

# ASAM – Open Standards

## Proposal Workshop ASAM OpenMaterial

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Höhenkirchen



# Where do we stand today in our projects?

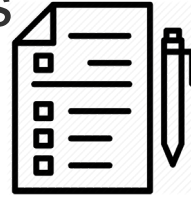
>400  
participants



>200  
unique companies



9  
Standardisation  
projects



9  
Releases  
in 2022



2  
Concept  
projects

1  
Ongoing  
ideation



1  
Study  
group



3  
Proposals being  
prepared

6  
Office  
employees  
supporting  
projects

# Ongoing standardisation efforts...

SOVD  
*Communication with SDVs*

ODS  
*Test data management*

OpenSCENARIO  
*Description of dynamic content*

XIL  
*Communication between test automation tools and test benches*

OTX  
*Definition of test procedures*

OpenDRIVE  
*Description of logical road networks*

OSI  
*Interface for the environmental perception of AD functions*

OpenTestSpecification  
*Hollistic test specification*

OpenODD  
*Specification of ODDs*

MDF  
*Storage of measurement data*

OpenLabel  
*Data structure for labels & tags*

# OpenSCENARIO

# OpenSCENARIO Differentiation Statement

## ASAM OpenSCENARIO®

### OpenSCENARIO 1.x

- XML schema for describing **scenarios** with synchronized maneuvers of vehicles, pedestrians, and other traffic participants
- Supports specifying precise trajectories with capability to parameterize and vary their properties
- Structured format that can be validated, edited, imported, and exported by simulation tools and content editors
- Tuned to support trigger-action scenario descriptions
- Optimized for simple machine parsing and processing
- **Primary use case: predictable highly precise scenarios that may be used with external test specification for V&V**

### OpenSCENARIO 2.x

- Domain specific programming language for describing **test scenarios** of synchronized maneuvers of vehicles, pedestrians, other traffic participants and ADS function control
- Supports specifying scenario intent at a higher level of abstraction along with KPIs, checks, & coverage metrics
- Built-in abstract road descriptions
- Designed to enable exploration of scenario/functionality space to identify potential unknowns
- Optimized for composability to maximize scenario reuse
- Designed as V&V programming language
- Enables higher level of automated test generation at scale
- **Primary Use case: Large scale V&V**

The differentiation between the two standards is by their primary use cases. A primary use case describes the main use case for which the standard is intended and a key consideration behind many design decisions. The primary use case is not exclusive, the standards may be (and are) used for a wide variety of additional use cases, with overlap, but these are not specified here.

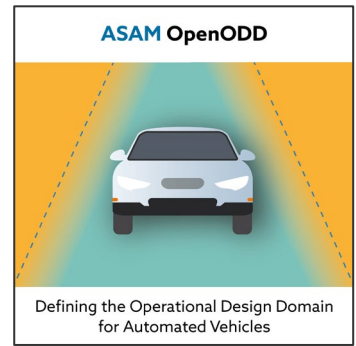
# Roadmap

- The two versions, 1.x. and 2.x, shall be developed as two separate standards, with no formal migration nor convergence required by ASAM.
- Continued alignment of the two standards is encouraged but is subject to project participant interests and is not required by ASAM. This will be driven by the market/members and is not part of the formal roadmap of ASAM OpenSCENARIO.

# OpenODD

# What is an ODD in the context of OpenODD?

A machine and human readable format for representing a defined Operational Design Domain that is measurable and verifiable



A list of attributes and values, based on a taxonomy or ontology

weather

temperature:`single`(-20..40) [°C]

rain

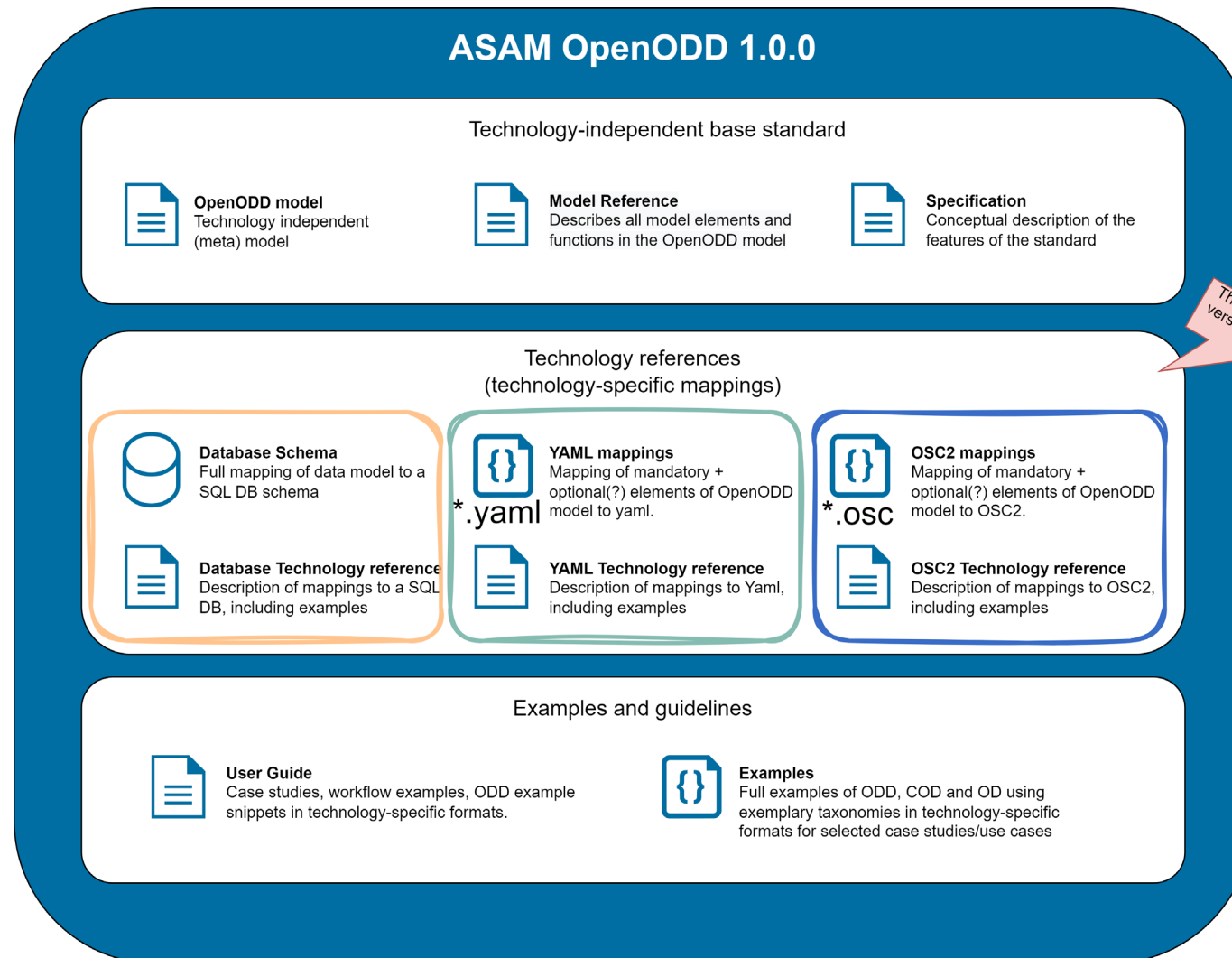
light:(droplet\_size:`single`,  
density:`single`) ((0..1),  
(0..1k)) ([mm<sup>3</sup>], [1/m<sup>3</sup>])



