ASAM OpenODD Concept Project

Introduction and Structure of ASAM OpenODD

Dr Siddartha Khastgir

Head of Verification & Validation, Intelligent Vehicles WMG, University of Warwick, UK

Nicco Hagedorn

Global Technology Manager ASAM e.V.

11 November 2021 Webinar, Online





Agenda

1	About OpenODD: scope and objectives
2	ASAM OpenODD structure
3	Deliverables



ASAM OpenODD Scope and Objectives

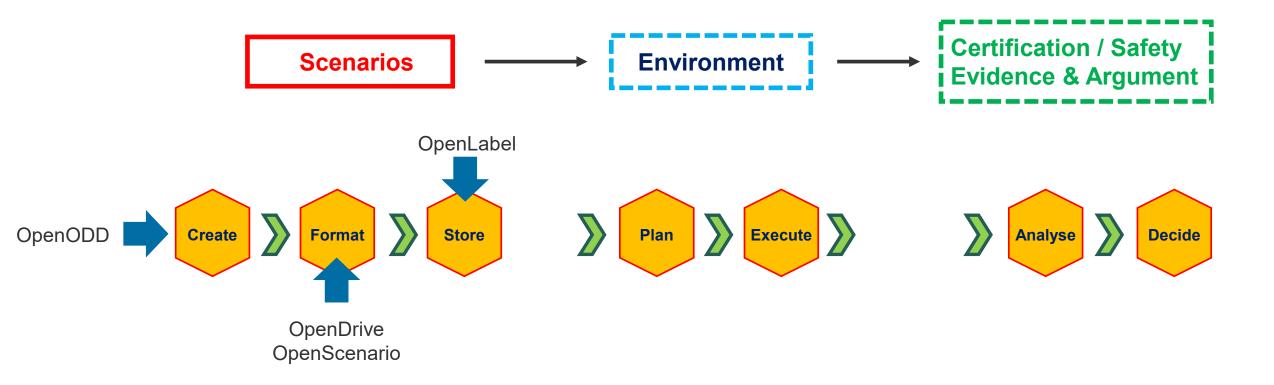
ASAM OpenODD: Scope and Objectives

The aim is to provide a format that is capable of representing a defined Operational Design Domain for connected automated vehicles (CAV) for *simulation based testing*.



ASAM OpenODD: Scope and Objectives

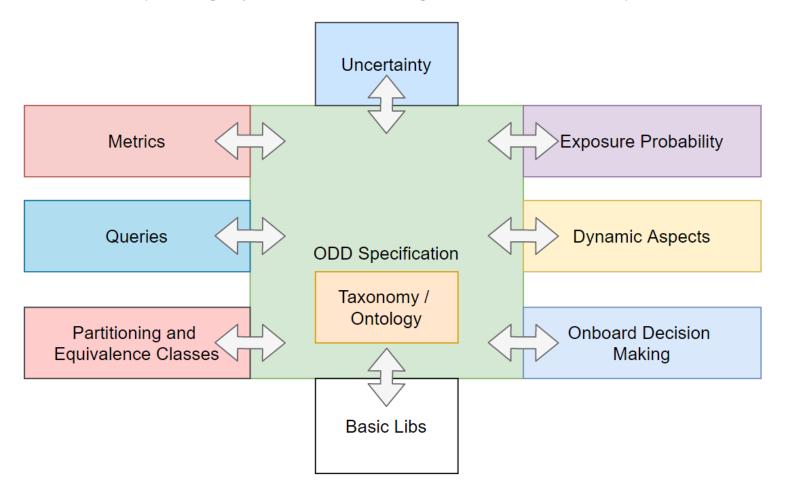
The aim is to provide a format that is capable of representing a defined Operational Design Domain for connected automated vehicles (CAV) for *simulation based testing*.





ASAM OpenODD: Scope and Objectives

ASAM OpenODD Language (including aspects accessible through extension mechanisms)





ASAM OpenODD work packages

- Four work packages
- Work Package 1: Attributes:
 - Ensure alignment with BSI PAS 1883, ISO 34503, and the ongoing ASAM OpenXOntology Project
- Work Package 2: Specification/format
 - Describe the semantic and syntactic description of the ODD description for format for simulation execution
- Work Package 3: Metrics / Measurement
 - Define and describes Metrics associated with ODD
- Work Package 4: Uncertainty
 - Define and describes uncertainty attributes associated with ODD



ASAM OpenODD: workflow

 User stories Step Requirements list Step 2 • Use case / examples Step 2 • Illustrate requirements and use cases in example syntaxes Step 3 • Illustrate open issues Step 4 Concept paper Step 5



ASAM OpenODD: Requirement & Syntax illustration

REQUIREMENT: Human and machine readability

Example Use case:

An example ODD states that motorway is only suitable when there is no rain, up slope is not suitable as the vertical geometry.

