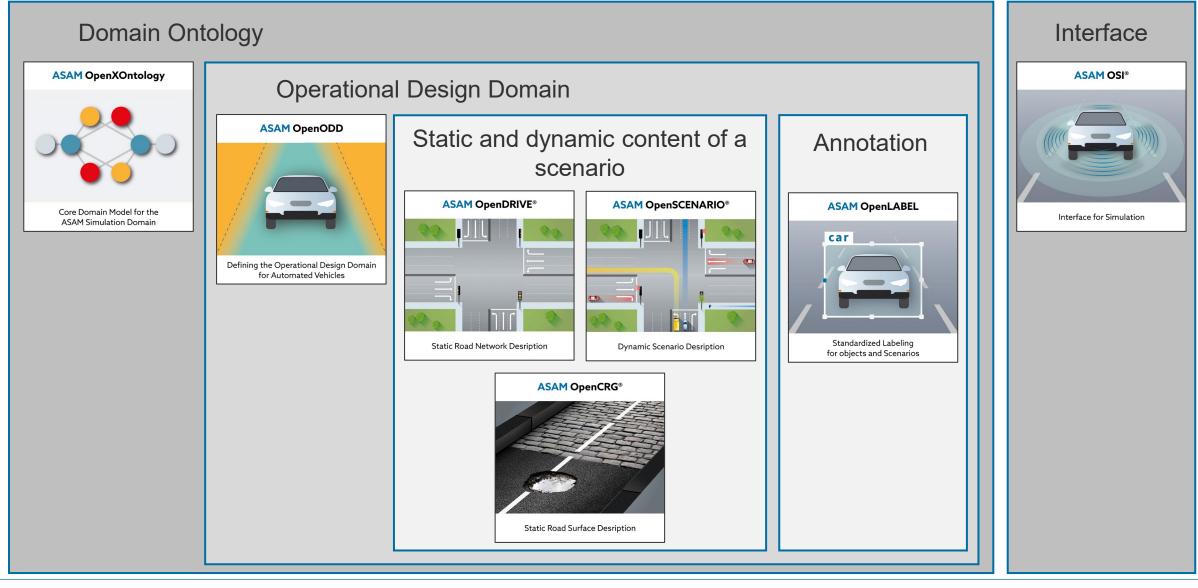
Feel free to reach out if you have any questions!

benjamin.engel@asam.net





Vison of ASAM OpenX...

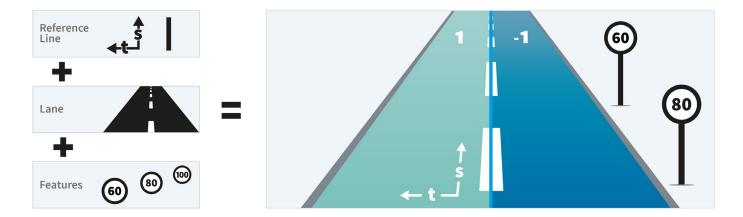




OpenDRIVE

- File format for the description of road networks.
- V1.6.1 released March 2021
 - Integration of OpenCRG
 - Bug fixes & clarifications
- New project started in May 2021 [Proposal]
 - Two releases:
 - V1.7.0 in July 2021
 - Address known issues in V1.6.1
 - V1.8.0 planned for June 2023
 - New features based on concepts from the <u>OpenDRIVE Concept Paper</u>







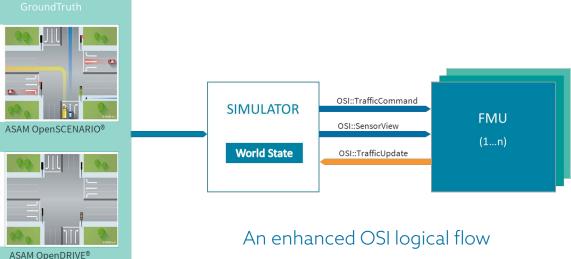
Open Simulation Interface (OSI)

• Open-source interface between models (e.g. sensors, traffic participants) and simulation environments