Boundary definition



# ASAM OpenODD deliverables

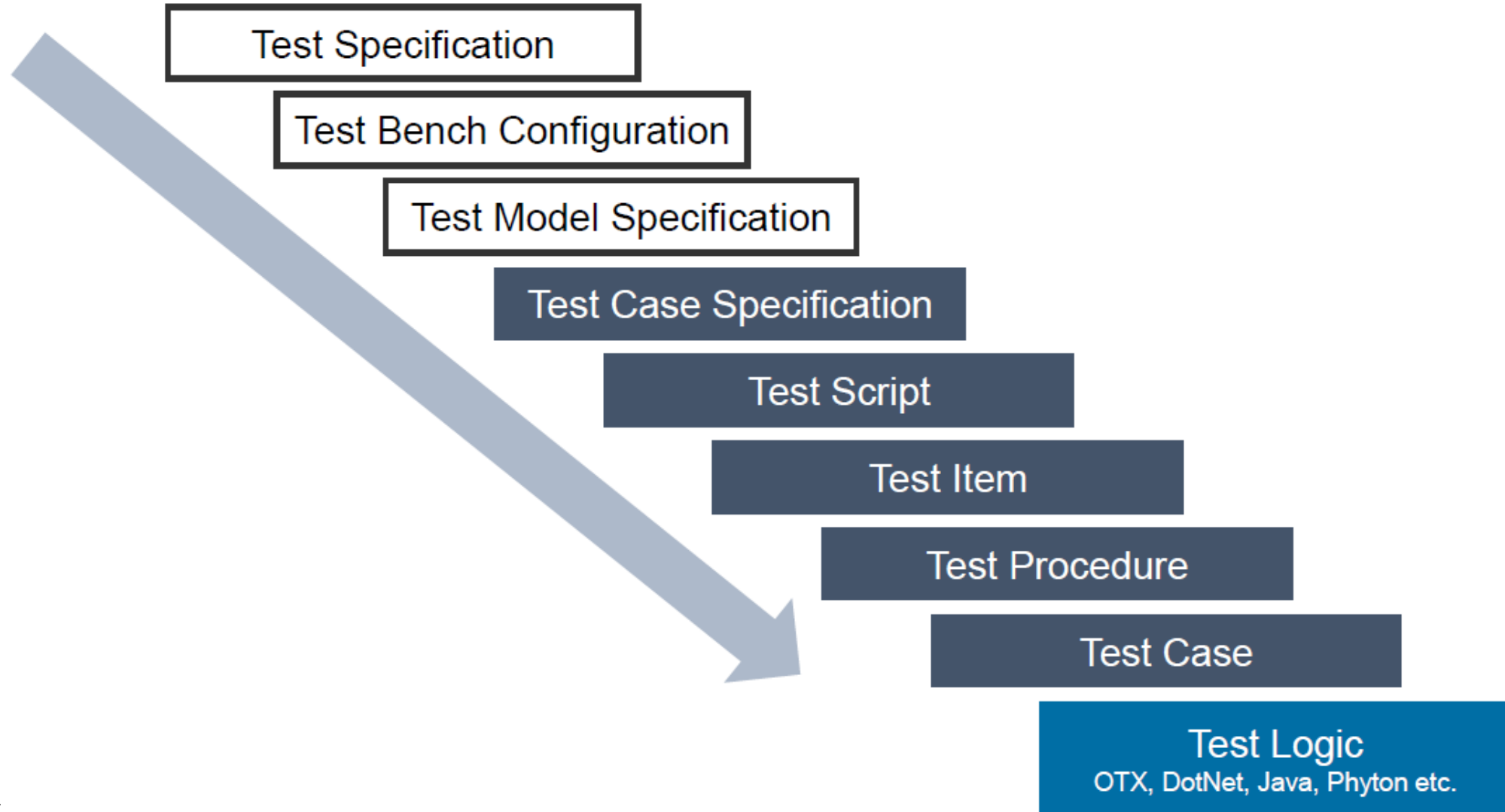


# OpenTestSpecification

# Concept Project ASAM OpenTestSpecification

	TEST ENVIRONMENT								
	MODEL- IN-THE-LOOP	SOFTWARE REPROCESSING	CLOSED-LOOP SIL	HARDWARE REPROCESSING DATA REPLAY	CLOSED-LOOP HIL	VEHICLE- IN-THE-LOOP (VIL)	DRIVER- IN-THE-LOOP (DIL)	PROVING GROUND	OPEN ROAD TESTING FIELD MONITORING
TEST METHOD									
<b>REQUIREMENTS- BASED TEST</b> (FUNCTIONAL TEST) <i>Software architectural design/Specified functionality</i>	<b>More details 5.2.2</b> Requirements-based testing MIL	<b>Test of ADAS/AD software via open loop</b> e.g. detection quality	<b>More details 5.2.1</b> Use cases Requirements-based test SIL		<b>More details 5.2.1</b> Requirements-based testing on closed-loop HIL	<b>More details 5.2.7</b> Requirements-based testing vehicle-in-the-loop		<b>Testing in a controlled proving ground environment</b> e.g. testing of the complete ADAS function in real-world conditions	<b>Testing of the ADAS/AD functions under real-life use cases in the field</b> e.g. shadowing
<b>INTERFACE TEST</b> <i>Software unit implementation/ Hardware - software interface specification</i>			<b>Software integration tests</b> e.g. test of interfaces for communication between ...	<b>More details 5.2.6</b> Hardware reprocessing Data replay	<b>Higher-level integration tests</b> e.g. testing of bus communication between ECUs	<b>Testing of complete ADAS/AD effect chain on system level</b> e.g. interaction			
<b>FAULT INJECTION</b> <i>Testing of safety mechanism/ Robustness</i>	<b>More details 5.2.3</b> Fault injection on MIL	<b>Evaluation of robustness</b> e.g. robustness against pixel faults	<b>Verification of safety mechanisms</b> e.g. out of range e.g. testing robustness of software calibration	<b>Verification of safety mechanisms including hardware</b> e.g. testing robustness	<b>Testing of safety mechanisms with integrated system</b> e.g. electrical failure simulation like short to ground e.g. testing of robustness against vehicle tolerances		<b>Validation of overall system behavior</b> e.g. testing of controllability	<b>Verification of overall system performance</b> e.g. testing of safety	
<b>RESOURCE USAGE PERFORMANCE TEST</b> <i>Sufficiency of resources/ Hardware architectural design</i>					<b>Testing of the vehicle network performance</b> e.g. sleep and wake				
<b>SCENARIO-BASED TEST</b> <i>Validation of real-life use cases/SOTIF validation</i>	<b>Validation of control components</b> e.g. testing of ADAS/AD effect chain in modeling environment		<b>More details 5.2.8</b> Scenario-based testing SIL Closed loop		<b>Validation of electronics integration</b> e.g. testing the overall system behavior in challenging scenarios	<b>Validation on system level</b> e.g. complete system reaction to the most challenging scenarios	Validate interaction of driver with safety- relevant vehicle function (HMI, ADAS, active chassis systems), confirm controllability classifications from hazard analysis and risk assessment	<b>More details 5.2.5</b> Scenario-based testing on proving grounds	<b>More details 5.2.4</b> Scenario-based open road testing

# Concept Project ASAM OpenTestSpecification



# Offroad Challenges

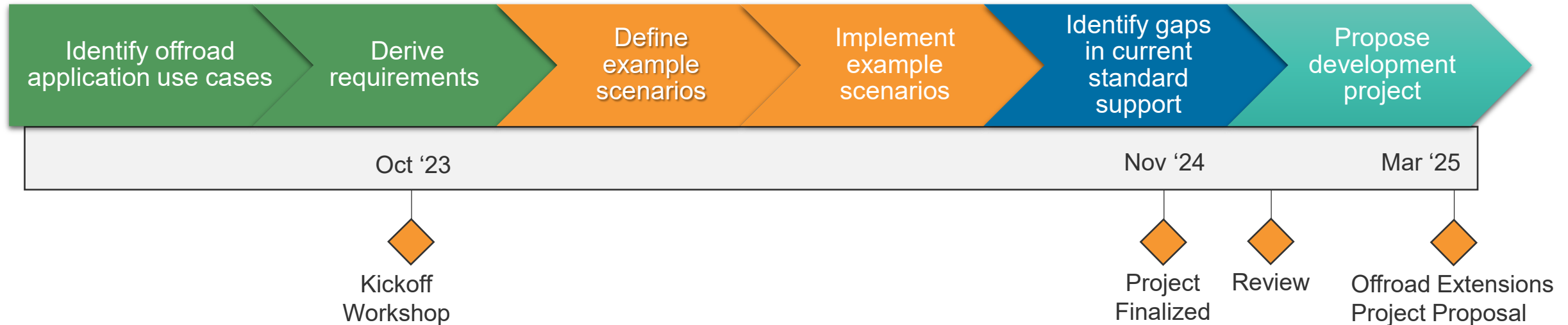
- Complex 3D terrain
- Sensor modeling and surface materials (including link between appearance and physical characteristics)
- Object representation
  - Vegetation and other natural obstacles
  - Meshes, materials, physics
- Representation of the subsurface
  - Soil strength, density, temperature, water content
  - Effects on mobility
- Vehicle-terrain interaction and material dynamics
  - Mud and water spray
  - Mud and snow deformation
  - Accumulation of material on vehicles
- Weather conditions
- Occlusion of sensors
  - Mud, snow, dirt in the air and on camera lens



# Concept Project ASAM OpenX in Offroad Applications

## GOAL

- Evaluate the need for extensions to existing standards or development of new standards to support modeling and simulation of (a) vehicle mobility in off -road conditions and (b) earth moving for digging, loading, and hauling



