

CONFIGURATION AND GENERATION OF ROAD SEGMENTS AND JUNCTIONS FOR VERIFICATION OF AUTONOMOUS SYSTEMS

Kick-Off Workshop ASAM OpenDRIVE 2018-10

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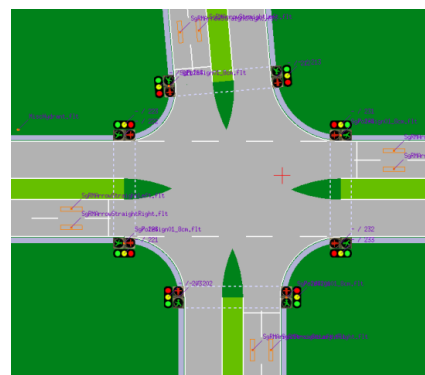
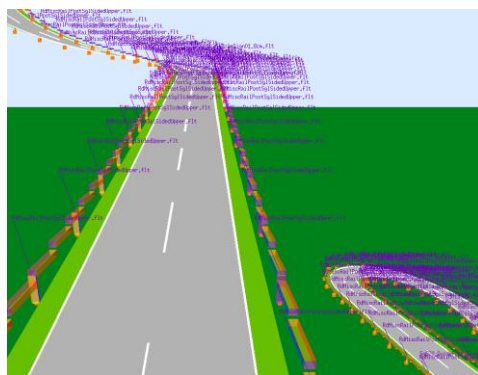
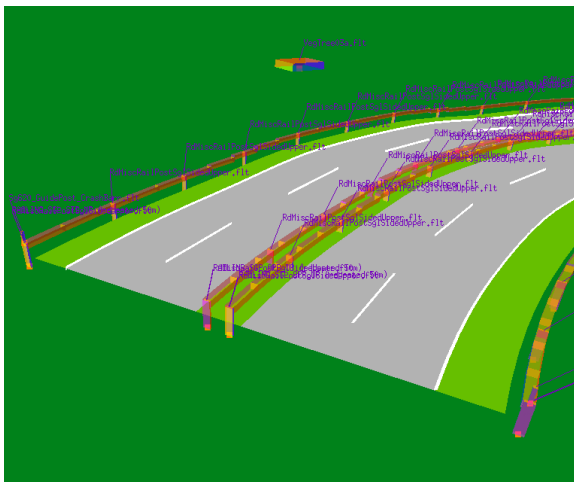


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Verification of Autonomous Systems

Road Configuration (SCODE)

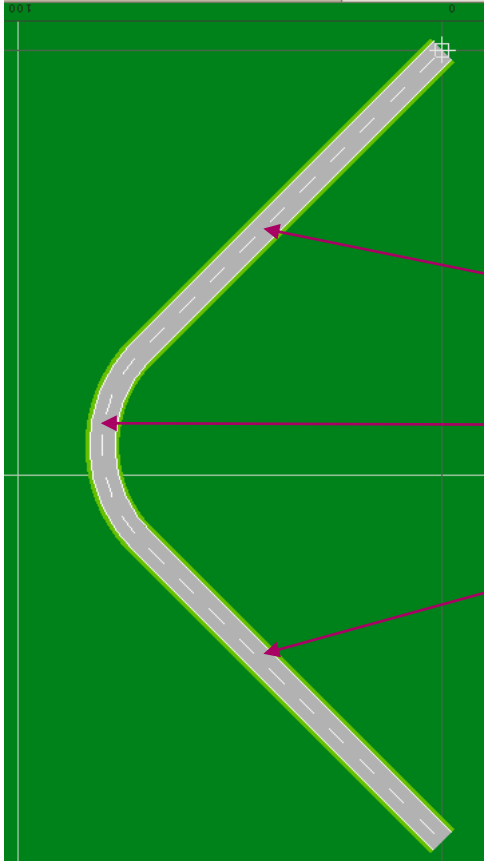
Dimension	NOT	Alte...e 1	Alte...e 2	Alternative 3	Alternative 4	Alternative 5	Alternative 6
roadtype	<input type="checkbox"/>	motorway	rural	town	lowSpeed	pedestrian	bicycle
roadtype-special	<input type="checkbox"/>	none	town-solid	motorway-2x2L	motorway-2x2L-StopL	motorway-2x4L-StopL	rural-bike
heading	<input type="checkbox"/>	0	30	45	90	180	270
shape	<input type="checkbox"/>	0	90	-90	s-curve	s100s100a30	-45
elevation	<input type="checkbox"/>	0	-0.2	0.2	1plateau	3hills5	10hills5
length	<input type="checkbox"/>	50	100	200	400	500	1000
tunnel	<input type="checkbox"/>	0	1	2			
bridge	<input type="checkbox"/>	0	1	2			
vegetation	<input type="checkbox"/>	0	1				
animal	<input type="checkbox"/>	0	1	2			
building	<input type="checkbox"/>	0	1				
guide-posts	<input type="checkbox"/>	0	1				
guardrail	<input type="checkbox"/>	0	1				



