

ASAM INTERNATIONAL CONFERENCE

Dec. 10–11, 2019
Dresden, Germany

ORGANIZATIONAL

Day and Time Tuesday, Dec. 10, 2019 9:00 – 17:00
Wednesday, Dec. 11, 2019 9:00 – 16:00

Venue **International Congress Center**
Ostra-Ufer 2
01067 Dresden, Germany
Phone: +49 351 216-0
www.dresden-congresscenter.de

Hotel Recommendation **Maritim Hotel**
Ostra-Ufer 2
01067 Dresden, Germany
Phone: +49 351 216-0
www.maritim.de (Code: ASAM)

Dinner Reception Tuesday, Dec. 10, 2019

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Association for Standardization of
Automation and Measuring Systems

AUTONOMOUS DRIVING –

Standardized Virtual Development
as a Key to Future Mobility

In cooperation with

STAATSMINISTERIUM
FÜR WIRTSCHAFT
ARBEIT UND VERKEHR





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AUTONOMOUS DRIVING –

Standardized Virtual Development as a Key to Future Mobility

■ The increasing number of driver assistance systems in the car culminating in the fully autonomous operation, implies that the interaction with the environment is gradually delegated from the driver to the vehicle. Therefore, the development of these driving systems can no longer be based solely on the understanding of the driver, the vehicle, and their interaction but must additionally take the environment into account.

Virtualized development is the key to manage this increased complexity. And it goes along with a radical change in the “classical” test methods: New concepts must be developed for comprehensive vehicle validation in both the real and virtual world.

These new concepts will be subject of the 4th **ASAM International Conference** taking place on Dec 10–11, 2019 in Dresden, Germany.

We will discuss various aspects of autonomous driving:

- Virtual verification and validation
- Strategies for sensor modeling and data fusion
- Artificial Intelligence and Machine Learning
- Standardization to support these new processes
- Excursions to infrastructural challenges and cyber security

ASAM invites you to take part in this exciting event. Look forward to two days with 40 presentations hosted in two tracks. An exhibition demonstrating the latest products and solutions will round up the conference. We are excited to welcome you in Dresden.

About the Conference

The ASAM International Conference is a biennial event that attracts more than 200 participants both managers and experts from the automotive industry worldwide. The conference focusses on the latest technologies and processes used in global development and validation of vehicles with specific emphasis on process integration, functional validation and quality.

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REGISTRATION FEE

| | Early Bird* | Regular | The following services are included |
|---------------------|---------------|---------------|--|
| Members: | 510 EUR + VAT | 590 EUR + VAT | – Participation in the conference – Dinner Reception on Dec. 10, 2019 – Entry to the exhibition – Conference documents – Lunch and refreshments on both days |
| Non-Members: | 810 EUR + VAT | 890 EUR + VAT | |
| Students: | 150 EUR + VAT | 150 EUR + VAT | |
| *until Sep 27, 2019 | | | |

TERMS OF CANCELLATION: Cancellations made before Nov. 10, 2019 (date of receipt of cancellation notice) will be subject to a processing fee of 100 EUR. Cancellations made after Nov. 10, 2019 and no-shows will result in a forfeiture of the full participation fee unless another person is designated. Cancellations require a written notice to dorothee.bassermann@asam.net

PRIVACY NOTICE: <https://www.asam.net/privacy/>

PROGRAM TUESDAY, DEC. 10, 2019

09:00 - 09:20 Welcome

Session I: General Aspects of Autonomous Driving

09:20 - 09:50 **KEY NOTE:** The German Government's Strategy on Automated and Connected Driving /
Dr. T. Miethaner, Federal Ministry of Transport and Digital Infrastructure

09:50 - 10:20 European View on Standardization in Vehicle Development – Process Integration, Functional Validation and Big Data Systems¹ / DG MOVE

10:20 - 10:50 *Coffee Break & Exhibition*

10:50 - 11:20 **KEY NOTE:** Development of Connected and Automated Vehicles (CAV) – Different Approaches /
Prof. Dr. F. Köster, DLR

11:20 - 11:50 **KEY NOTE:** Paradigm Change – From Field Testing to Scenario-Based Testing¹ /
Prof. Dr. G. Prokop, Technical University of Dresden

11:50 - 13:20 *Lunch & Exhibition*

Session II: From Development to Homologation

13:20 - 13:50 **KEY NOTE:** The AV Test Fleet of the Future is Virtual /
Z. Greenstein, NVIDIA

13:50 - 14:20 Handling the Complexity of Developing Automated Driving Functions with Scenario-Based Systems Engineering (SBSE) / Audi AG