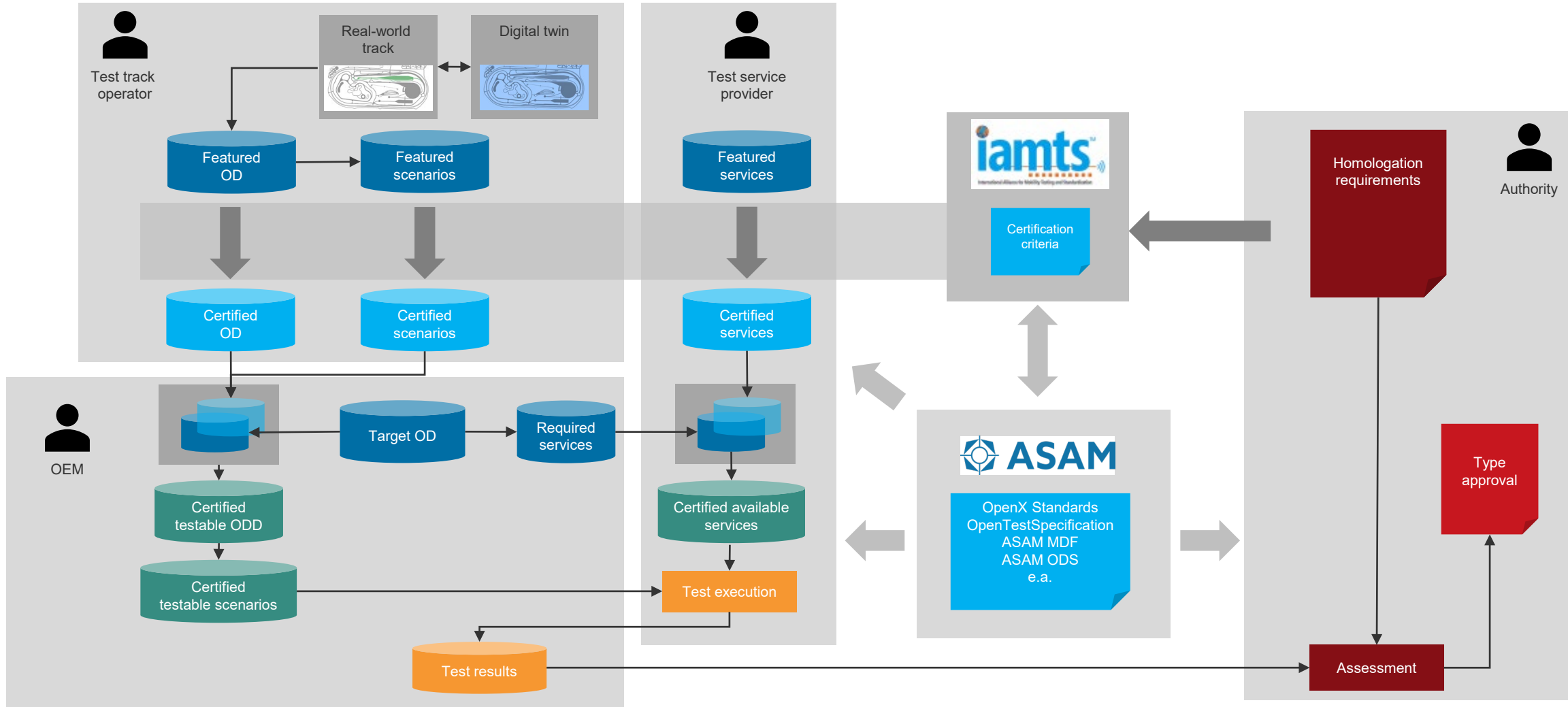
# Upcoming topics

# Describing and Certifying Proving Grounds with the help of ASAM standards



# Collaboration along the workflow

How it works – on OD(D) level

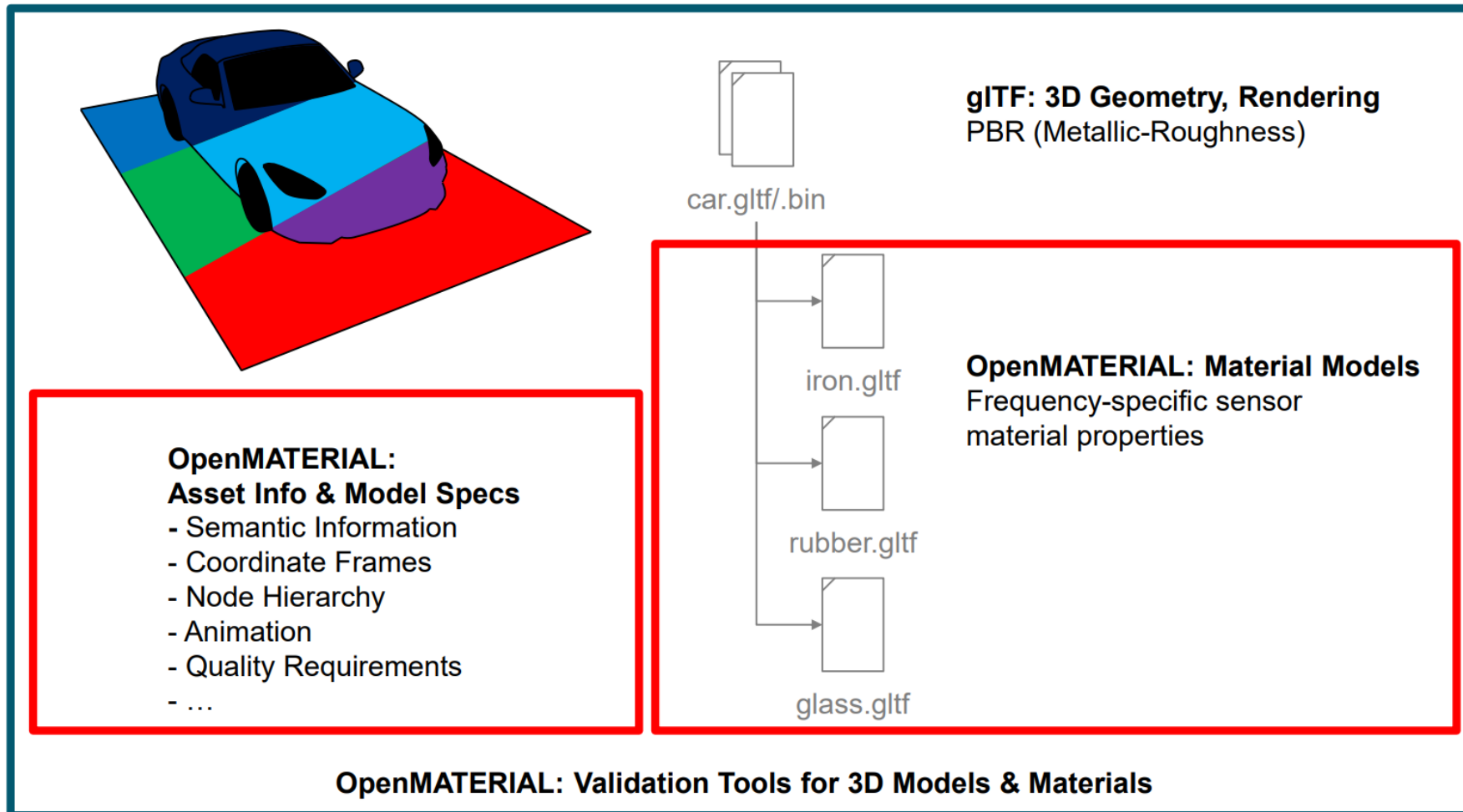