- ▶ Mission: Develop methods and tools for the model-based verification of autonomous systems
- ▶ Goal: Automated generation of relevant test cases for SIL simulation from structured, formalized scenarios
 - ▶ Configure and generate the static elements of a scenario -> OpenDrive
 - ▶ Add dynamic agents -> OpenScenario
 - ▶ Simulate and apply optimization-driven approach

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Gapless Roads without redundant information



- ▶ Goal: Enable easy combination of road geometries
- ▶ Example: combine two straight road segments with a curve
current state:

```
<road name="Highway2Hell" length="250" id="1" junction="-1">  
  <type s="0" type="rural"/>  
  <planView>  
    <geometry s="0" x="0" y="0" hdg="0.785398163397448" length="100">  
      <line/>  
    </geometry>  
    <geometry s="100" x="70.711" y="70.711" hdg="0.7853981" length="50">  
      <arc curvature="0.0314159"/>  
    </geometry>  
    <geometry s="150" x="70.711" y="115.727" hdg="2.356194" length="100">  
      <line/>  
    </geometry>  
  </planView>  
</road>
```

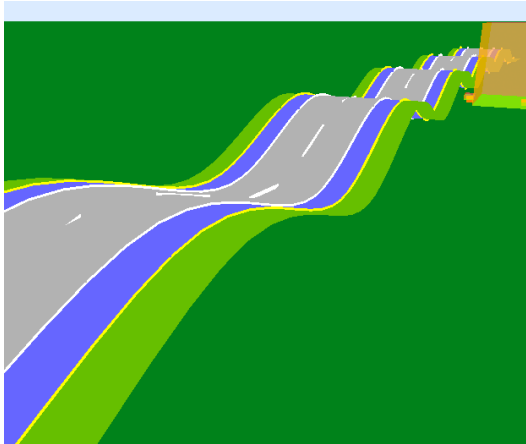
Redundant
information

- ▶ What it should be:

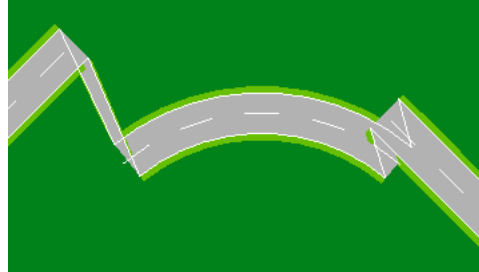
```
<road name="Highway2Hell" id="1" junction="-1">  
  <type s="0" type="rural"/>  
  <planView>  
    <geometry s="0" x="0" y="0" hdg="0.785398163397448" length="100">  
      <line/>  
    </geometry>  
    <geometry length="50">  
      <arc curvature="0.0314159"/>  
    </geometry>  
    <geometry length="100">  
      <line/>  
    </geometry>  
  </planView>  
</road>
```

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Gapless Roads without redundant information



- ▶ What happens if x/y-coordinates are wrong:



Redundant information

- ▶ Same for e.g. elevation

```
<elevation s="100" a="0" b="0" c="0.0015" d="-1e-005"/>  
<elevation s="200" a="5" b="0" c="0" d="0"/>  
<elevation s="300" a="5" b="0" c="-0.0015" d="1e-005"/>  
<elevation s="400" a="0" b="0" c="0" d="0"/>
```