Scenario

Мар

- V3.5.0 released July 2022
- Followup project running from September 2022 to early 2024
 - V3.6.0 planned for March 2023
 - V4.0.0 for January 2024
 - Planned features:
 - Further alignment with other ASAM standards
 - Performance improvements
 - Streaming Interface for Visualization
 - Improvements to existing interfaces
 - Support for additional use cases and other domains ASAM OpenT
 - Support for vehicle internal interfaces







Test Specification

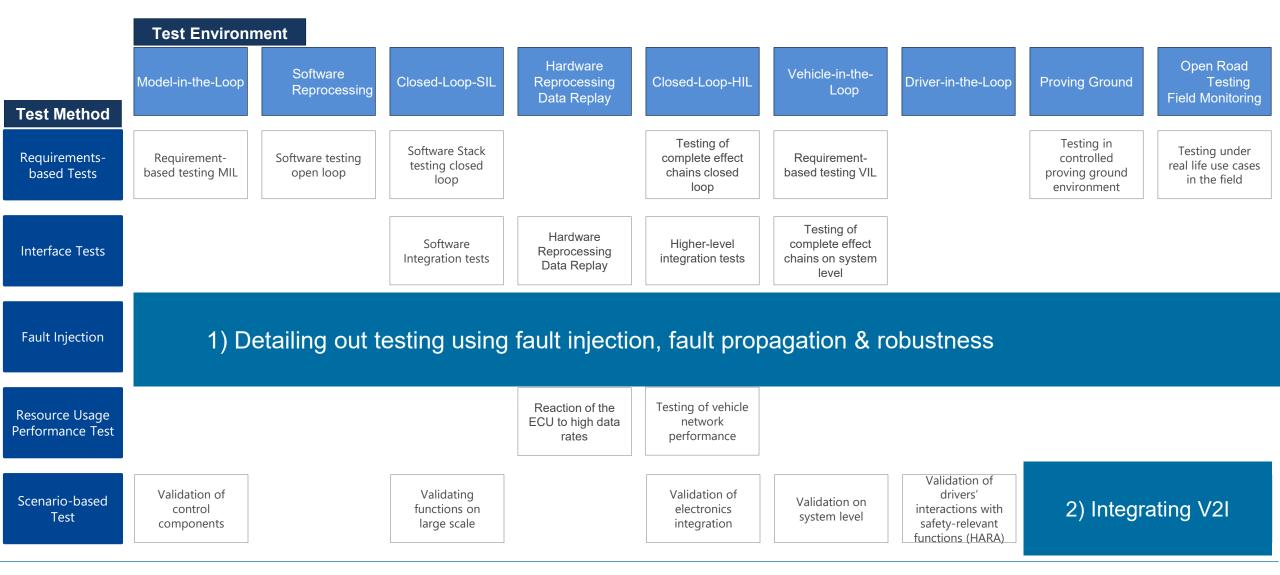
- Enrollments to participate are open (ASAM website -> proposals -> Test Specification
- Two goals
 - 1. Testing blueprint.

Long term goal: A blueprint for development and type approval authorities on testing to make the safety argumentation for ADAS systems.

- Fault injection, fault propagation & robustness testing
- Integration of V2X in scenario-based testing
- 2. Standardization
 - At least one project proposal to be prepared for March 2023.
 - Proposal will outline a project for a test specification standard and maybe development of an ontology for test specification