# OpenMaterial

# OpenMaterial

Status

Standardized data structure for materials and 3D assets



Define a format for material properties

Extend OSI Sensor View to support material properties

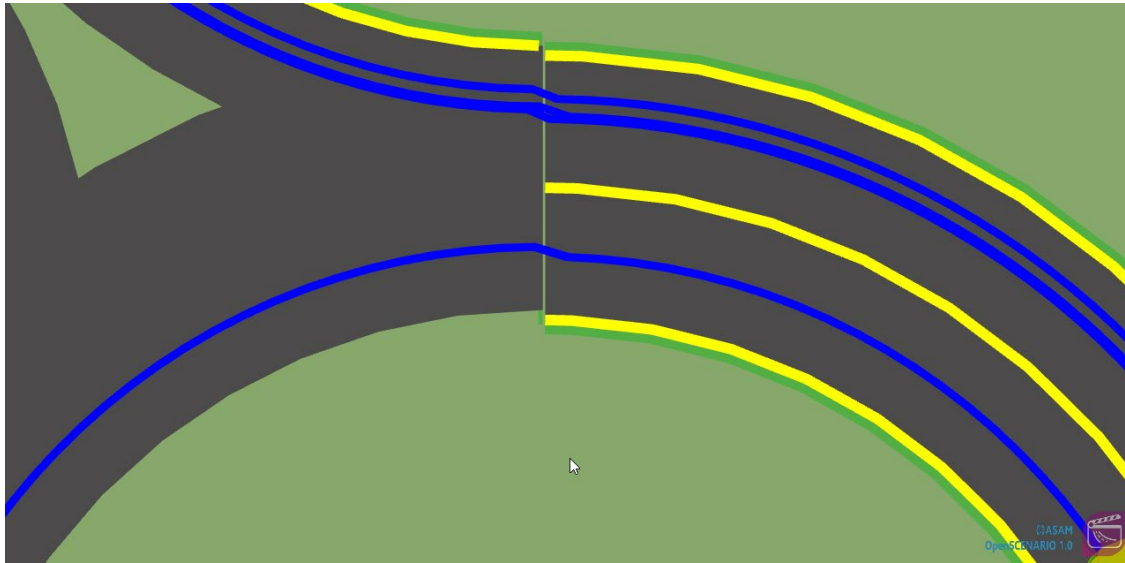
Define a format for data associated with assets