- ▶ Put all trigonometric calculations into viewer/simulator
- ▶ Make attributes optional
 - ▶ if missing assume gapless roads
 - ▶ if available -> use them -> backwards compatible

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Road Objects



- ▶ To generate realistic environments we need additional elements
 - ▶ Guide posts, guard rails, vegetation, buildings, bridges, tunnels, pedestrians, animals, hydrants, recycle bins, bus stops, street lights, illuminated advertising, ...
- ▶ Library of 3D road objects
 - ▶ Open, expandable
 - ▶ Usable in all viewers, editors, simulators
 - ▶ Support animation (e.g. walking pedestrians, rotating wind turbine)
 - Controllable via signals from OpenScenario (e.g. switch on street light)
 - ▶ Format: e.g. glTF from Khronos Group <https://www.khronos.org/glTF/>
 - ▶ Scalable objects
 - ▶ Add hints for correct position, e.g. zOffset values for posts

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Surface and horizon



- ▶ Add a simple way to add a surface to both sides of a road
 - ▶ Follow elevation of road
 - ▶ Should also work for not even terrain like pass roads
 - ▶ Smooth transition to other roads and junctions
 - How to handle z-positioning of road objects like vegetation?
 - ▶ Should consider tunnels and bridges
- ▶ Enable to add a horizon (end-of-terrain)
 - ▶ City, mountains, forest, wall, fence, ...
- ▶ Goal: Enable to specify a complete static scenario
 - ▶ Not only a floating road in free space



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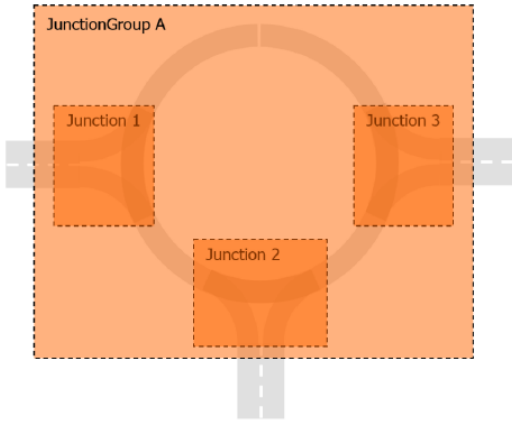
Traffic Signs



- ▶ Support all traffic signs and lights
 - ▶ All major countries
 - ▶ At least all German signs and lights according to https://de.wikipedia.org/wiki/Bildtafel_der_Verkehrszeichen_in_der_Bundesrepublik_Deutschland_seit_2017
 - ▶ Provide a catalog with pictures and options (value = speed limit)
 - ▶ Use type, subtype and value
 - ▶ Use country attribute (and not country=„OpenDRIVE“)
 - ▶ Add option to easily add a post (to avoid hovering traffic signs)

