



Technische Hochschule  
Ingolstadt

CARISSMA Institute of Automated Driving

# Design of a Mixed Reality Test Environment to Validate Autonomous Vehicles

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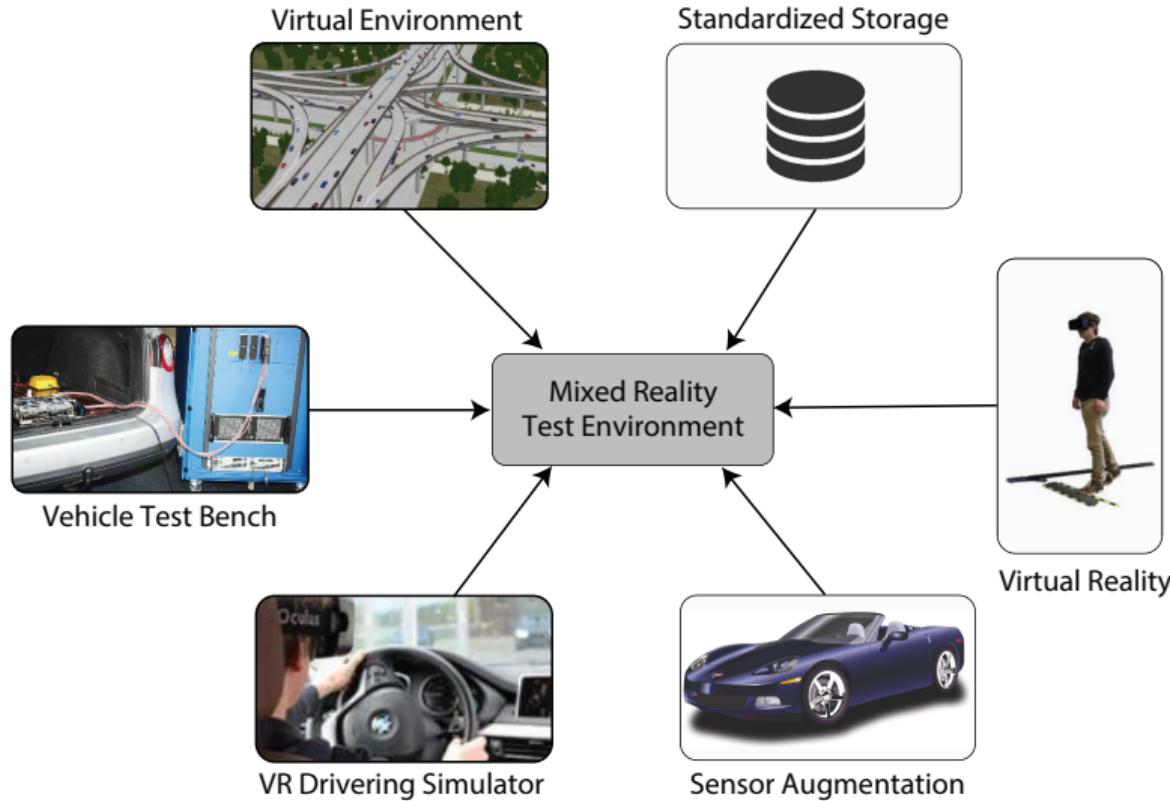
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# Motivation



# Objective



- Extension of classic XIL test setups
- Seamless transition between virtual and real parts
- Physical separation of individual participants
- Standardized interfaces
- Simple connection of individual parts



- Design of a system architecture
  - Run time exchange of moving objects and traffic lights
  - Static environment only at startup
- Identification and evaluation of exchange formats
- Possibilities for connecting components such as
  - Simulation Systems
  - Experimental Vehicles
  - HiL-Systems
  - Prototype Models



## Open Simulation Interface

- ASAM OSI standard (according to PEGASUS)
- automotive context
- programming language independent through IDL compiler

