

# MUSICC's Metadata: Enabling Scenario Searches by Story or ODD

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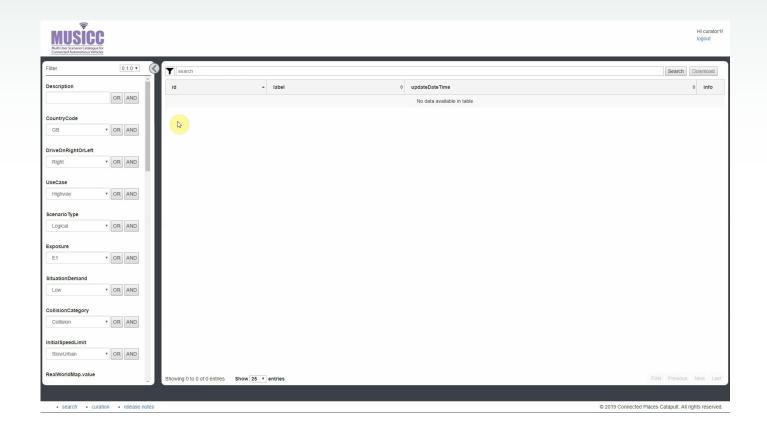
## **MUSCC relevance**



MUSICC is a live scenario database, aimed at regulator use. We've addressed:

- Storing OpenSCENARIO and OpenDRIVE files in a DB
- Metadata for searching scenarios
- An API for tool integrations
- Randomising parameters within scenarios

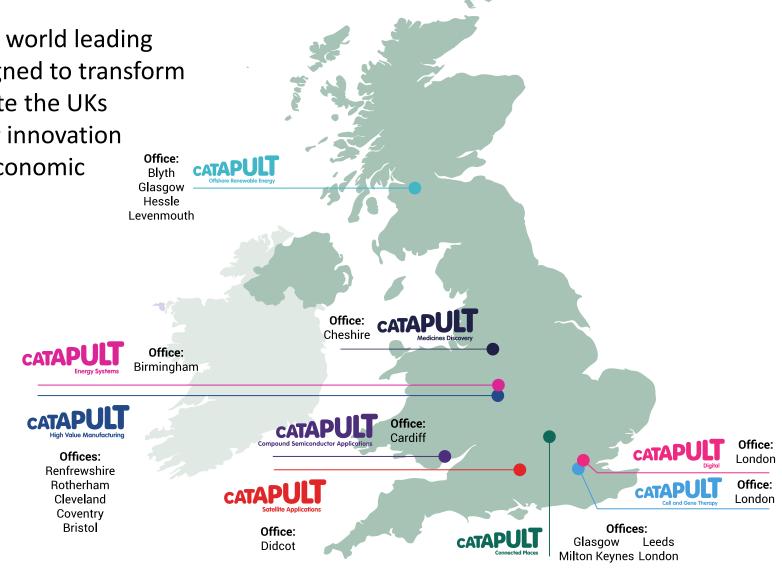
We fully support standardisation in this area.





### **Catapults – a force for innovation and growth**

A network of world leading centres designed to transform and accelerate the UKs capability for innovation and future economic growth.