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Junctions

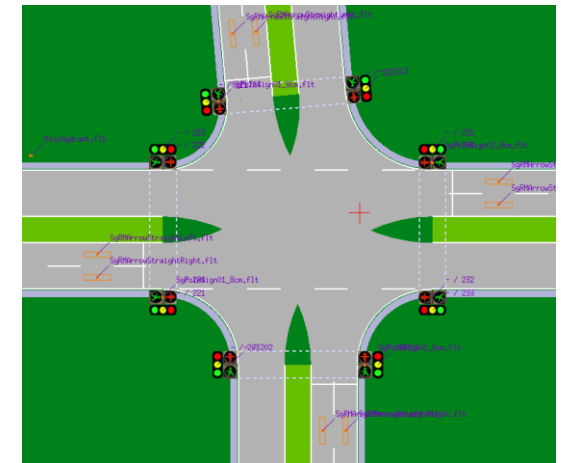
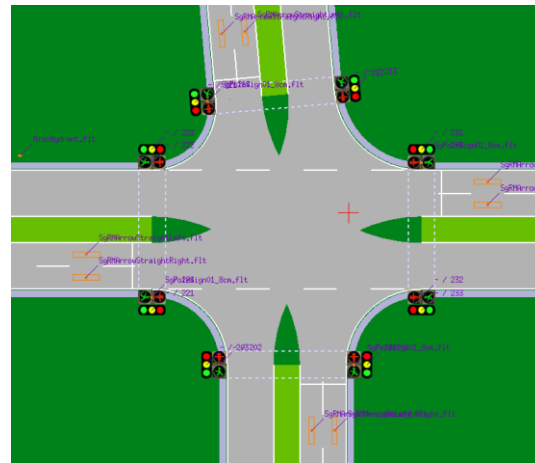
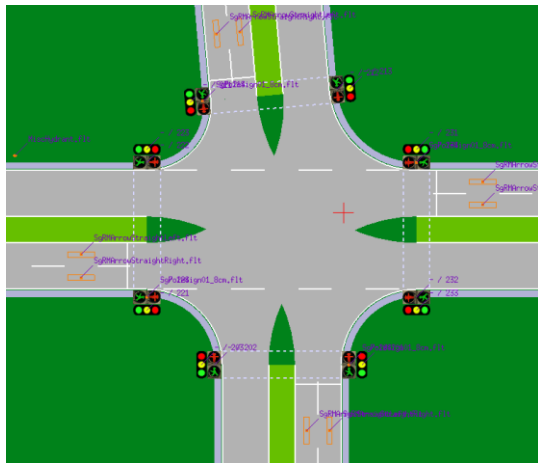


- ▶ Rough idea:
 - ▶ Simplify roundabouts
 - Special handling for roundabouts instead of combination of several junctions
 - Should support at least standard roundabouts

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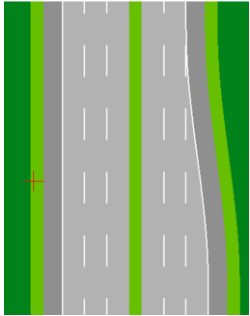
Reference Implementation

- ▶ To get the comparable results in all viewers, editors and simulators we need a reference implementation



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Documentation

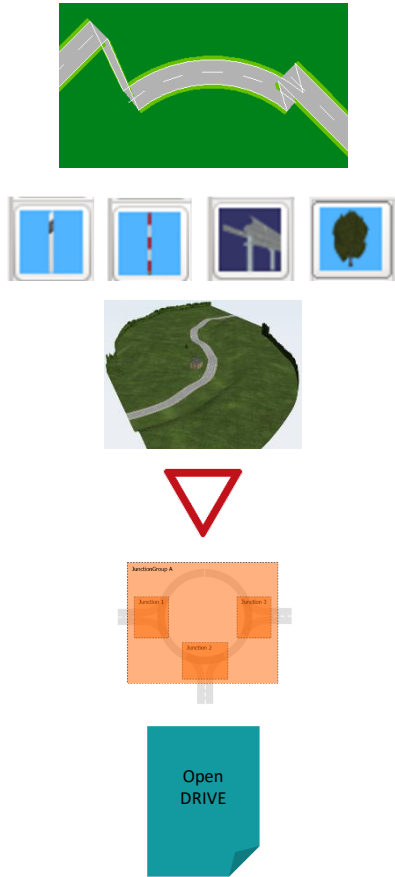


- ▶ Improve OpenDrive documentation
 - ▶ Add complete XML parts (copy-and-paste)

```
<signal s="50" t="-3.2" id="200" name="VorfahrtAchten" dynamic="no" orientation="+" zOffset="4" type="205" country="OpenDRIVE" subtype="-1" value="-1"/>
```
 - ▶ Add all supported signals and objects with pictures
 - ▶ Add formulas for smooth transitions (lane merge, elevation)
$$c = 3 * (b2 - b1) / d^2 \quad d = 2 * (b1 - b2) / d^3$$
 - ▶ Add simple but complete OpenDrive examples files

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Requirements Summary



- ▶ Remove redundant information
- ▶ Library of 3D road objects
- ▶ Add surface and horizon
- ▶ Support all traffic signs
- ▶ New roundabouts element
- ▶ Reference implementation
- ▶ Improve documentation

- ▶ Other
 - ▶ Weather and sun position -> better handled in OpenScenario or other format