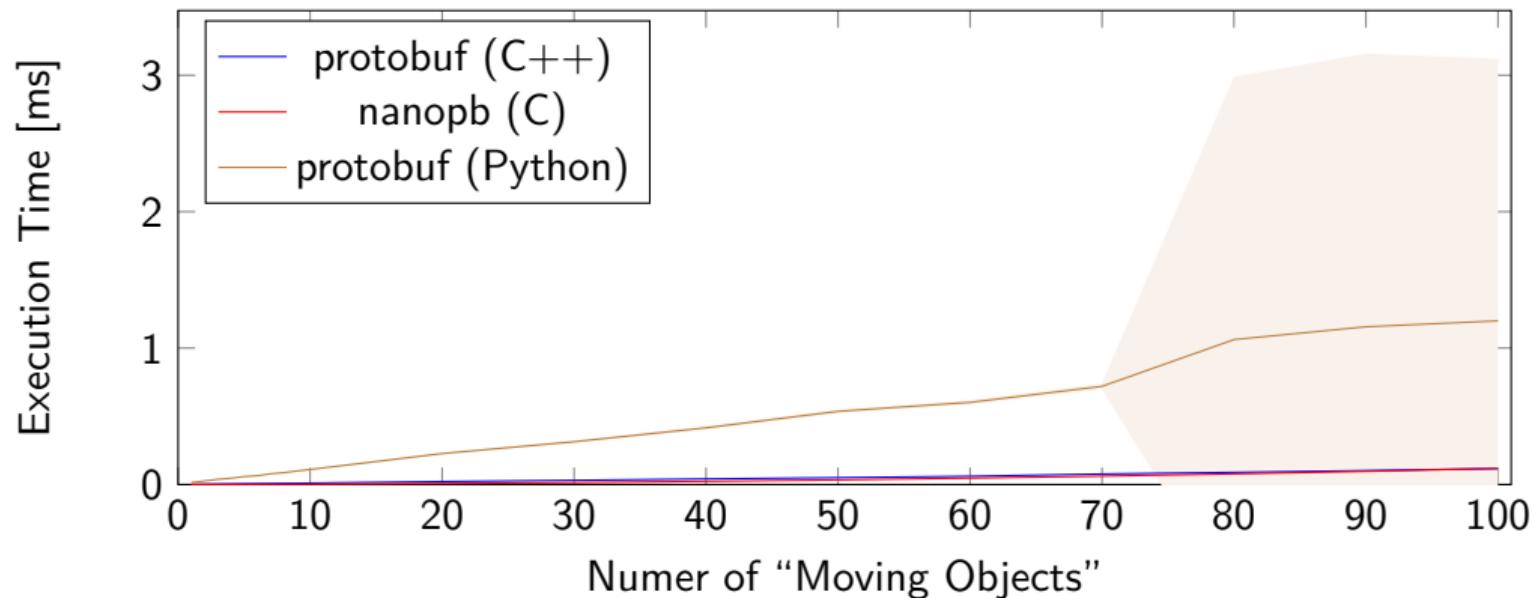
## Selection of the protobuf implementations

- main components in compilable language
- prototype also in interpretable language
- Official implementation of Google (C++ and Python)
- Lightweight third party implementation (nanopb in C)