Syntax 1

```
keep(road_type == motorway => odd_5.weather.rain == none)
keep(geometry.vertical != up_slope)
```

Syntax 2

SUITABLE Motorway EXCEPT WHEN Rain UNSUITABLE Up slope

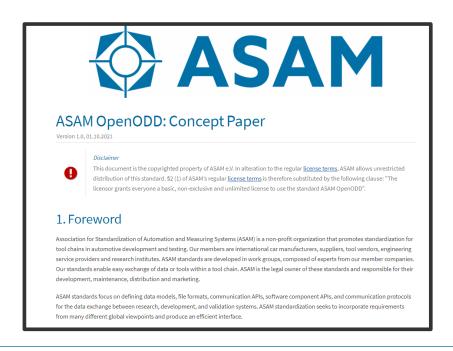


Deliverables OpenODD Concept project.

What Is Being Released

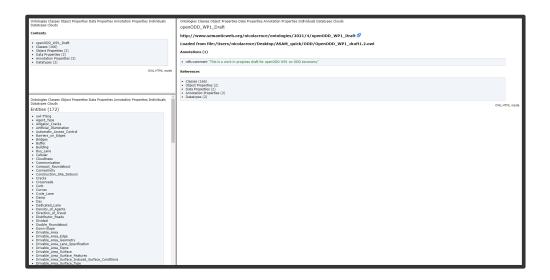
Concept Paper

- Documentation
- Illustration in 2 example syntaxes



Ontology Web App

Online portal with detailed ODD attributes and their ontological relationships





ASAM OpenODD Concept paper structure

Structure



ASAM OpenODD: Concept Paper

Version 1.0, 01.10.2021

Disclaime



This document is the copyrighted property of ASAM e.V. In alteration to the regular <u>license terms</u>, ASAM allows unrestricted distribution of this standard. \$2 (1) of ASAM's regular <u>license terms</u> is therefore substituted by the following clause: "The licensor grants everyone a basic, non-exclusive and unlimited license to use the standard ASAM OpenODD".

1. Foreword

Association for Standardization of Automation and Measuring Systems (ASAM) is a non-profit organization that promotes standardization for tool chains in automotive development and testing. Our members are international car manufacturers, suppliers, tool vendors, engineering service providers and research institutes. ASAM standards are developed in work groups, composed of experts from our member companies. Our standards enable easy exchange of data or tools within a tool chain. ASAM is the legal owner of these standards and responsible for their development, maintenance, distribution and marketing.

ASAM standards focus on defining data models, file formats, communication APIs, software component APIs, and communication protocols for the data exchange between research, development, and validation systems. ASAM standardization seeks to incorporate requirements from many different global viewpoints and produce an efficient interface.

Concept Paper



Structure



Concept Paper

ASAM Ope

Version 1.0, 01.10.2021



This docu distribution

1. Foreword

Association for Standard tool chains in automotive service providers and res Our standards enable eadevelopment, maintenar

ASAM standards focus on for the data exchange bet from many different globa

2. Introduction

2.1. Overview

Safety is fundamental to the development of public trust and acceptance of Connected and Autonomous Vehicles (CAVs) and their on board Automated Driving Systems (ADSs) and to enable deployment of automated driving. Safety of CAVs has two aspects: safe design and safe use of the system. In order to ensure safe use of the system, it is important to convey the knowledge of the true capabilities and limitations of the ADSs to the users to prevent misuse of the systems.

In order to establish the true capabilities and limitations of an Automated Driving Systems (ADSs), we need to first define their Operational Design Domain. An ODD refers to the operating environment (road type, weather conditions, traffic conditions) in which a vehicle can drive safely. For example, for Low-Speed Automated Driving (LSAD) systems such as pods and shuttles, the ODD may include urban areas with predefined routes that include pedestrians and cyclists. On the other hand, for a motorway chauffeur system, an ODD may include a four-lane divided motorway and dry conditions only. The types of scenarios a vehicle may encounter will be a function of its defined ODD, making this fundamental to any safety evaluation and scenario identification.