Define Test Strategies for ADAS/AD and SDV





OpenSCENARIO



OpenSCENARIO

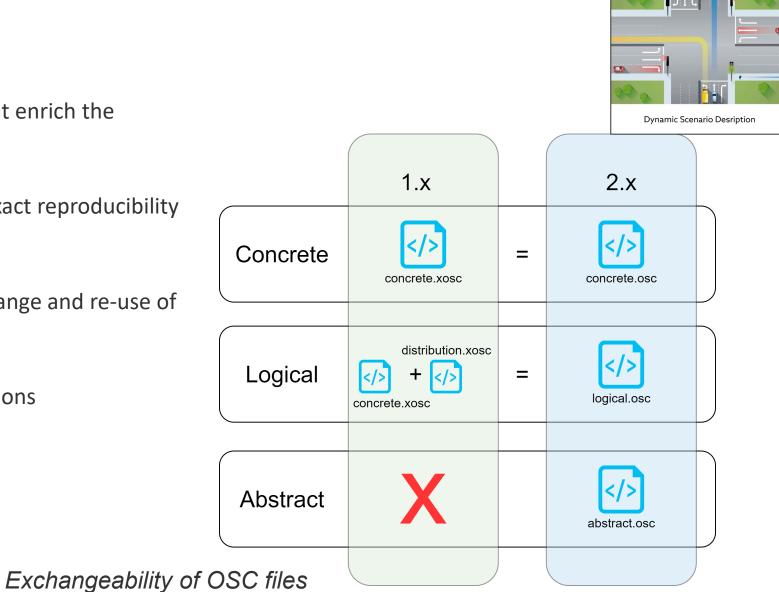
- Exchangeable scenario descriptions
- V1.2.0 released May 2022
 - Many clarifications in the specification
 - Support for virtual sensor recognition algorithm testing
 - Support for sensor error injection
- V2.0.0 released July 2022
 - Shift to a DSL together with a domain model
 - Support for abstract scenarios
- Followup project aiming to start in January 2023! Focus on migration first, new features second





Intro

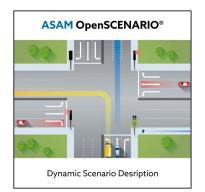
- OSC 2.x offers additional features that enrich the scenario description
- Neither version of OSC guarantees exact reproducibility across different tools
- The focus of OSC is on enabling exchange and re-use of scenario descriptions
- This does not change across the versions

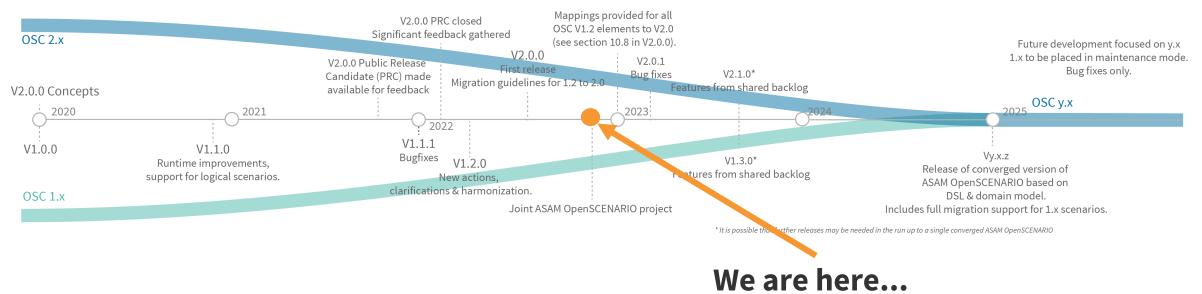




ASAM OpenSCENARIO®

Roadmap (07.2022)

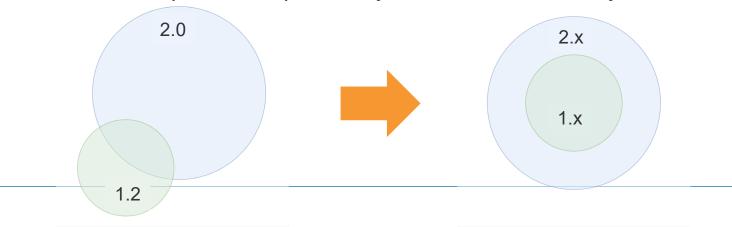


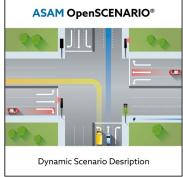




Convergence of versions

- ASAM will not stop supporting OSC 1.x or 2.x until it is clear that everything that needs to be covered in a converged version can be covered
- Assuming 2.x covers all use cases of 1.x and more, it does not make sense to develop two standards in parallel that do the same thing
- Overall goal is thus: converge to one version, based on 2.x
- One joint version ensures the most efficient allocation of member resources and least amount of confusion in the industry
- BUT: We need to ensure the requirements previously set are met! (and likely more...)