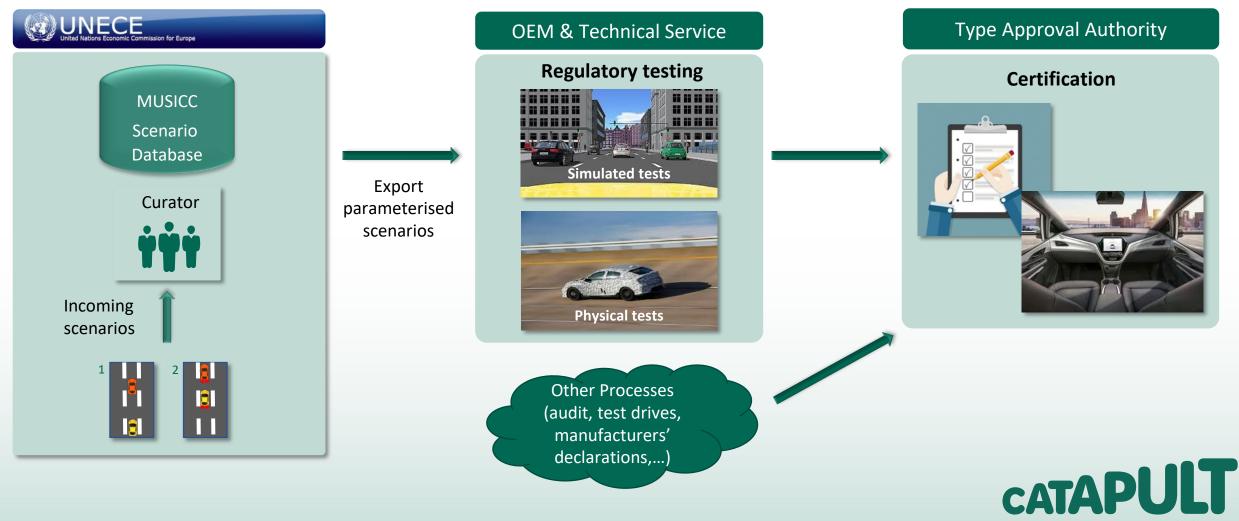




9 **Innovation Centres** across the UK

### **Vision: The scenario-based certification process**

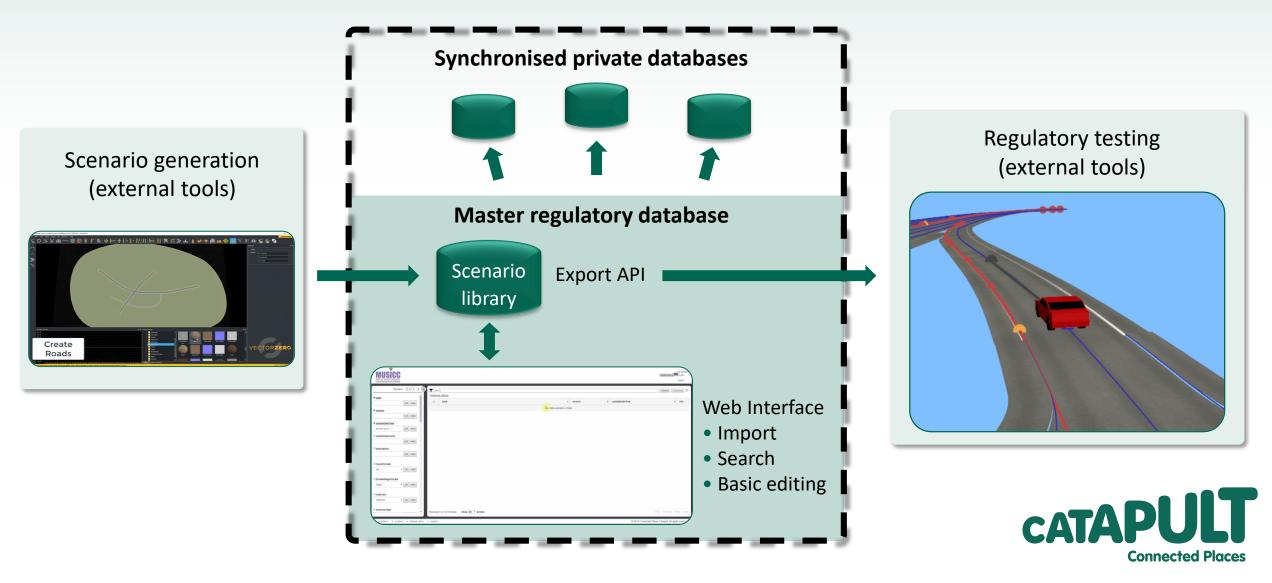




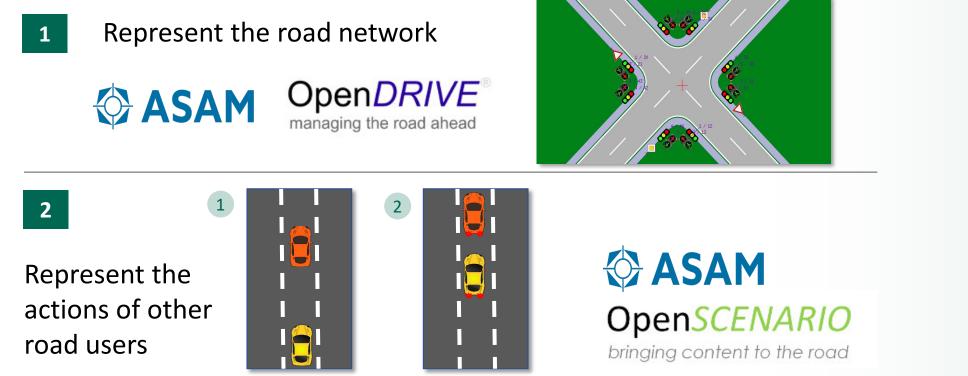
**Connected Places** 

### **MUSICC scope and context**





## **MUSICC's scenario description language**





The SDL is a key part of MUSICC's deliverables.