- A more formal definition of ODD as defined by SAE J3016 (2018) states that "Operating conditions under which a given driving automation system or feature thereof is specifically designed to function, including, but not limited to, environmental, geographical, and time-of-day restrictions, and/or the requisite presence or absence of certain traffic or roadway characteristics".

In order to enable stakeholders to share, compare and re-use ODD definitions, there is a need for standards to provide guidance to the stakeholders on both the attributes to be used for ODD definition and a format for defining the ODD using those attributes. BSI PAS 1883 (UK) provides a taxonomy for ODD. Additionally, ISO 34503 uses the taxonomy to provide a high-level definition format for ODD. While these standardization activities address the important needs of the industry, a gap still exists in the industry for an ODD definition format for simulation.

ASAM OpenODD is a representation of the abstract ODD specification in a more well-defined syntax and semantics which enables machines to interpret and perform the required analysis. Additionally, the ASAM OpenODD specification shall be measurable and verifiable for the attributes it specifies.

2. Introduction

- 2.1. Overview
- 2.2. Normative and non-normative statements and deliverables
- 2.3. Conventions
- 2.4. Understanding ODDs
- 2.5. Use cases for ASAM OpenODD



Structure



Concept Paper

ASAM Ope

Version 1.0, 01.10.2021



This doc distribution

1. Foreword

Association for Standard Our standards enable ea development, mainten

ASAM standards focus or for the data exchange be from many different globa

2. Introduction

2.1. Overview

Safety is fundamental to Automated Driving Syst of the system. In order to ADSs to the users to prev

In order to establish the Design Domain. An ODD safely. For example, for predefined routes that in lane divided motorway a this fundamental to any s

- A more formal definition system or feature thereo restrictions, and/or the re

In order to enable stakeh stakeholders on both the provides a taxonomy for standardization activities simulation.

ASAM OpenODD is a repr to interpret and perforn attributes it specifies.

2.4. Understanding ODDs

2.4.1. What is a ODD Specification?

An ODD defines the operating conditions an ADS is designed to operate in. This includes all ranges of roads, environmental conditions, part of the dynamic elements (mainly the ego designated speed) and types of traffic participants within a macroscopic traffic during all allowed weather conditions and time-of-day restrictions. The ODD will specify the domain and its borders the ADS is designed to safely operate in or needs to be capable of handling. This opens up a multidimensional space that needs to be specified.

According to SAE J3016 an ODD is defined as follows:

SAF J3016 (2021)

Operating conditions under which a given driving automation system or feature thereof is specifically designed to function, including, but not limited to, environmental, geographical, and time-of-day restrictions, and/or the requisite presence or absence of certain traffic or roadway characteristics.

2.4.2. Operational Domain (OD) vs. Operational Design Domain (ODD)

A specific type of terminology misuse in practice is failing to distinguish between the real world and the ODD.

- . "ODD" refers to the intended ADS capability to handle operating conditions, and not the real world.
- . "Operational Domain (OD)" refers to what the world actually is, which might (in most cases will) differ from the ODD.

Thus, when the real world (OD) is outside the intended operational design environment (ODD), the vehicle has exited the ODD and is no longer in an environment it was designed to operate within. The difference between OD and ODD highlights the limitations of the ADS. Additionally, an automated driving system feature can have only one ODD. However, a vehicle can have multiple automated driving system features. Thus it is incorrect to say, for example, that a Level 4 highway feature has "multiple ODDs of day and night with fair weather" when what should be said is that the feature has "an ODD that includes both day and night in fair weather."

In all practical cases, an ODD definition will not be exhaustive enough to cover all attributes or occurrences in an OD. Therefore, it is essential to be able to define an ODD which is not only objective but which defines clear boundaries to enable ADSs to perform fallback manoeuvres to ensure safe operation

2. Introduction

- 2.1. Overview
- 2.2. Normative and non-normative statements and deliverables
- 2.3. Conventions
- 2.4. Understanding ODDs
- 2.5. Use cases for ASAM OpenODD



Structure



Concept Paper

ASAM Ope

Version 1.0, 01.10.2021



This doc distribution

1. Foreword

Association for Standard Our standards enable ea development, maintena

ASAM standards focus or for the data exchange bet from many different globa

2. Introduction

2.1. Overview

Safety is fundamental to Automated Driving Syst of the system. In order to ADSs to the users to prev

In order to establish the Design Domain. An ODD safely. For example, for I predefined routes that in lane divided motorway a this fundamental to any s

- A more formal definition system or feature thereo restrictions, and/or the re

In order to enable stakeh stakeholders on both the provides a taxonomy for standardization activities simulation.