Define a data structure for 3D models

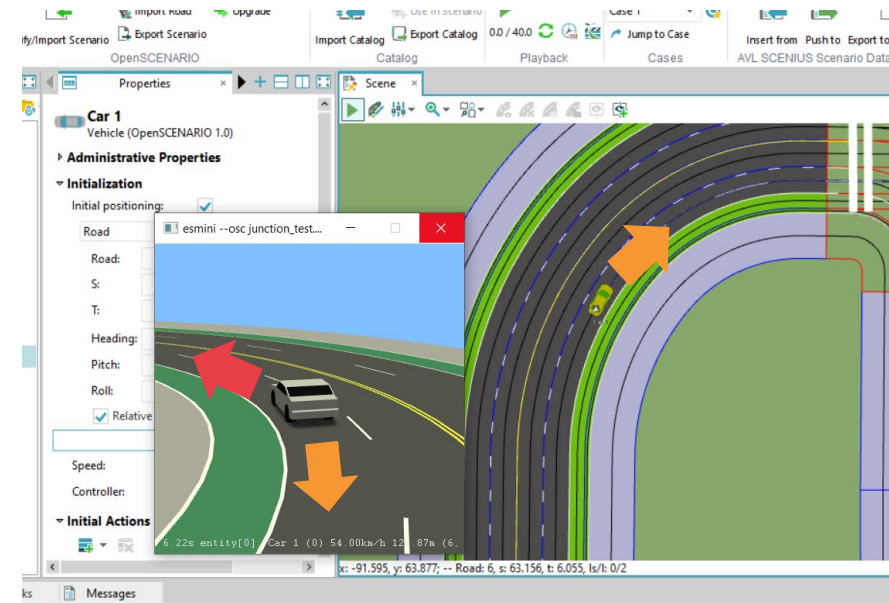
# Quality Checker

# Ambiguity examples

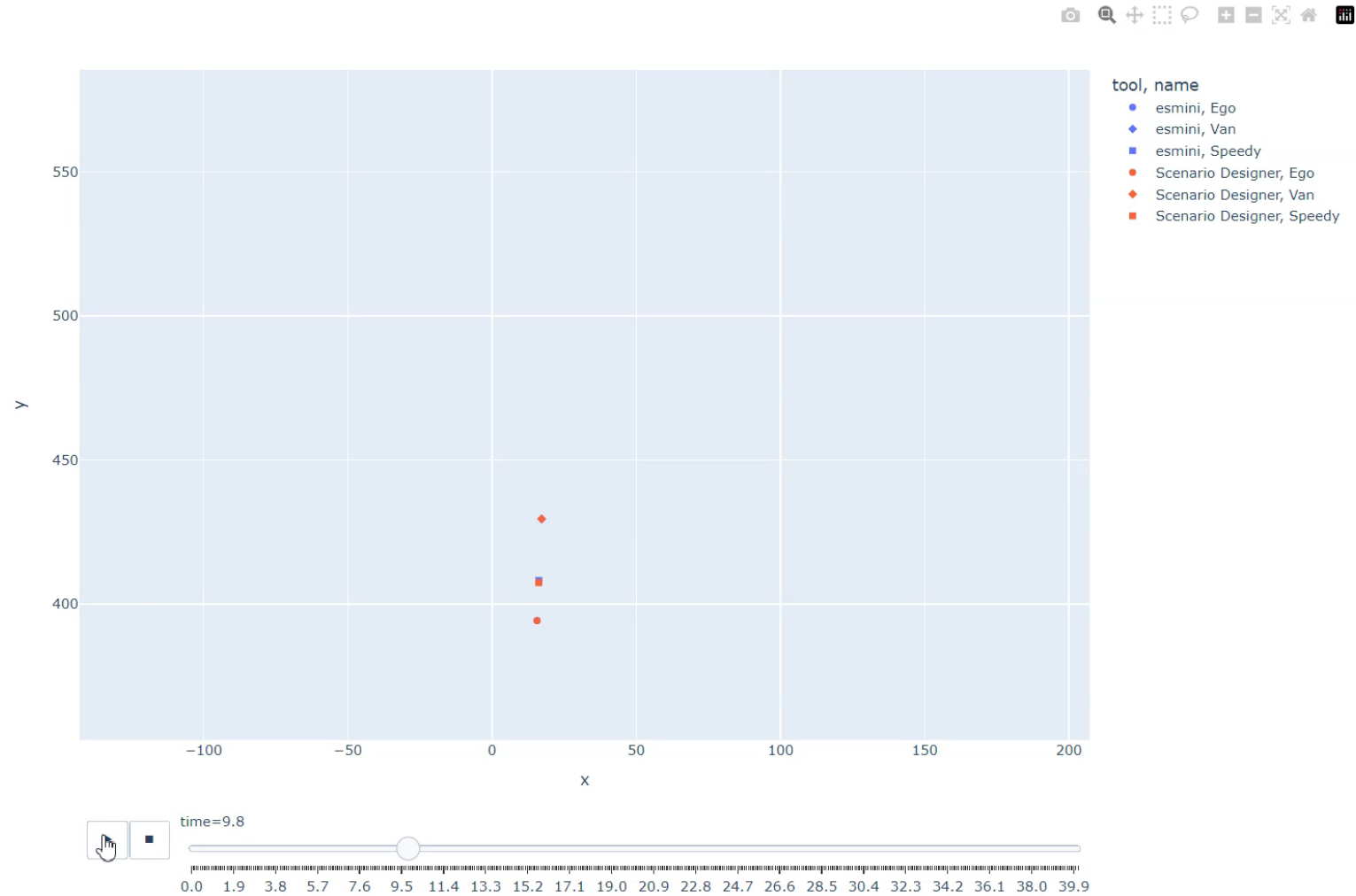
## Geometric discontinuity



## Default value misinterpretation – driving direction rules



# OpenSCENARIO



## Another example: Traffic participants

What's wrong?