- Stakeholders will be more willing to engage given a standardised format
- CPC is an active member of ASAM OpenSCENARIO standardization groups

3 Additions (the MUSICC record)

### Metadata

- Search for scenarios corresponding to the ODD of the ADS under test

### **Parameter stochastics**

- Variables in the scenario can take randomly generated values



## **Quick notes: API and parameter stochastics**

### MUSICC Multi User Scenario Catalogue for Connected Autonomous Vehicles

### **API for tool integration**

- Simple HTTP GET requests, with responses encoded in JSON if applicable
- Currently working on automating fetch and execution of scenarios from CARLA

### **Parameter stochastics**

From regulatory perspective, important to prevent *design-to-test*; stochastically varying parameters within scenarios is one method.

• Using PEGASUS terminology, MUSICC stores *logical* scenarios (plus optionally concrete scenarios). This is enabled by parameters in the OpenSCENARIO file:

#### <ParameterDeclaration>

<Parameter name="\$lead\_vehicle\_speed" type="double" value="33.3"/>

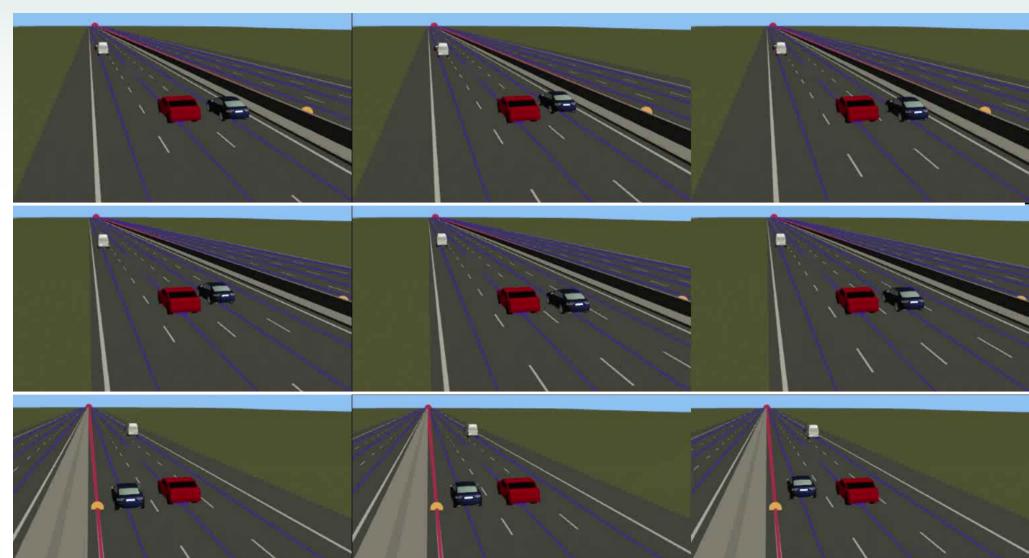
 Random selection of parameter values, according to ranges and distributions defined in the MUSICC record, has been implemented in our system



### Randomisation

### **Generates multiple concrete scenarios from each logical**





3 lane – GB

4 lane – GB

3 lane – FR

## **Quick notes: Storing OpenX files**



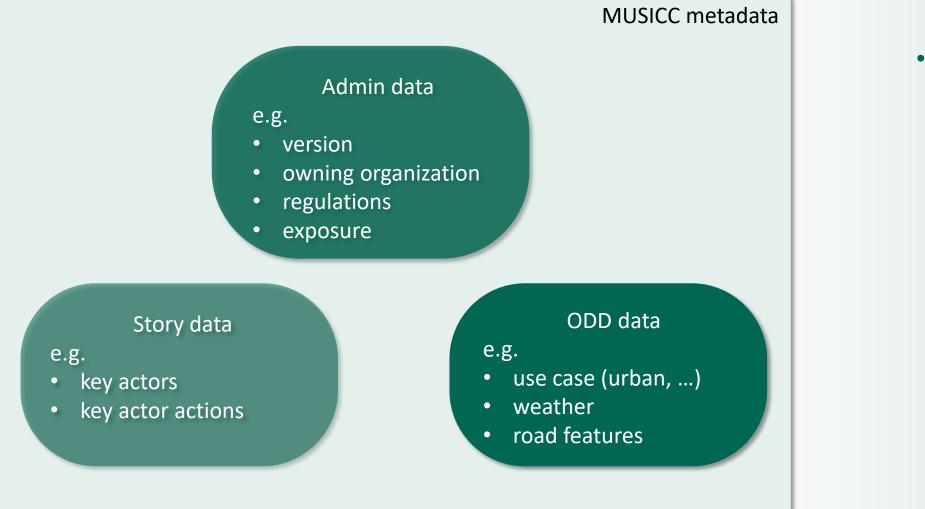
MUSICC is a database targeted at certification use, with scenarios arriving from a variety of different sources. This leads to two key requirements:

- 1. We cannot rely on filenames being unique
- 2. We need to track version history of stored scenarios
- For the "parent" MUSICC record, we enforce a unique key of:
  - label + version + revision
- For OpenSCENARIO, catalog, OpenDRIVE, and other child files, we assign them a unique ID number in the DB
- On import a file/string comparison needs to be carried out to check if the file(s) are already present in the DB
  - This is a complex process, as we need to back-propagate any existing record IDs during the uniqueness check
  - Even then, there's no way to know if an uploaded OpenX file should be a new version or a new OpenX record



### **MUSICC metadata overview**





 ODD language should be complete and independent

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## **Need for story metadata**



In many cases, it's important to find, or treat as a group, all the logical scenarios for a particular functional scenario. E.g.:

- Find all highway cut-in scenarios
- Find all scenarios that test AEB

Some relevant fields may be part of the ODD, e.g. weather, and the desired ego manoeuvre. But not all.

- This doesn't cover the types, locations, and actions of the other participants
- But: that's what OpenSCENARIO is supposed to represent
- In some ways, the requirement here is for an abstract variant of OpenSCENARIO
  - Will OpenSCENARIO 2.0 be usable for this purpose?



## **Metadata: Importance of ODD**



All near-term AVs are likely to have a restricted Operational Design Domain



- For MUSICC, it's critical that we test an ADS against all the scenarios matching its ODD (and not against scenarios outside its ODD)
- This implies we need a precise way of specifying ODDs



## **Current ODD metadata**



Current MUSICC ODD variables include:

- Use Case (Highway, Urban, Inter-Urban, Parking)
- Country (GB, FR, DE, etc)
- Features of the road

(e.g. roundabout / 2-lane / 3-lane / divided carriageway / roadworks)

Environmental conditions

(e.g. weather: rain / snow / fog; time-of-day: day / night / dawn / dusk)

• ... and others not listed.

(Note most of these may have multiple values.)



### **Evaluation of current ODD metadata**



#### **Good points**

• Simple and unambiguous

### Key problem: level of detail

- Too much (e.g. want to allow any manoeuvre at a junction, but forced to list them all explicitly – RightTurn, LeftTurn, GoStraightAtJunction, TurnOntoMinorRoad, TurnOntoMajorRoad)
- Too little (e.g. can only specify PedestrianCrossing, but want to specify pelican crossing as OK, but not zebra crossings)
- Never likely to be exactly right...

### Second problem: cannot specify combinations

• E.g. can perform a TurnOntoMajorRoad, but only in daylight

In short: developers are creating ADS with ODDs that we cannot currently represent in MUSICC metadata



### **Solution #1: Hierarchy**

#### Allow different levels of detail to be used, depending on need and use case

- Query for scenarios matching an ODD
- Specify ODD elements present in a scenario

#### **Category: Road type**

Arterial

Urban

....

Urban motorway

High street (significant through traffic) Urban arterial other Rural Rural motorway

Local (minimal through vehicle traffic) Urban Residential street Town centre / high street Commercial / industrial area

#### **Category: Atmospheric weather**

Precipitation Rain (categories as per METAR) Light rain Moderate rain Heavy rain Violent rain Cloudburst Snow Light Medium ..... Obscuration Fog or mist

Haze

Thanks to several key stakeholders for input on this!





### Solution #2: Language



### Need a formal method for declaring which ontology elements are part of the ODD

- Need to be clear about semantics: e.g. does *exclude* "Town centre / high street" mean everything else under the "Local/Urban" category is included?
- What about combinations? E.g. "can use rural roads but not at night"

#### **Requirements**

- Easy to understand (for safety drivers, regulators, and the end users)
- Can specify simple ODDs concisely
- Powerful enough to express complex ODDs
- Cope with fact that ontology cannot (and should not) model everything



### PAS 1883: Guidance for defining Operational Design Domain for an Automated Driving System

### Challenges

- SAE J3016 introduces the concept of Operational Design Domain – what are the conditions in which the ADS is expected to perform the driving task?
- ISO/SAE standards (e.g. ISO AWI 22737) use concept but no agreed approach to defining ODD for an ADS.
- Stakeholders currently can under define ODD that may lead to confusion with endusers and unsafe introduction of ADS on roads.

### Opportunity

- Provide guidance framework on ODD definitions for the CAV eco-system (OEMs, operators, end-users, regulators) to ensure safe deployment of L3+ ADS.
- Create consistency in how ODD attributes are described (and monitored potentially) but allowing flexibility for limited and controlled environments.
- Assist end-users (e.g. transport authorities) to reference minimum sets of attributes for the ODD.
- PAS will provide recommendations on a hierarchical taxonomy for defining and describing the ODD.



### Thank you for your attention



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