ASAM OpenODD is a repr to interpret and perform attributes it specifies.

2.4. Understanding ODDs

2.4.1. What is a ODD Specification?

An ODD defines the operating conditions the dynamic elements (mainly the ego de weather conditions and time-of-day restr needs to be capable of handling. This op

According to SAE J3016 an ODD is define

SAE J3016 (2021)

Operating conditions under whi designed to function, including restrictions, and/or the requis

2.4.2. Operational Domain (OI

A specific type of terminology misuse in p

- · "ODD" refers to the intended ADS cap
- "Operational Domain (OD)" refers to v

Thus, when the real world (OD) is outside longer in an environment it was designed Additionally, an automated driving syste features. Thus it is incorrect to say, for ex what should be said is that the feature h

In all practical cases, an ODD definition w to be able to define an ODD which is not ensure safe operation

2.4.3. Difference between ODD and Scenario

It is important to highlight that while ODDs and scenarios are related, they are not the same. As mentioned earlier, an ODD essentially defines the operating environment for which a system is designed. It may also be seen from the perspective of the end-user (e.g. city council authority) as the operating environment in which a system should be able to operate safely. It is essential that there is an overlap between the two perspectives of the ODD, manufacturer (or the system designer) and the end-user for ensuring the safe deployment of CAVs.

A scenario defines the behavior of various actors and entities in an ODD. Below the difference between scenario and ODD is highlighted graphically. [fig-simple-odr-odd] depicts a part of an ODD with single lane non-divided road which has passenger cars. Simple scenario with $\underline{\textit{passenger cars}} \ depicts \ a \ scenario \ which \ illustrates \ the \ behavior \ of \ the \ vehicles \ in \ the \ ODD \ of \ [\underline{\textit{fig-simple-odr-odd}}]. \ In \ summary, \ once \ the$ behavior of the actors is defined in a part of an ODD, it becomes a scenario. This has no influence on the fact that a scenario is a stand alone entity regardless of the ODD definition and therefore can be defined independently

There are 4 vehicles, VehicleA , VehicleB , VehicleC and VehicleA and VehicleB are in Road3 , VehicleC is in Road2 , and VehicleD is in Road1 . When VehicleD is driving , VehicleC drives , with constant

And then VehicleC turns righ t, with constant speed , across VehicleD at its front .

speed , towards Vehicle D at its front left .

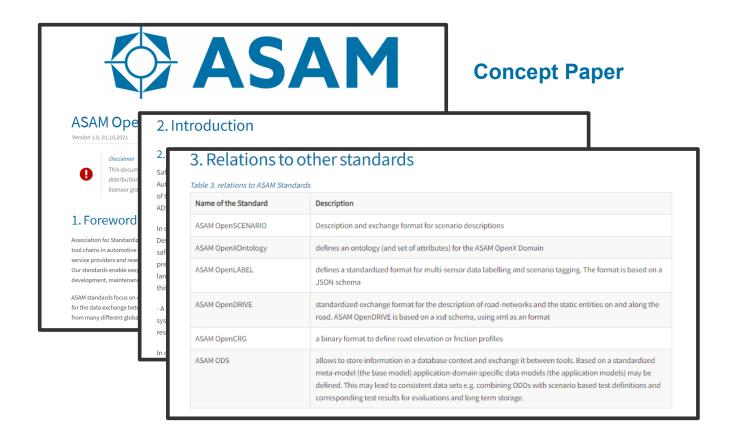
Then VehicleC drives , with constant speed , away from VehicleD at its right