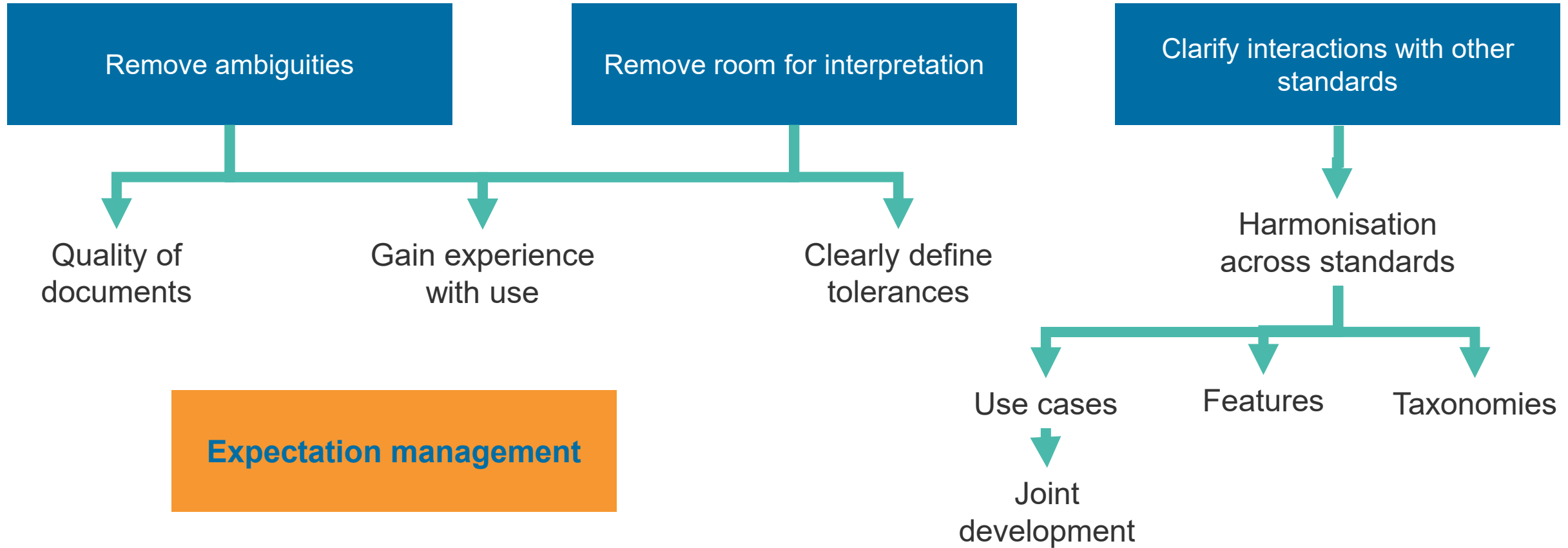


A **pedestrian** in OSC 1.x and a **vehicle** in OSI.



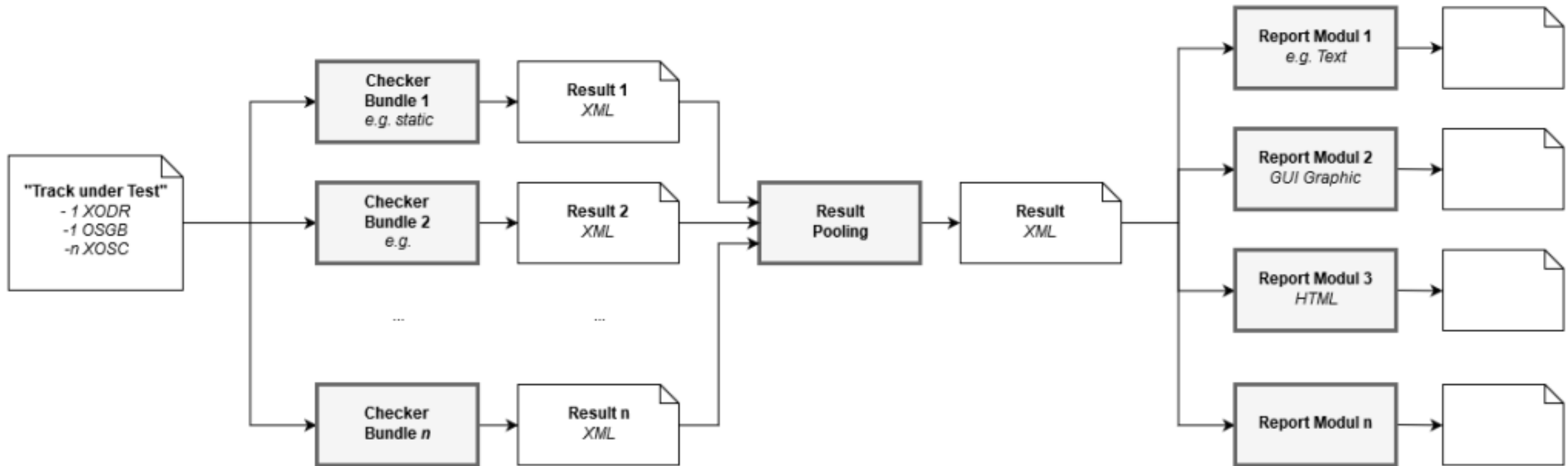
**Truck** or **car with trailer** in OSC 1.x?  
**Luxury\_Sedan with Trailer** in OSI?