OpenSCENARIO

- Joint ASAM OpenSCENARIO 1.x and 2.x project
- Start 15.01.23 / End 02.10.23 (Goal: Pending TSC approval on 05.12.2023)

Goals

- 1. Migration
 - Improve and close gaps in the migration guidelines OSC 1.x \rightarrow 2.x
 - Ensure the same semantic meaning of a scenario in 2.x and 1.x
 - Approval for migration tooling pending TSC discussion
 - Decide on additional steps needed to reduce the migration/implementation hurdles
- 2. Bug fixes, clarifications & new features for both versions
 - Based on a shared backlog of features
- 3. Detail out the ongoing roadmap for OpenSCENARIO

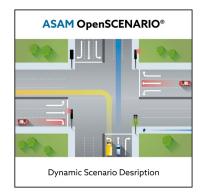




Some comments on migration

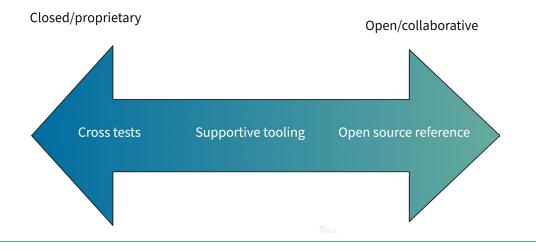
- Migration guide is non-normative & provides mapping for elements from OSC 1.0 to 2.0
- It is not complete. The current theory is that everything domain-related has at least one mapping, but there was not sufficient time to do this mapping in all cases for 2.0.
- Some elements already have unpublished concepts for how to map them (some do not)
- What about further elements from >1.0?
- Some exceptions are named where a mapping is not needed
- Minimum for this project: Aim to finish the guidelines to cover the most recent versions of OSC 1.x
 → Clear overview of mappings, open points and when these will be addressed (in order of prio.)
- Separate the migration document, make it a standalone document

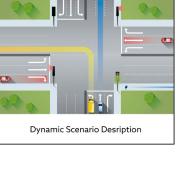




Some comments on migration - forward looking

- These are all currently 'just' guidelines. A great start, but what next?
- We think that more than guidelines is needed. → proposal pending to provide a migration tool
- What can be done to reduce the hurdle of migration?
- How about other alignment topics? Terminology? Domain model?





ASAM OpenSCENARIO®



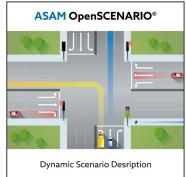
Some comments on migration

- Suggestions brought up in the proposal workshop:
 - Reference scenarios described in both versions with reference results. Automated pipeline to check submitted results against reference with series of tests.
 - Complete mapping of OSC1 elements available in OSC2 domain model could be made available by 51World → potential for significant time savings
 - Extending reference open source solutions with support for both versions (e.g. esmini)

These solutions are out of scope for the next project BUT what is in scope is figuring out what the members are interested in pursuing in future

• Last phase of migration work package will focus on these questions.