# Performance Measurement of Different Libraries



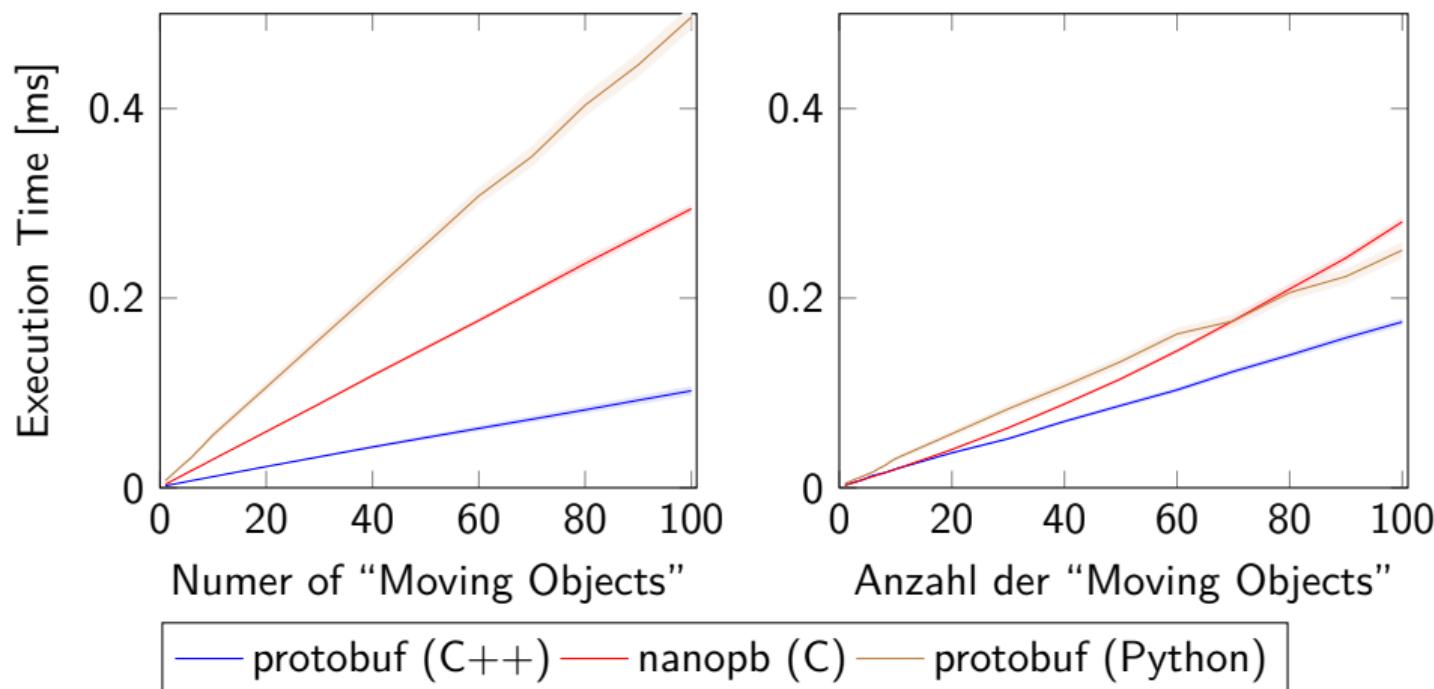
## Creation of OSI protobuf Structures



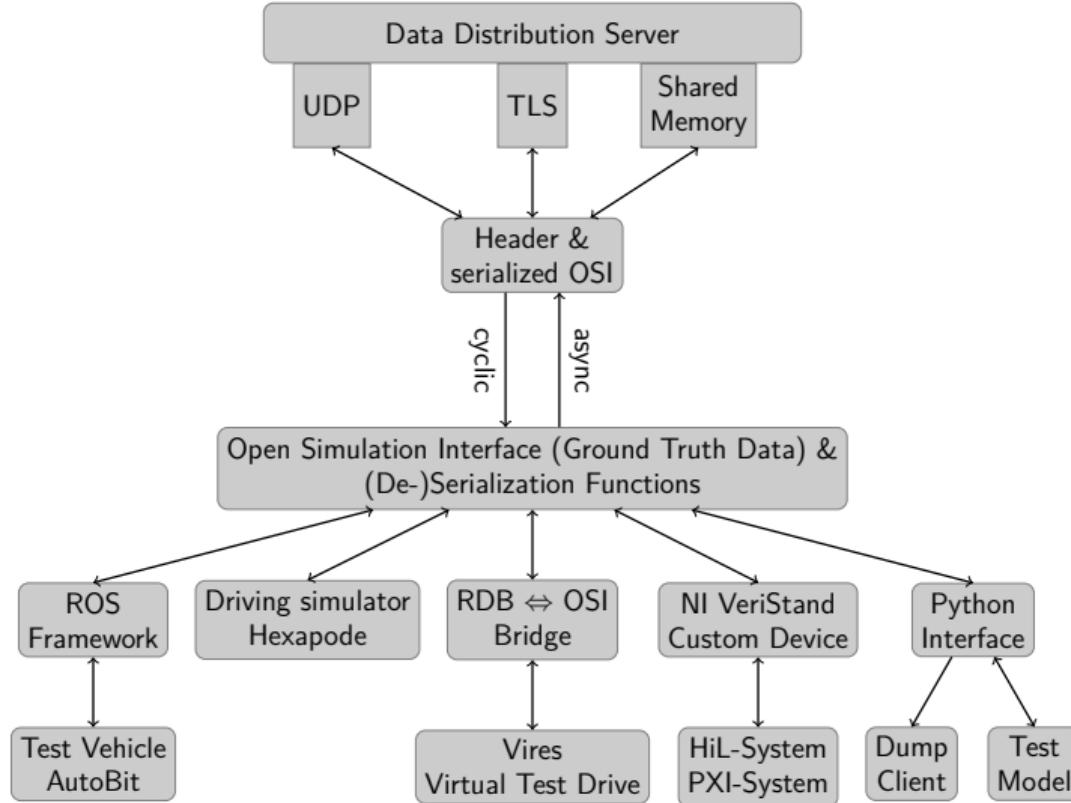
# Performance Measurement of different Libraries