# Mitigating the differences





# ASAM Checker & Validation Tooling



# Upcoming topics

SCDL  
*Formal notation for  
ISO26262 safety  
concepts*

OpenMaterial  
*Description of material  
properties & 3D model  
data structures*

ASAM Quality Checker  
*Checking & validation  
framework for ASAM  
standards*

Offroad  
*Application of OpenX in  
other domains*

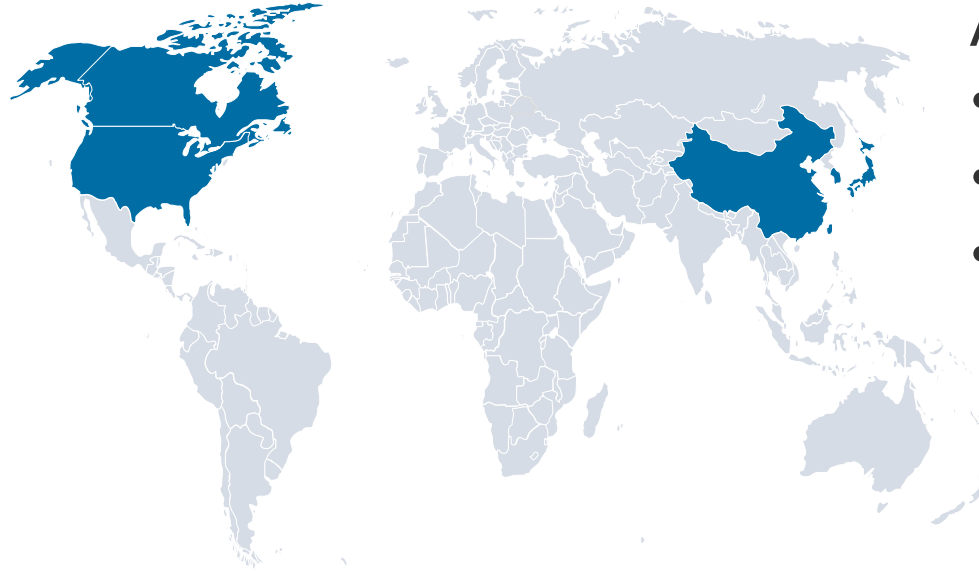


# What else?

## New topics



## More targeted regional efforts

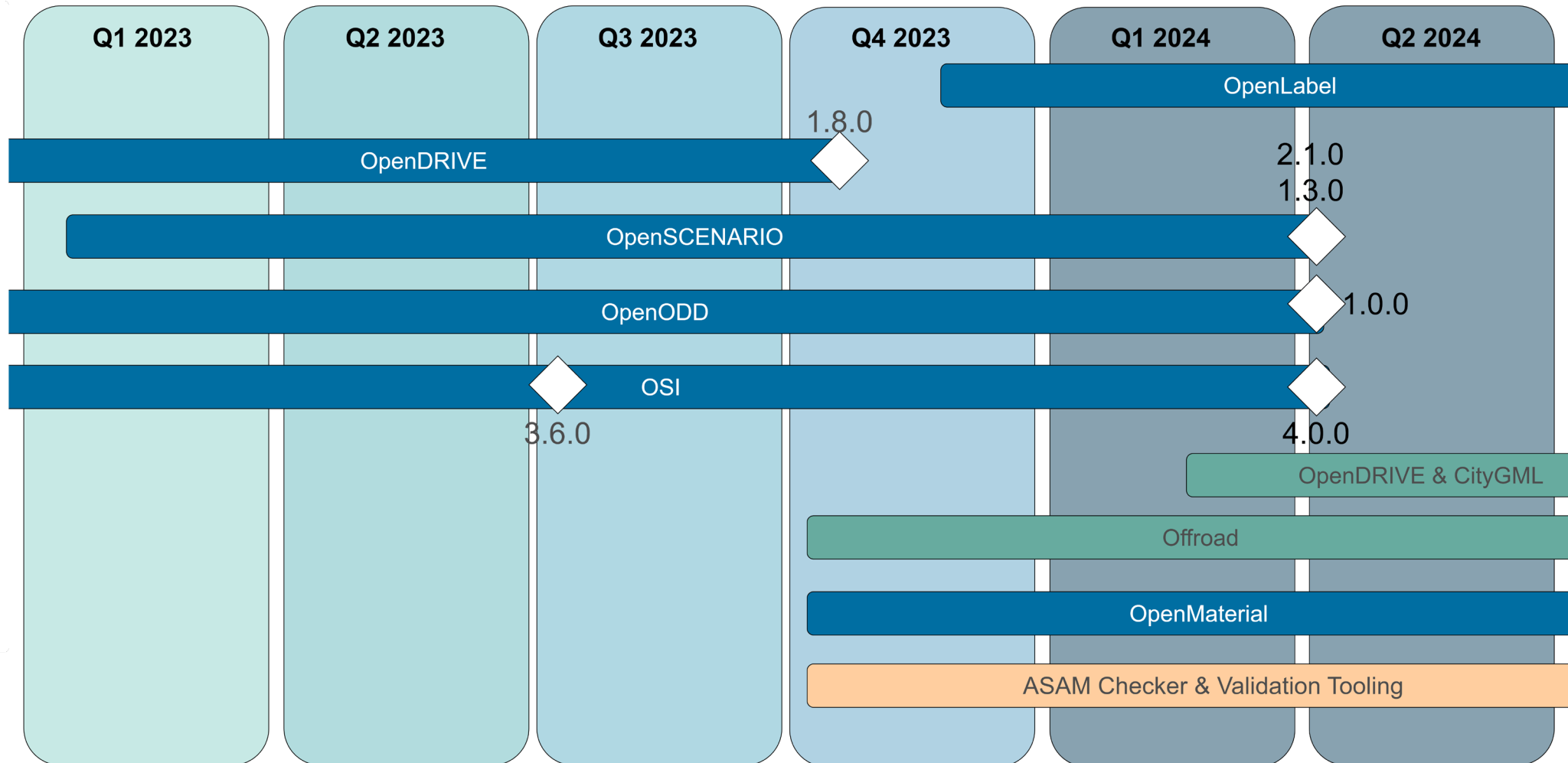


## And more...

- Growing the team
- Harmonisation
- Supporting research projects

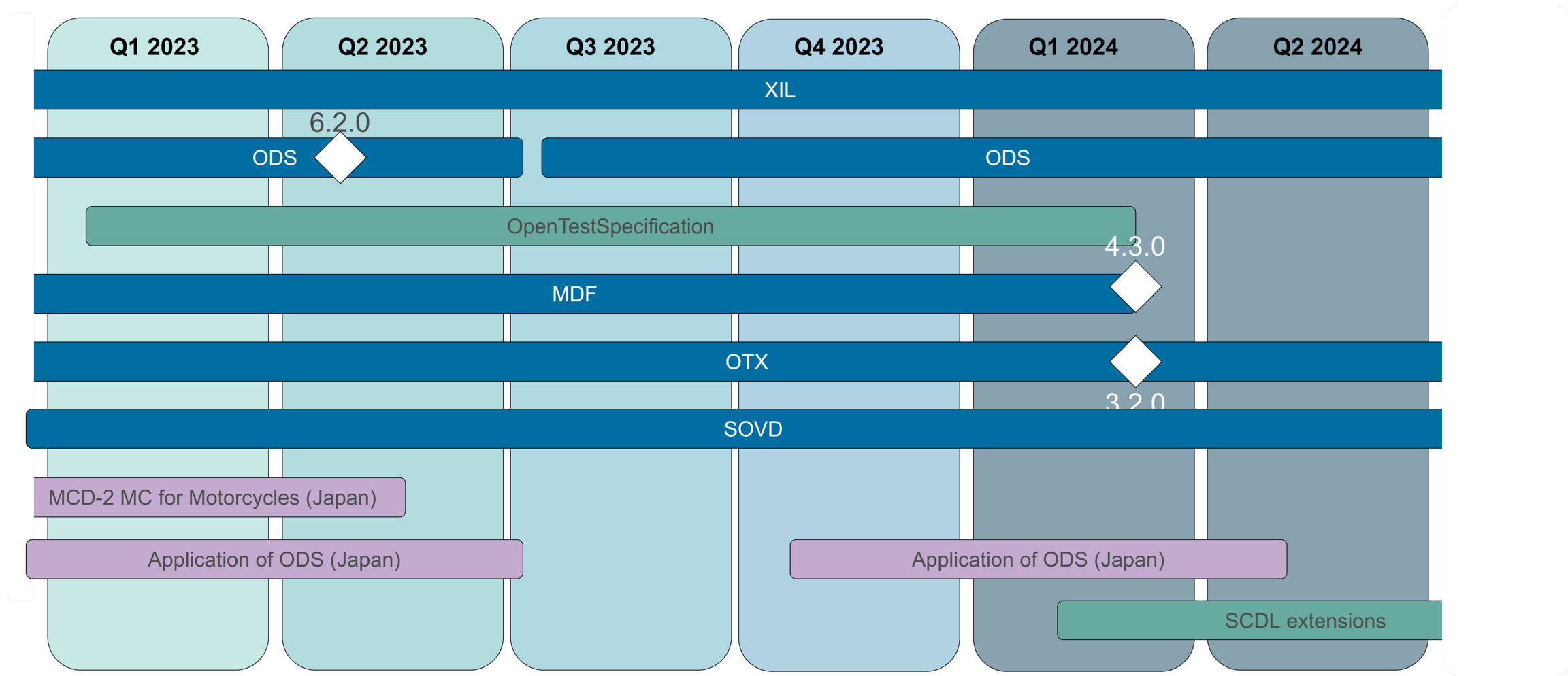
# Project roadmap 2023 (simulation) (as of 01.11.2023)

Color key:



# Project roadmap 2023 (all other domains) (as of 01.11.2023)

Color key:



# Thank you for your attention!

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# Getting involved in ASAM

# Putting ASAM into perspective

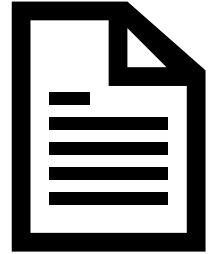
- Understand the goals & strengths of each organisation



Our main driver: leverage each organization's strengths and expertise!