2. Introduction

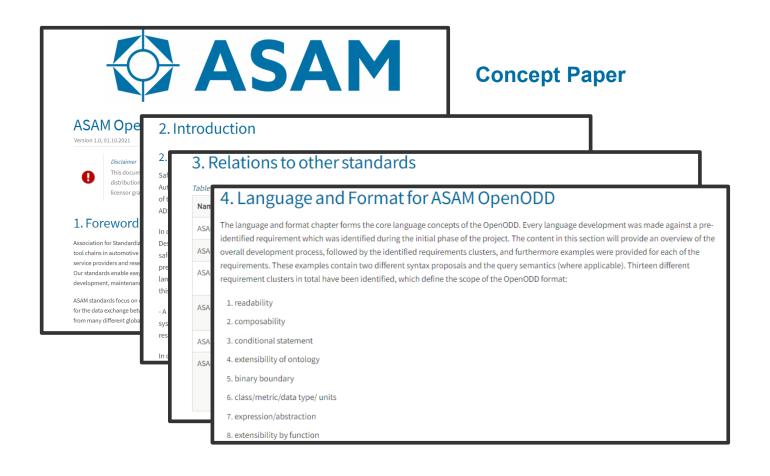
- 2.1. Overview
- 2.2. Normative and non-normative statements and deliverables
- 2.3. Conventions
- 2.4. Understanding ODDs
- 2.5. Use cases for ASAM OpenODD





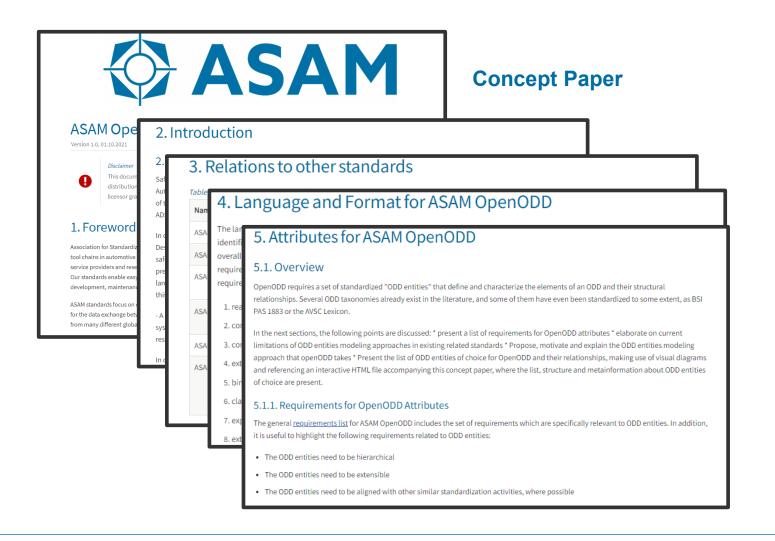
- 3. Relations to other standards
 - 3.1. Positioning of ASAM OpenODD within ASAM activities
 - 3.2. References to other standards





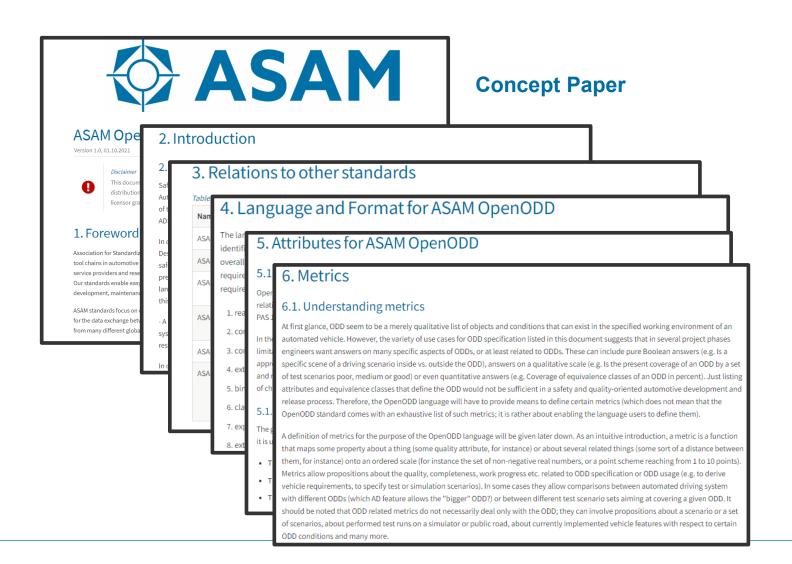
- Language and Format for ASAM OpenODD
 - 4.1. Example syntax representation
 - 4.2. Overview
 - 4.3. Requirements for ASAM OpenODD
 - 4.4. Concepts for the language and format of ASAM OpenODD
 - 4.5. Extensibility
 - 4.6. Integration with Scenario-based Testing Workflow





- 5. Attributes for ASAM OpenODD
 - 5.1. Overview
 - 5.2. Requirements for the attributes of ASAM OpenODD
 - 5.3. Attributes for ASAM OpenODD