14:20 - 14:40 Virtual-Based Homologation of AV Systems / TÜV SÜD Czech

14:40 - 15:00 Certification of Autonomous Vehicles in Synthetic Environments / XPI Simulation

15:00 - 15:30 *Coffee Break & Exhibition*

Session III: Testbed Dresden – Synchronized Mobility 2023

15:30 - 15:50 "Synchrone Mobilität 2023" – An Initiative of the Free State of Saxony /
Fraunhofer IVI

15:50 - 17:00 Vehicle Architecture for Automated Driving in Urban Areas¹ / IAV GmbH
HMI in the Vehicle / Technical University of Chemnitz

ITS Testbed Backend for Highly Automated Urban Traffic¹ / Fraunhofer IVI

Roadside Infrastructure for Connected Driving / MUGLER AG

Simulation based Research of Optimal Longitudinal Control of Automated Vehicles with GLOSA Functionality / Technical University of Dresden

Traffic and Accident Scenarios Merged in the Harmonized PCM v5 Standard –
Harmonization & Collection Methods¹ / VUFO, Fraunhofer IVI

¹ Working Title

PROGRAM WEDNESDAY, DEC. 11, 2019

Session IV: Standardized virtual development

- 9:00 - 9:20 Development of a 3D Model Exchange Format With Physical Material Properties for Virtual Development, Test and Validation / BMW AG
- 9:20 - 9:40 Real Driving Validation of Highly Automated Driver Assistance Systems based on OTX standardization / ASAM e.V.
- 9:40 - 10:00 Semantically Rich Distributed Data Science Platforms – Patterns for Future Standardized Virtual Development in autonomous driving
iASYS Technology Solutions Pvt Ltd.
- 10:00 - 10:20 No Bit Lost – High Volume MDF4 Recording in ADAS Development / ViGEM GmbH

10:20 - 10:50 *Coffee Break & Exhibition*

- 10:50 - 11:10 Enabling Virtual Product Validation: Quality Measures and Traceability / BMW AG
- 11:10 - 11:30 Boosting the Development of OpenDRIVE Through Integration Into Standardised GIS Frameworks / DLR e.V.
- 11:30 - 11:50 OpenSCENARIO Beyond Simulation – Application Methods for Field Testing / Fraunhofer IVI
- 11:50 - 12:10 Open Standards as a Leverage for the Development of Automated Driving / Vector Informatik GmbH

12:10 - 13:45 *Lunch & Exhibition*

Session V: Virtual Validation + Verification

- Moving Testing from “Proving Ground” to “Proving Cloud” / IPG Automotive GmbH
- Scenario-Based Validation Framework for highly automated/autonomous vehicles / AVL List GmbH
- OpenSCENARIO for Automated Vehicle Validation and Verification / Siemens Product Lifecycle Management Software Inc.
- The Road to Cloud: Cloud based Validation of Automotive Software / dSPACE GmbH

Coffee Break & Exhibition

- Traffic in Co-Simulation as a Standard Toolchain for Automotive Development / PTV AG
- Testing Challenges for Autonomous Driving: From ASAM OpenX to the Evaluation of Millions of Simulations / TraceTronic GmbH
- Coverage Driven Verification – A Novel Approach for Virtual Testing and Validation / Foretellix Ltd.
- Extraction of Real-World Driving Scenarios and Generation of Effective-Valid Scenarios for Autonomous Vehicles and ADAS Using Artificial Intelligence / AKKA GmbH & Co. KGaA

Lunch & Exhibition

Session VI: Artificial Intelligence / Machine Learning

- 13:45 - 14:15 **KEY NOTE:** Current Trends in Machine Learning for Automated Driving / Dr. A. Jungmann, IAV GmbH
- 14:15 - 14:35 Object Detection in Autonomous Driving Scenarios / FusionSystems GmbH
- 14:35 - 14:55 Convolutional Tunneling and Its Application in Neural Network / Automotive Artificial Intelligence GmbH

Session VIII: Cyber Security

- 14:55 - 15:15 An Update on SAE Scenario Development and Cyber Security for ADS / SAE International
- 15:15 - 15:45 **KEY NOTE:** Cyber Security Innovation Lead / Dr. M. Cheah, HORIBA MIRA
- 15:45 - 16:00 Closing Remarks

Session VII: Sensor Modeling and Data Fusion

- New Sensor Modeling Approach for Autonomous Driving Simulation and Sensor Simulation / OTSL Inc., COSEDA Technologies GmbH
- Data Fusion Development for Series Production / BASELABS GmbH
- An Efficient Approach to Generate Tagged Traffic Scenario Models from Naturalistic Driving Data / CHJ Automotive

More details: www.asam.net/conferences-events