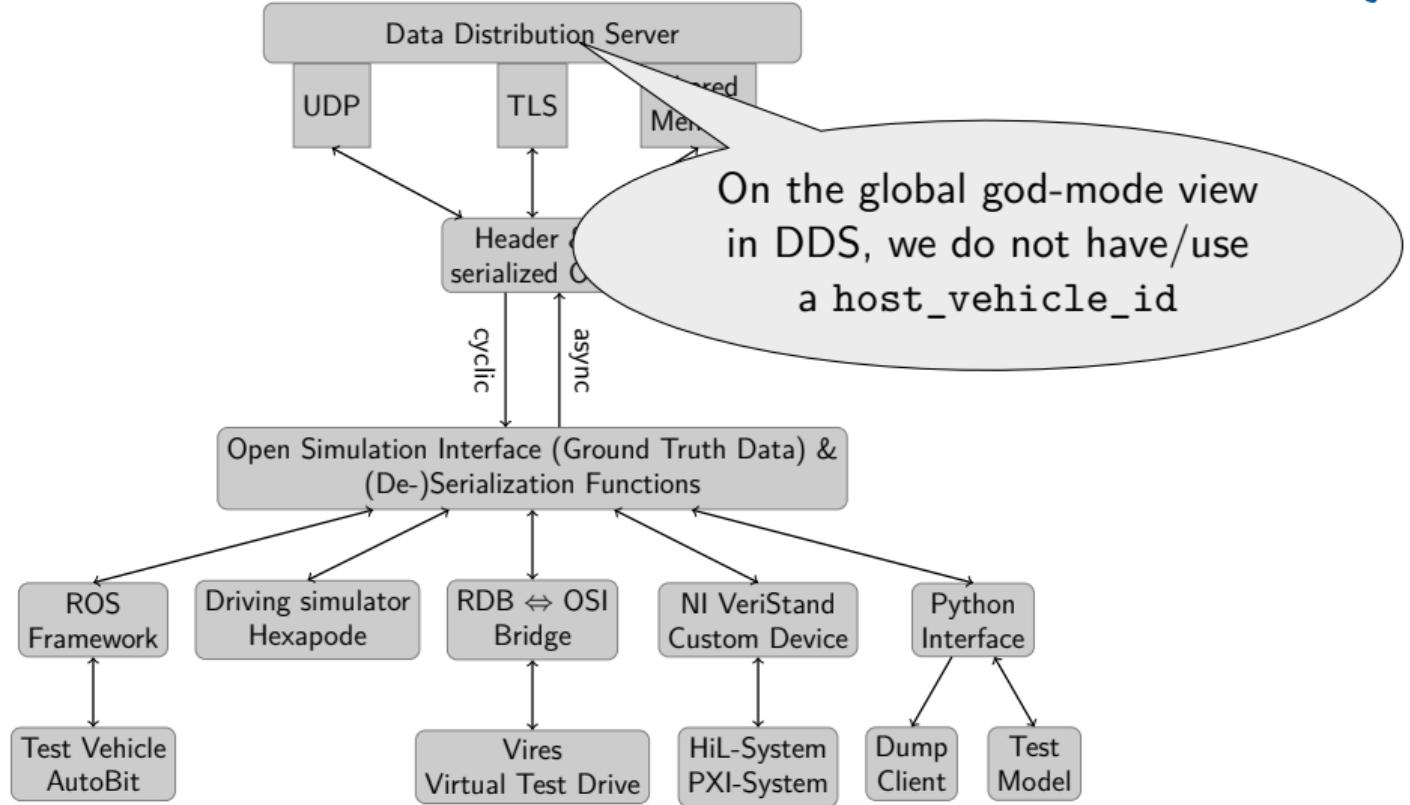
## Serialisation and deserialisation of OSI protobuf Structures