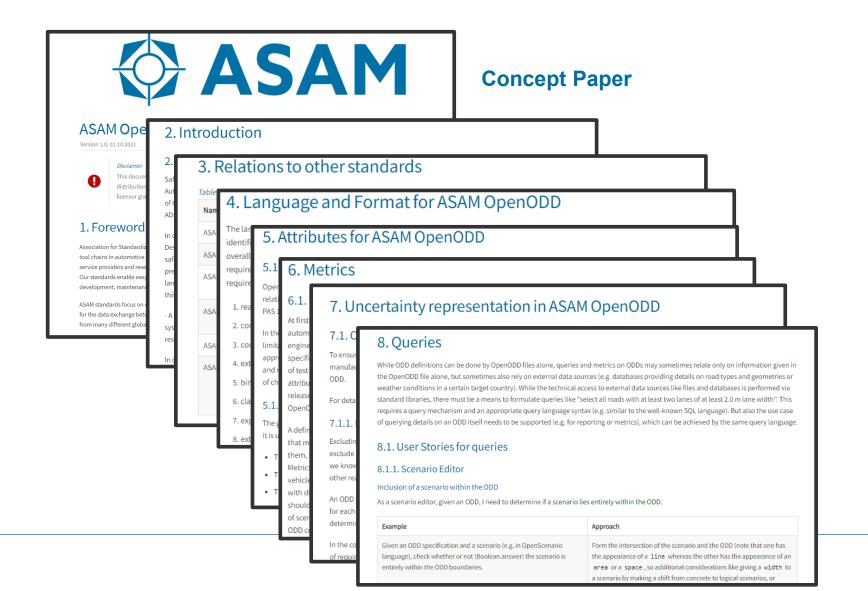
Structure



6. Metrics

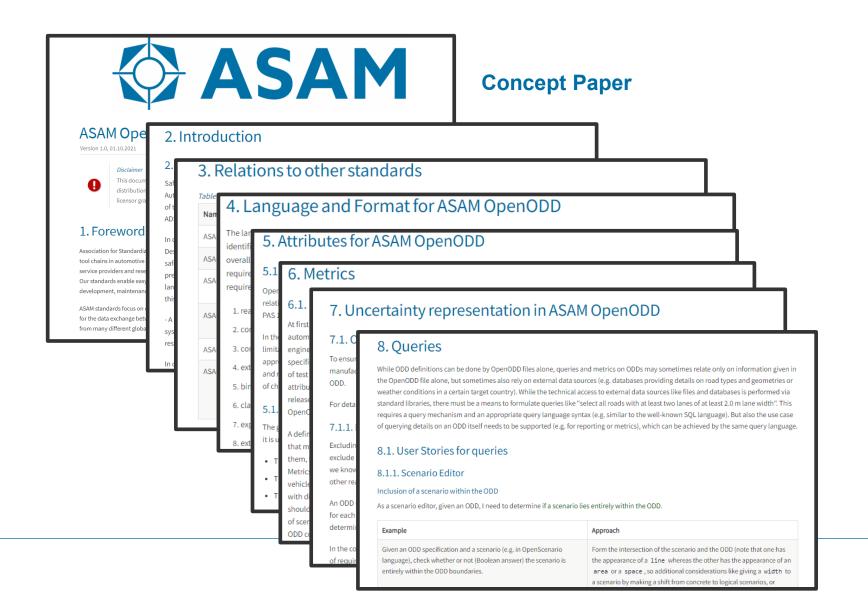
- 6.1. Understanding metrics
- 6.2. Overview
- 6.3. User stories for metrics of ASAM OpenODD
- 6.4. Concepts





- Uncertainty representation in ASAM OpenODD
 - 7.1. Overview
 - Requirements for the uncertainty representation of ASAM OpenODD
 - 7.3. Concepts





- 9. Partitioning and equivalence classes
- Exposure and probability
- 11. Dynamic aspects
- 12. Onboard decision making
- 13. Annex to ASAM OpenODD



Thank you for your attention!

Dr Siddartha Khastgir
Head of Verification & Validation, Intelligent Vehicles,
WMG, University of Warwick, UK
ASAM OpenODD Concept Project Lead

Phone: +44 7881 267502

Email: S.Khastgir.1@warwick.ac.uk

Nicco Hagedorn Global Technology Manager, ASAM e.V.

Email: nicco.hagedorn@asam.net