# Why become a member?



Access to  
all ASAM  
standards

Participate  
in projects



Global community  
of experts



„Early access“  
to new features

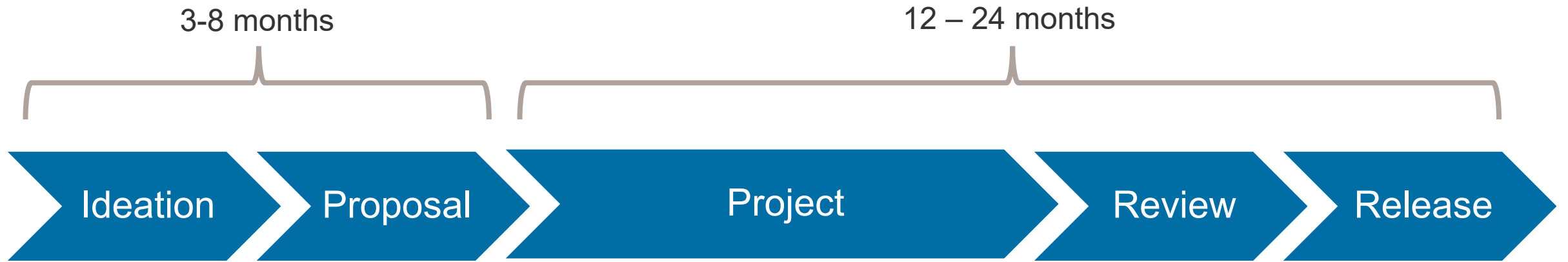


Fast, lean processes  
& toolchains



Ensure ASAM standards  
cater to your use cases  
& requirements

# How does a project work?



All projects are **member-driven**

Average commitment / yr **25-30 person days**

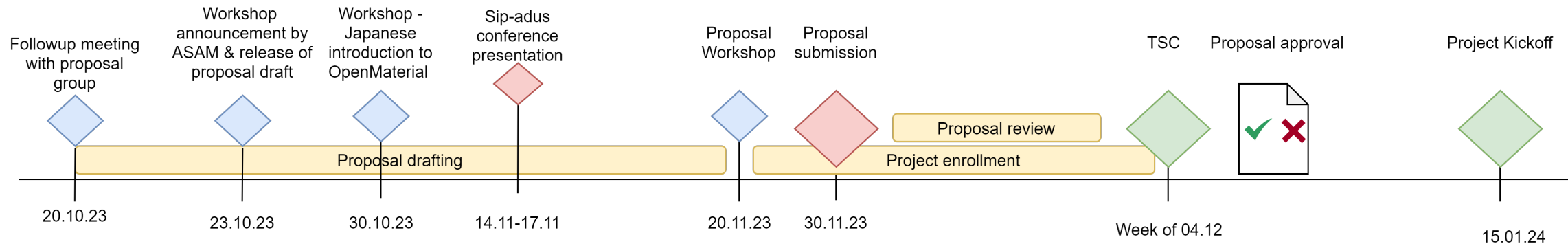
Work involves: Expert **discussion**, content **authoring**, **review**

# Other topics

# OpenMaterial

Status

Standardized data structure for materials and 3D assets



# ASAM Checker & Validation Tooling

- Scope of the activity
  1. Checker framework (standard independent)
  2. Checker libraries for OpenSCENARIO XML/DSL, OpenDRIVE, OpenCRG
- Followups may address additional libraries or standards
- Project participants to define requirements towards a framework and an initial set of checks for OSC & ODR
- Software development to be performed by a service provider (framework & check implementation)