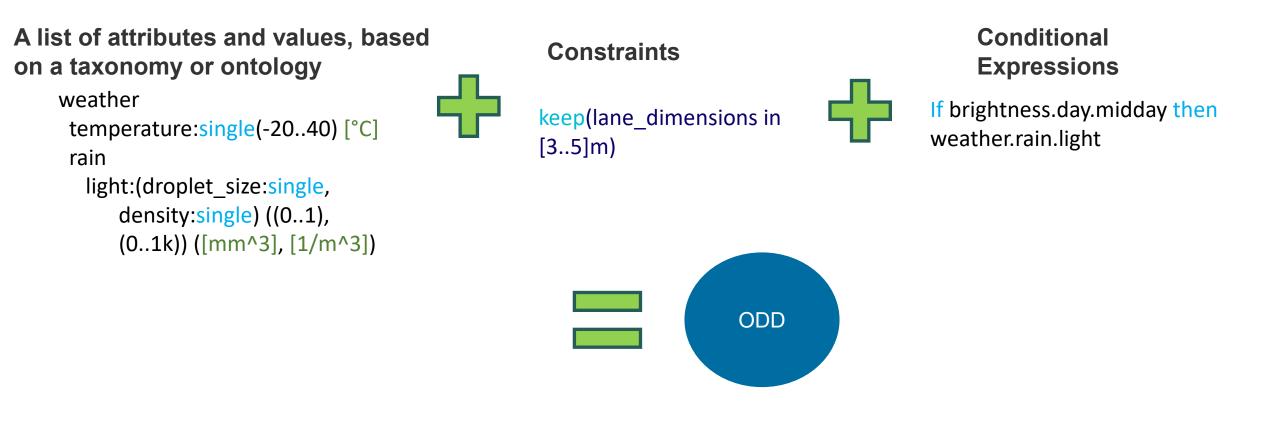


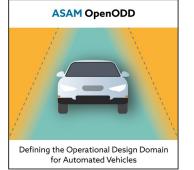




What is OpenODD?

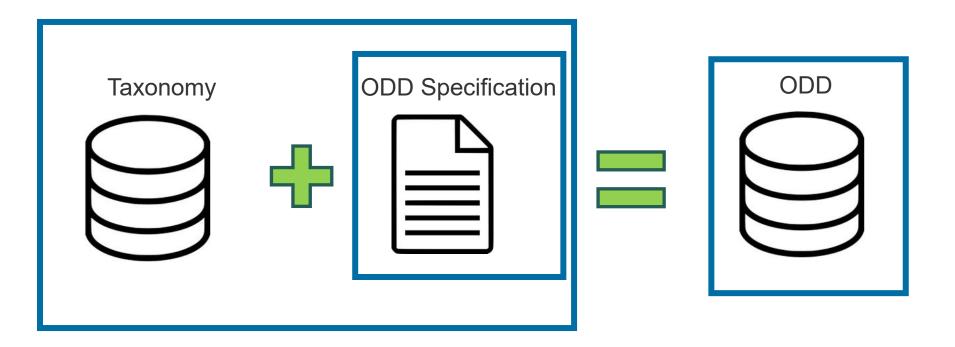
A machine and human readable format for representing a defined Operational Design Domain that is measurable and verifiable



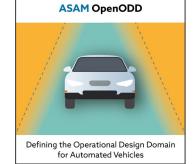


What is **OpenODD**

How do we exchange ODD specifications? Another way to look at it...









OpenX as a whole...

Name	Planned Version		, ,,	Status 🖵	▲ Nov-22	Dec-22	Jan-23	Feb-23	▲ Mar-23	Apr-23	▲ May-23	Jun-23	Jul-23	Aug-23	Sep-23	4 Oct-23	▲ Nov-23	Dec-23
OpenDRIVE	1.7.0;1.8.0	OpenX	Minor	Running														
OpenODD	1.0.0	OpenX	Major	Running														
OSI	3.6.0;4.0.0	OpenX	Major	Running														
OpenSCENARIO	2.0.1;1.3;2.1.0	OpenX	Minor	Enrollments open														
Testing Study Group		OpenX		Enrollments open														
Study project Off-road Applications of OpenX		OpenX		Planned														
OpenLabel FVD		OpenX		Planned														
OpenDRIVE + CityGML Concept	-	OpenX	Concept	Proposal Phase														

New releases this year:

- OpenSCENARIO 1.2.0
- OpenSCENARIO 2.0.0
- OSI 3.5.0

Some highlights:

- Pilot activity for harmonization \rightarrow description of dynamic traffic signals
- Next OSI project kicked off in September
- Application of OpenX for Off-road Workshop in Feb. 2023
- CAV Testing Expert group starting in Jan. 2023



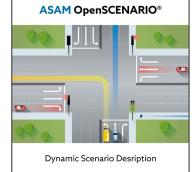
Thank you for your attention!