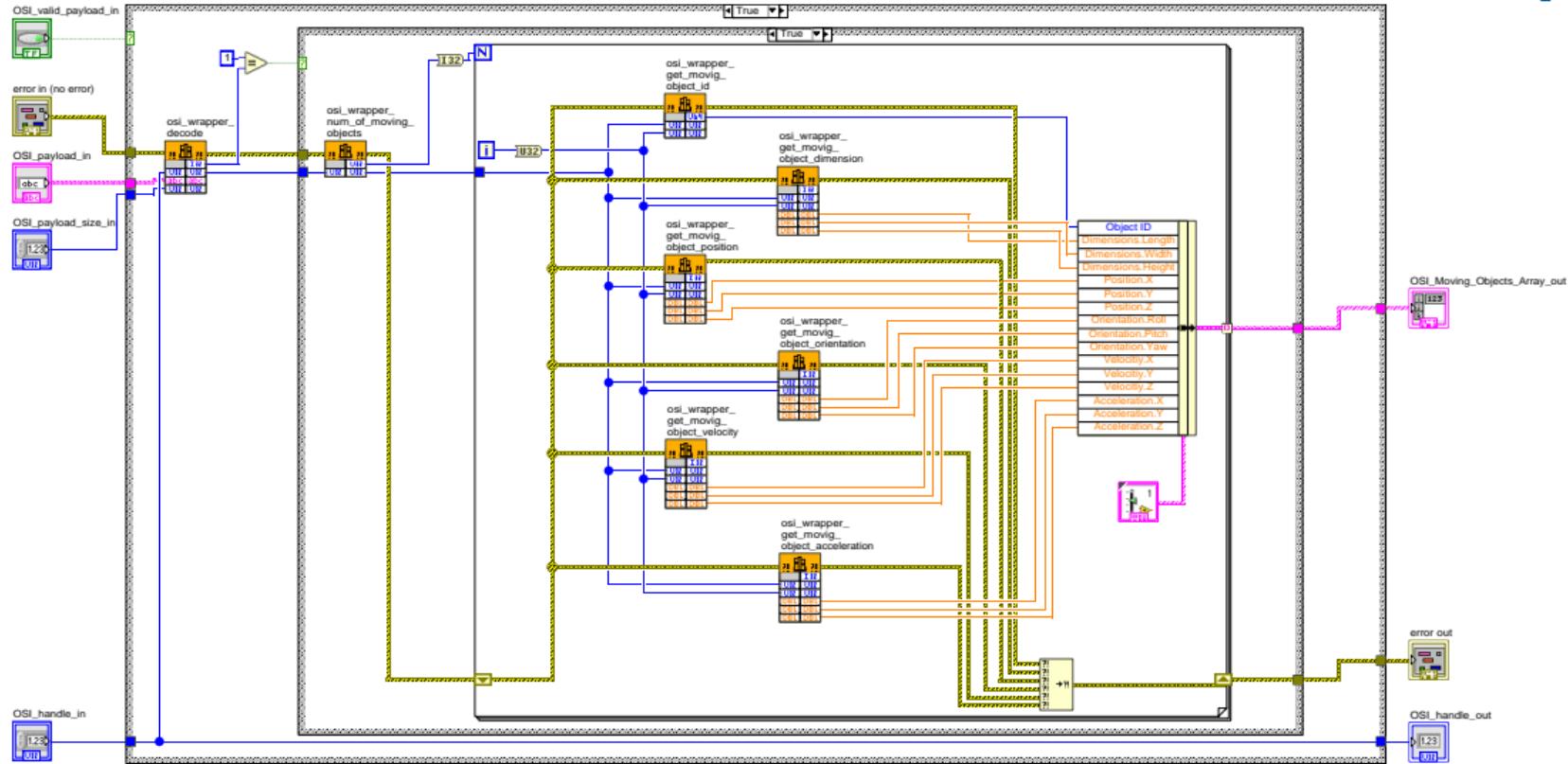
# System Design



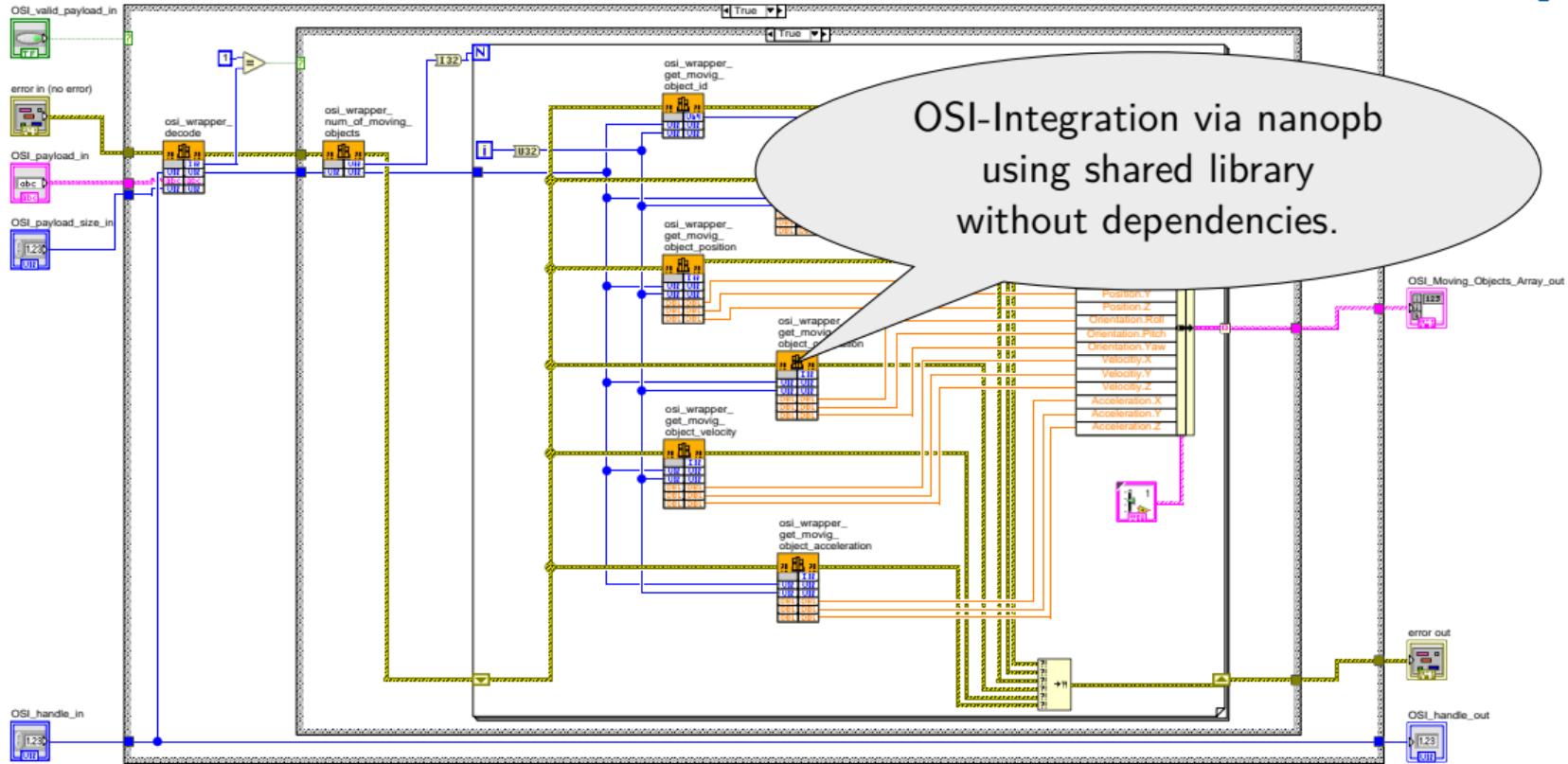
# System Design



# HiL-Integration in NI LabView and Phar Lap ETS



# HiL-Integration in NI LabView and Phar Lap ETS



# Conclusion



- protobuf and OSI for soft real time for < 100 objects usable
- Exchange of moving objects and traffic lights using
  - Data Distribution Server (DDS)
  - HiL system,
  - main simulation,
  - simple vehicle model
- based on Open Simulation Interface (OSI) possible
- Possibilities to integrate additional test components



- Integration of
  - test vehicles with sensor augmentation,
  - test persons
  - etc.
- Comparison of physical test drives and mixed reality tests



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## Initial Publication:

Aufbau einer Mixed-Reality-Versuchsumgebung zur Absicherung autonomer Systeme  
Echtzeit 2019 – “Autonome Systeme – 50 Jahre PEARL”  
[https://doi.org/10.1007/978-3-658-27808-3\\_5](https://doi.org/10.1007/978-3-658-27808-3_5)