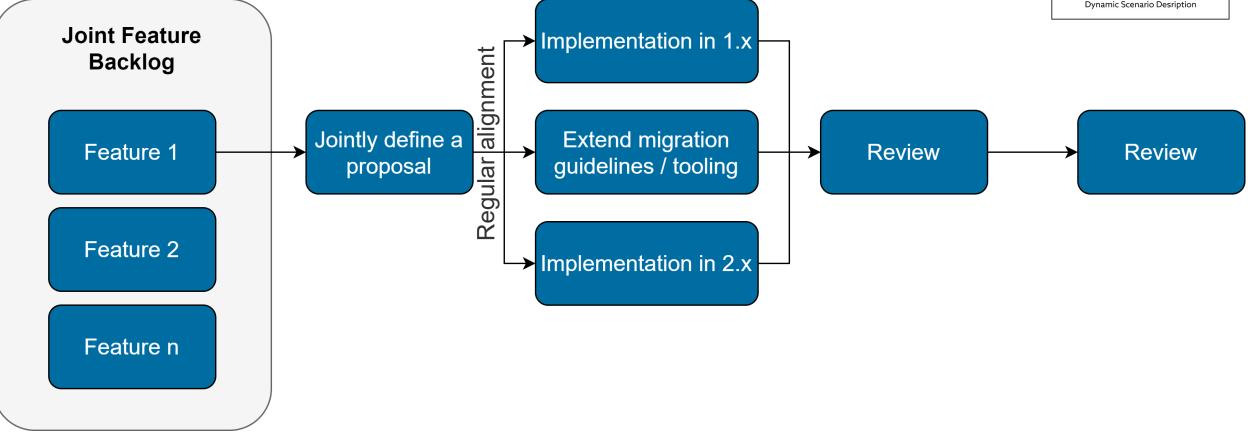
Ben Engel Mail: <u>benjamin.engel@asam.net</u>





Process guidelines for OSC Feature Development



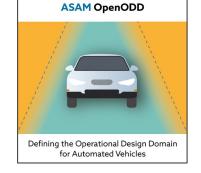


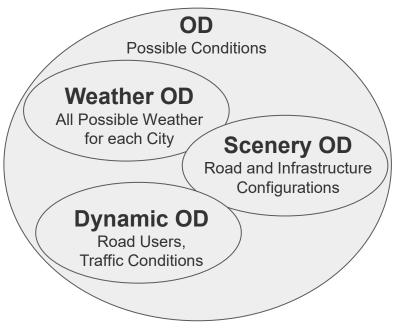


Operational Domain (OD) What is it?

What circumstances is the ADS expected to experience?

- Weather: Temperature, Rain, Snow, Visibility, etc.
- Scenery: Roads, Intersections, Infrastructure
- Traffic: Vehicles, VRUs, etc
- Which combinations are expected?



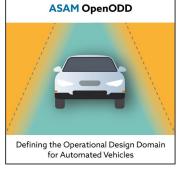


Operational Domain (OD) What is it?

What circumstances is the ADS expected to experience?

- Weather: Temperature, Rain, Snow, Visibility, etc.
- Scenery: Roads, Intersections, Infrastructure
- Traffic: Vehicles, VRUs, etc • Which combinations are expected? Weather OD

Which subset admits **safe operation**?



OD **Possible Conditions**

Scenery OD

Safe

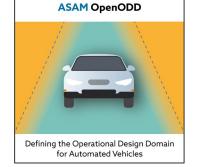
Safe

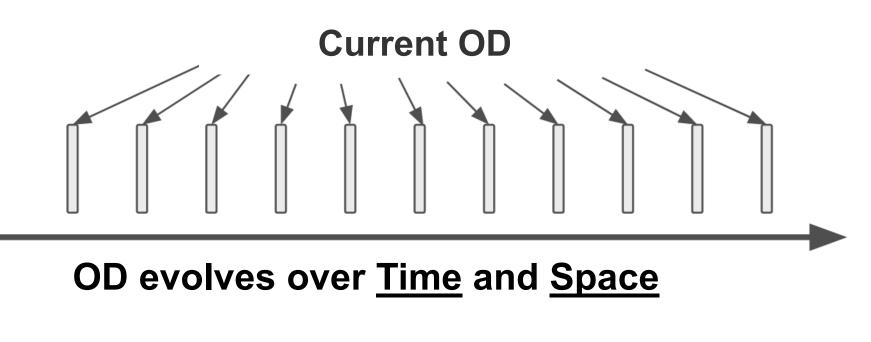
Dynamic OD

Safe

Operational Domain (OD) and Current Operational Domain (COD)

The data replay / recorded data approach





$$OD = COD_{t_0} + COD_{t_1} \dots + COD_{t_n}$$

